ISO TC22/SC12/WG5
WorldSID TG N393

USER'S MANUAL FOR THE WORLDSID 50TH PERCENTILE MALE SIDE IMPACT DUMMY

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SECTION 1

1. PROCEDURES FOR DISASSEMBLING AND ASSEMBLING THE WORLDSID

1.1 Head

1.1.1 Parts list for head

Table 1.1 lists the parts required for assembling the WorldSID head, which are illustrated in Figure 1.1. Part numbers correspond to those on electronic drawing W50-10000.

Table 1.1 — Parts list for WorldSID head

Item number	Description	Qty	Part number
1	Head core	1	W50-10007
2	Moulded head	1	W50-14014
3	Rotational accelerometer	3	Endevco 7302M4
4	Dual-axis tilt sensor	1	Endevco 7302M4
5	Linear triaxial accelerometer	1	Endevco 7268C-2000M1
6	Neck load cell structural replacement	1	W50-71003
7	SHCS M3 x 0,5 x 6	6	5000393
8	Cheese screw, M2 x 16	1	5000254
9	SHCS M4 x 0,7 x 10	1	5000151
10	SHCS M6 x 1 x 16	4	5000081
11	Flat washer M8 (8,9 ID x 18,8 OD x 2,3 thick)	1	5000123
12	BHCS M8 x 1,25 x 25	1	5000255
13	Neck shroud assembly	1	W50-24103
14	SHCS M6 x 12	4	5000281
15	BHCS M4 x 0,7 x 10	5	5000010
Not shown	Rotational accelerometer mass replacement	3	W50-10010
Not shown	Linear triaxial accelerometer mass replacement	1	W50-61063
Not shown	Dual-axis tilt sensor mass replacement	1	W50-10011
Not shown	Universal neck load cell	1	W50-71000

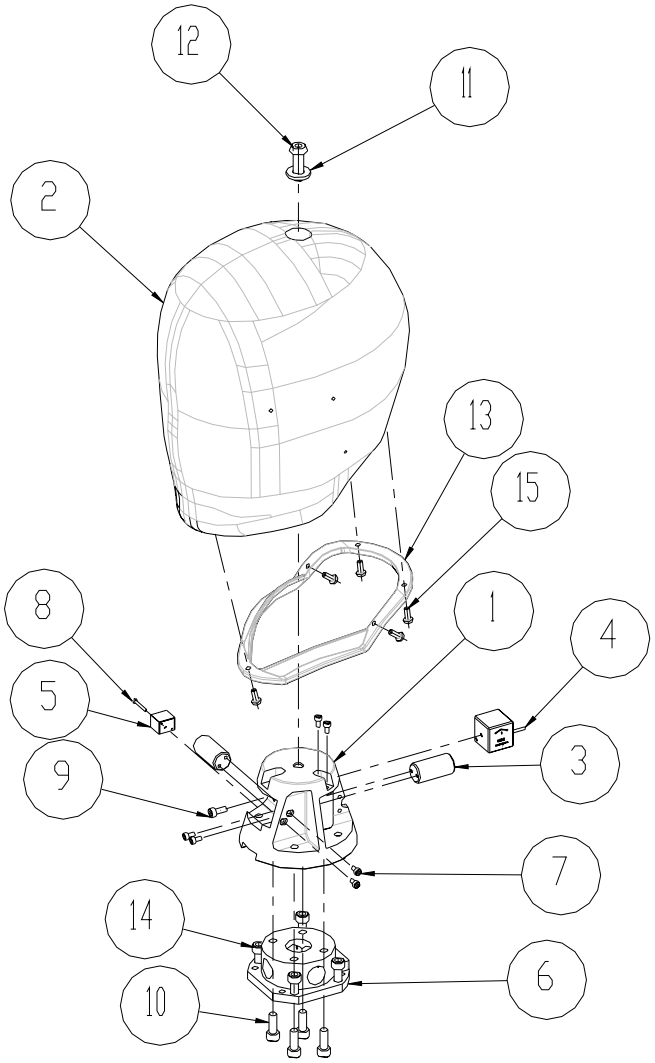


Figure 1.1 — WorldSID head components

1.1.2 Disassembling

As shown in Figure 1.2, remove the BHCS M8x25 (Figure 1.1, Item 12) and M8 flat washer (Figure 1.1, Item 11) from the top of the head. Lift the moulded head (Figure 1.1, Item 2) off the head core assembly. If the head sticks to the core, tap the bottom edge of the head lightly with a plastic hammer. Detach the neck shroud assembly (not illustrated, Item 13) from the head by removing five screws, BHCS M5 x 10.

Figure 1.2 — Removal of moulded head

Remove the four SHCS M6 x 12 (Figure 1.1, Item 14) that connect the head core assembly to the neck assembly (see Figure 1.3).

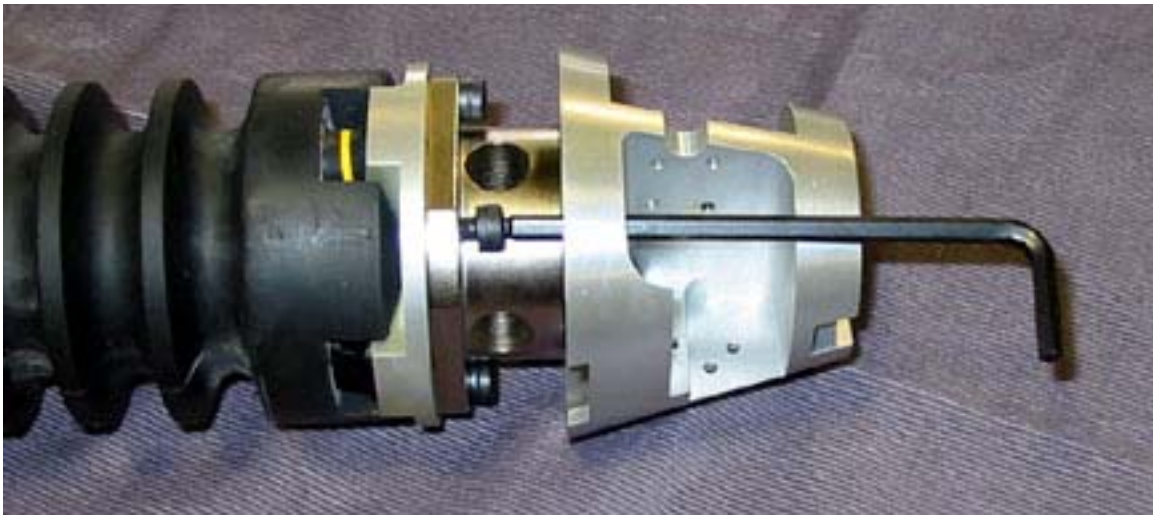


Figure 1.3 — Separating the head core from the neck

Remove the four SHCS M6 x 16 (Figure 1.1, Item 10) from the bottom of the upper neck load cell structural replacement (Figure 1.1, Item 6) that attach it to the bottom of the head core (see Figure 1.4).

Figure 1.4 — Removing upper neck load cell from instrumented head core

1.1.3 Assembling

Install the head instrumentation as described in 1.4. Use four SHCS M6 x 16 (Figure 1.1, Item 10) to attach the upper neck load cell to the bottom of the head core (Figure 1, Item 1). Make sure the slot at the top front of the head core is lined up with the connector for the upper neck load cell. Torque the screws to 6 Nm. Attach the head core assembly to the neck assembly using four SHCS M6 x 12 (Figure 1.1, Item 14). Torque the screws to 6 Nm.

Mount the neck shroud assembly (Table 1.1, Item 13) to the moulded head (Figure 1.1, Item 2) using five BHCS M5 x 10. Place the head/neck shroud assembly over the instrumented core, making sure that all wires are free. Place the M8 flat washer into the recess at the top of the head and connect the head to the instrumented core using the BHCS M8 x 25 (Figure 1.1, Item 12). Tighten the screw 1/4 - 1/2 turn after engagement of the screw head and the skull.

As shown in Figure 1.5, bundle the wires from the head instrumentation together at the rear with cable ties and route down the back of the neck over to the non-struck side of the dummy. Pass the cables between the shoulder rib and first thoracic rib to be plugged into the DAS modules from the other wiring so it can be plugged into an off-board readout during setup. As shown in Figure 1.5, make sure that the cable has some slack. See Section 1.3 for more detailed wiring information.

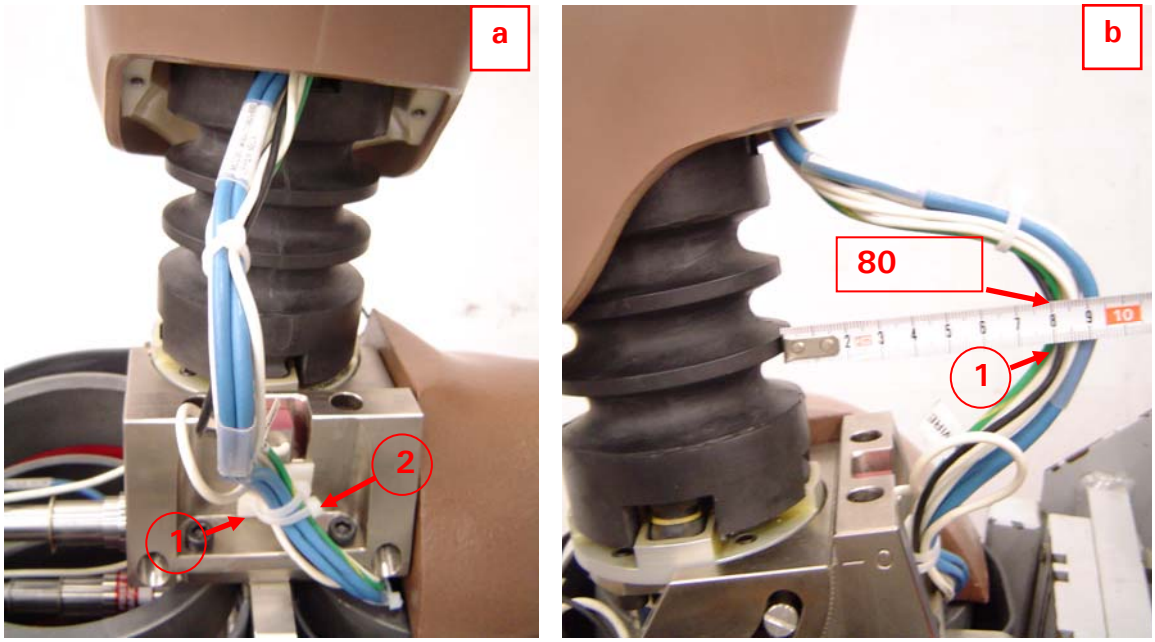


Figure 1.5 — Wire routing for head instrumentation

1.1.4 Instrumentation mounting

As shown in Figure 1.6, the head core can be instrumented with three rotational accelerometers (Figure 1.6, Item 3), one linear triaxial accelerometer (Figure 1.6, Item 5), and one dual-axis tilt sensor (Figure 1.6, Item 4). Each rotational accelerometer is secured with two SHCS M3 x 6 (Figure 1.6, Item 7) and that the y-axis rotational accelerometer is mounted in the right-front chamber with screws accessed from the left-front chamber. Mount the z-axis rotational accelerometer in the left-rear chamber with screws accessed from the top. Mount the x-axis rotational accelerometer in the right-rear chamber with screws accessed from the right-front chamber. The linear triaxial accelerometer is mounted in the right-front chamber with one cheese screw M2 x 16 (Figure 1.6, Item 8) that is accessed from the right. Mount the tilt sensor in the right-rear chamber with one SHCS M4 x 10 (Figure 1.6, Item 9) accessed from the right-front chamber. The instrumentation in the right-rear chamber must be installed before the instrumentation in the right-front chamber. The upper neck load cell is also considered part of the head assembly instrumentation.

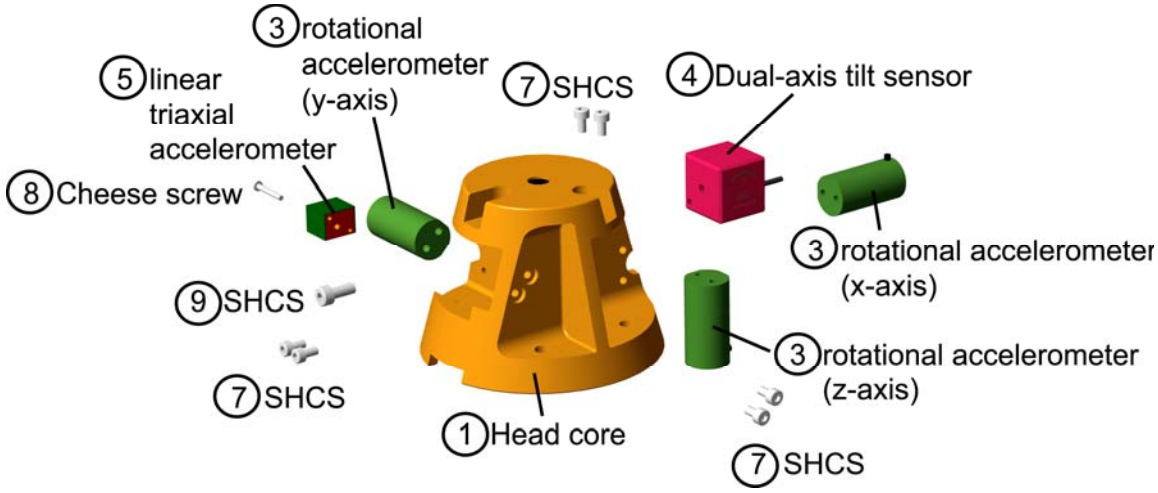


Figure 1.6 — WorldSID head instrumentation

1.2 Neck

1.2.1 Parts list for neck

Table 1.2 lists the parts required for assembling the WorldSID neck, which are shown in Figure 1.7. Part numbers correspond to those found on drawing W50-20000.

Table 1.2 — Parts list for WorldSID neck

Item number	Description	Qty	Part number
1	Lower neck bracket	1	W50-20009
2	Upper neck bracket	1	W50-20010
3	Neck load cell structural replacement	1	W50-71003
4	Neck column assembly	1	W50-21001
5	SHCS M6 x 50	2	5000324
6	Neck bracket nut	2	W50-20011
7	SHCS M6 x 12	8	5000281
8	Linear triaxial accelerometer	1	Endevco 7268C-2000M1
9	Cheese screw M1,5 x 16	1	5000227
Not shown	Linear triaxial accelerometer structural replacement	1	W50-61063
Not shown	Universal neck load cell	1	W50-71000

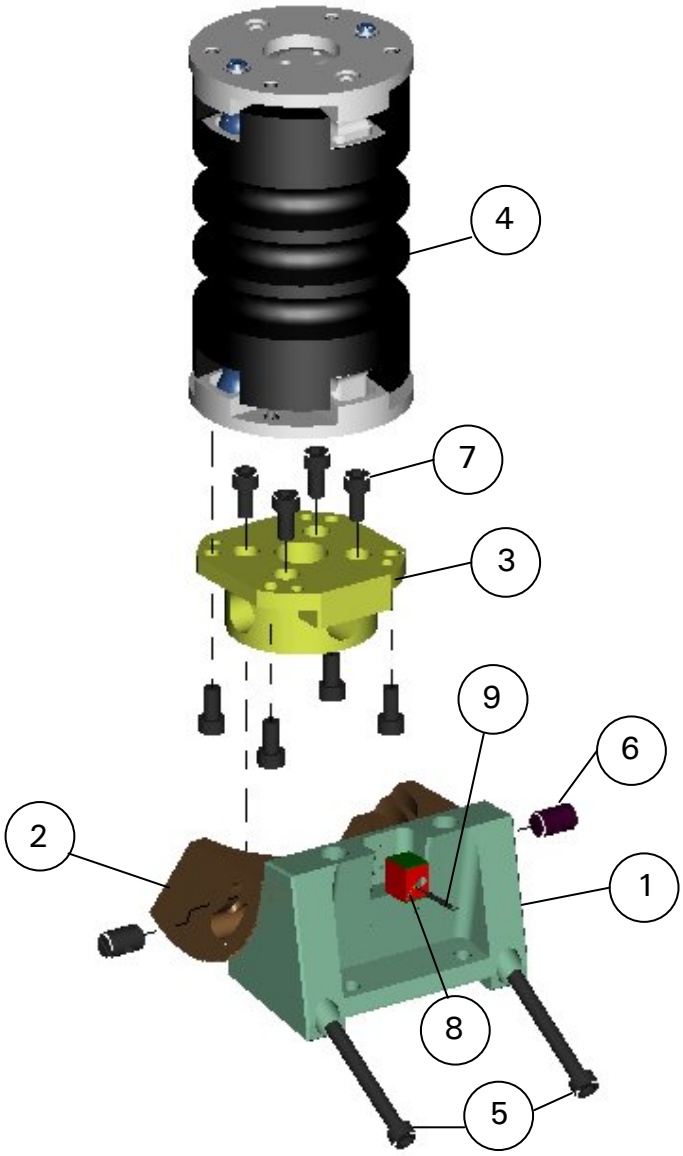


Figure 1.7 — WorldSID neck components

1.2.2 Disassembling

Separate the upper (Figure 1.7, Item 2) and lower (Figure 1.7, Item 1) neck brackets by removing two SHCS M6 x 50 (Figure 1.7, Item 5) accessed from the rear of the dummy (see Figure 1.8). Remove the two free neck bracket nuts (Figure 1.7, Item 6), accessed from either side.

Figure 1.8 — Removing lower neck bracket

Remove the upper part of the neck bracket and lower neck load cell structural replacement from the neck assembly by removing four SHCS M6 x 12 (Figure 1.7, Item 7) accessed from the bottom (see Figure 1.9). Remove the lower neck load cell from the upper neck bracket by removing four SHCS M6 x 12 (Figure 1.7, Item 7).

Figure 1.9 — Removing upper neck bracket

To take apart the neck assembly, use the neck compression wrench to remove the half-spherical screw from the neck (see Figure 1.10). After the interface plates come off, remove the four dampers by pulling them out (see Figure 1.11).

Figure 1.10 — Using clamp to remove neck interface plate

Figure 1.11 — Neck dampers are free to be removed when interface plates are removed

1.2.3 Assembling

When assembling the neck, mount the neck buffers with the circular cross-sections on the lateral sides of the neck, and mount the neck buffers with the square cross-sections on the front and rear of the neck. As shown in Figure 1.12, the lateral locations for the buffers in the interface plates are farthest from the holes for mounting the neck to the head and torso.

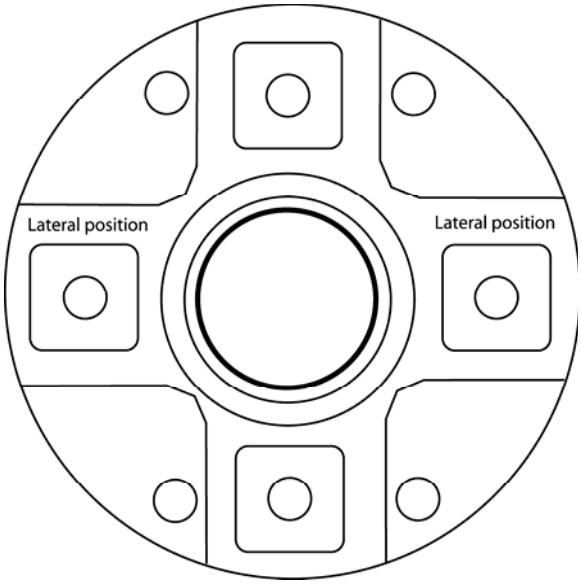


Figure 1.12 — Lateral positions for neck buffers

The circular cross-section buffers have a cylindrical end and a mushroom-shaped end. Press the mushroom ends firmly into the top and bottom interface plates so that the mushroom cap protrudes into the counterbore on the flat face of the interface plate. A turning action during assembly helps to get the circular buffers positioned correctly. Tune the correct response of the neck in lateral bending by using three different hardnesses of lateral circular cross-section buffers. When installing the flexion/extension buffers in the interface plates, position them as shown in Figure 1.13 so the end that sticks out farther is facing the moulded neck.

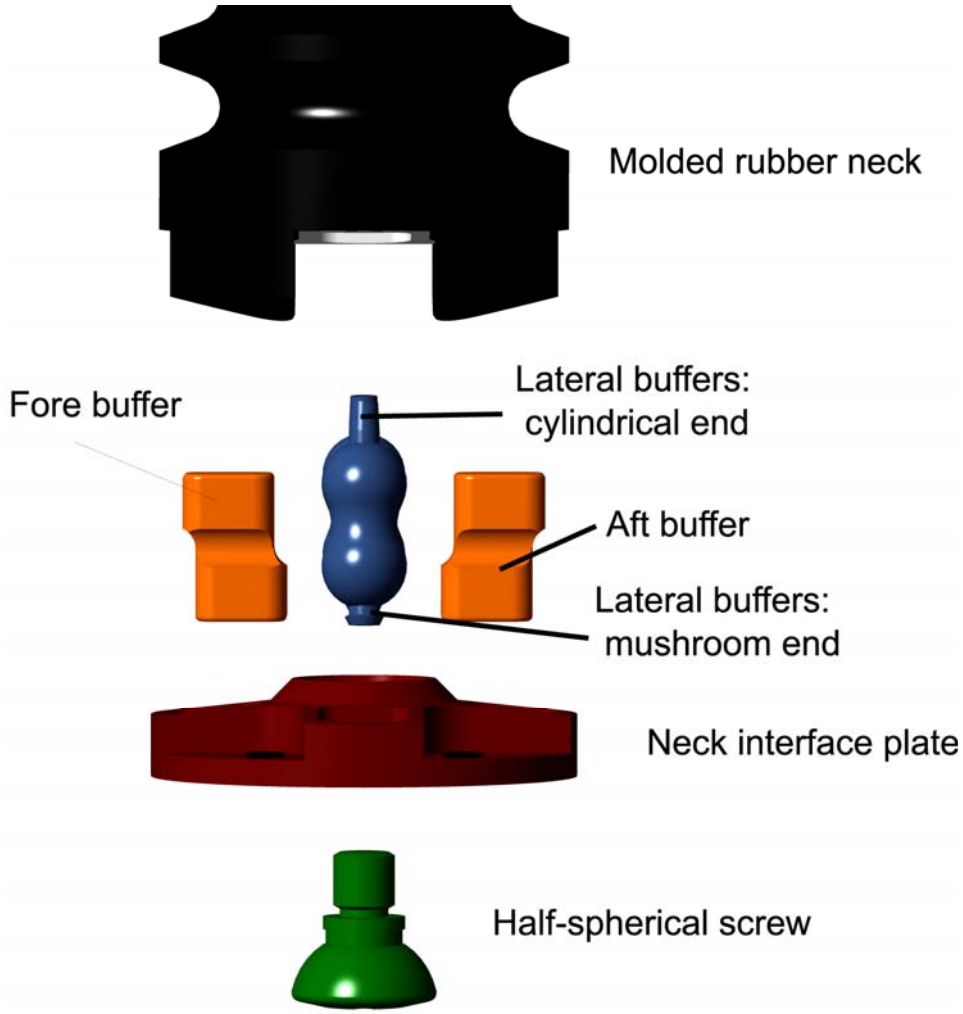


Figure 1.13 — Assembling of neck buffers

Position the interface plate with the installed buffers over one end of the neck. Lubricate the surface of the half-spherical screw with the "Never Seez" high-pressure grease, which is provided in the toolbox. Attach the interface plate to the neck by tightening the half-spherical screws to 10 Nm using the neck compression tool. Repeat for the other end of the neck.

Place the upper neck bracket (Figure 1.7, Item 2) over the lower neck bracket (Figure 1.7, Item 1) and engage the teeth in the desired orientation. Insert the neck bracket nut (Figure 1.7, Item 6) into the slot on one side and orient it so the hole in the nut lines up with the hole accessed from the back

of the lower neck bracket. Insert the SHCS M6 x 50 (Figure 1.7, Item 5) to secure the brackets together. Repeat with the second neck bracket nut and SHCS on the other side.

Mount the neck load cell or its structural replacement (Figure 1.7, Item 3) to the neck bracket with four SHCS M6 x 12 (Figure 1.7, Item 7). Tighten the screws to 6 Nm. Attach the neck assembly (Figure 1.7, Item 4) to the neck bracket/load cell assembly with four SHCS M6 x 12 (Figure 1.7, Item 7) accessed from the bottom. Tighten the screws to 6 Nm.

1.2.4 Instrumentation mounting

The neck assembly includes a lower neck load cell (the upper neck load cell is considered part of the head assembly). In addition a triaxial accelerometer can be mounted in a recess in the back of the lower neck bracket. Install the triaxial accelerometer or its mass replacement to the upper neck bracket using a cheese screw M2 x 16 (see Figure 1.14).

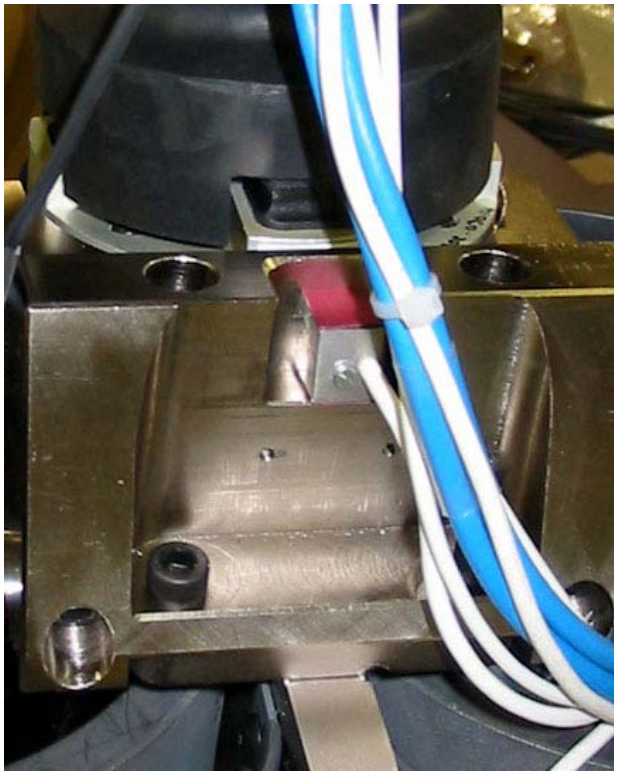


Figure 1.14 — Neck triaxial accelerometer installation

1.3 Thorax, abdomen and shoulder

1.3.1 Parts list

1.3.1.1 Parts list for thorax, abdomen and shoulder assembly

Table 1.3 lists the parts required for assembling the WorldSID thorax, abdomen and shoulder, which are illustrated in Figure 1.15. Part numbers correspond to those on drawing W50-30000.

Table 1.3 — Parts list for the WorldSID thorax, abdomen and shoulder

Item number	Description	Qty	Part number
1	Spine box assembly	1	W50-31000
2	IRTRACC displacement sensor assembly, ribs 1-6	6	IF-363
3	Thorax rib assembly 1, WorldSID	2	W50-32111
4	Thorax rib assembles 2 and 3, WorldSID	8	W50-32131
5	Sternum, thorax rib	1	W50-35022
6	Rib coupler, abdominal, WorldSID	1	W50-35021
7	Shoulder rib sternum mounting strip	2	W50-32177
8	Thorax and abdominal rib sternum mounting strip	10	W50-32178
9	Thorax and abdominal rib mounting strip, threaded	10	W50-32176
10	BHCS M5 x 0,8 x 10	64	5000003
11	Shoulder rib assembly, inner band, WorldSID	2	W50-32160
12	Thorax rib assembly, inner band, WorldSID	6	W50-32150
13	Abdomen rib assembly, inner band, WorldSID	4	W50-32155
14	Shoulder rib mounting bracket, struck side, WorldSID	2	W50-32171
15	Thorax and abdominal rib accelerometer mounting bracket, WorldSID	10	W50-32172
16	Accelerometer, linear triaxial	6	Endevco 7268C-2000M1
17	Rib assembly, shoulder	2	W50-32001
18	Shoulder rib sternum strip, threaded	2	W50-32175
19	Thorax and abdominal rib clamping bracket, WorldSID	10	W50-32173
20	FHCS M5 x 0,8 x 16	8	5000467
21	Screw, rib IRTRACC mount	6	W50-32179
22	Rib doubler, shoulder	2	W50-32010
23	Shoulder assembly	2	W50-61053
24	Clamp, damping	24	W50-32180
25	FHCS M5 x 0,8 x 10	48	5000084
26	BHCS M5 x 0,8 x 6	24	5000214
27	Shoulder pad, left, WorldSID	1	W50-35023-1

Item number	Description	Qty	Part number
28	Shoulder pad, right, WorldSID	1	W50-35023-2
29	Battery mounting bracket	1	W50-37011
30	SHCS M5 x 0,8 x 30	2	5000471
31	Battery mass replacement	1	W50-37012
32	BHCS M2,5 x 0,45 x 10	6	5000208
33	FHCS M2,5 x 0,45 x 6	24	5000202
34	SHCS M5 x 18	2	5000112
35	Nut, locknut M12 x 1,75	2	5000462
36	Thorax pad	2	W50-35024
37	SHCS M6 x 1 x 16	4	5000081
38	Cheese screw M2 x 16	6	5000254
39	Cable tie mount, 0,50 x 0,50, nylon, adhesive backed	10	6002035
40	Cable tie mount, #4 screw, nylon	1	6002036
41	BHCS M3 x 0,5 x 6	1	5000399
42	Cable tie, 7,4 inch (not shown)	8	6000004
43	Temperature logger assembly	1	Dallas DS192H/Z
Not shown	IR-TRACC mass replacement	6	W50-31060
Not shown	Linear triaxial accelerometer mass replacement	6	W50-61063
Not shown	Temperature logger assembly mass replacement	1	W50-71701

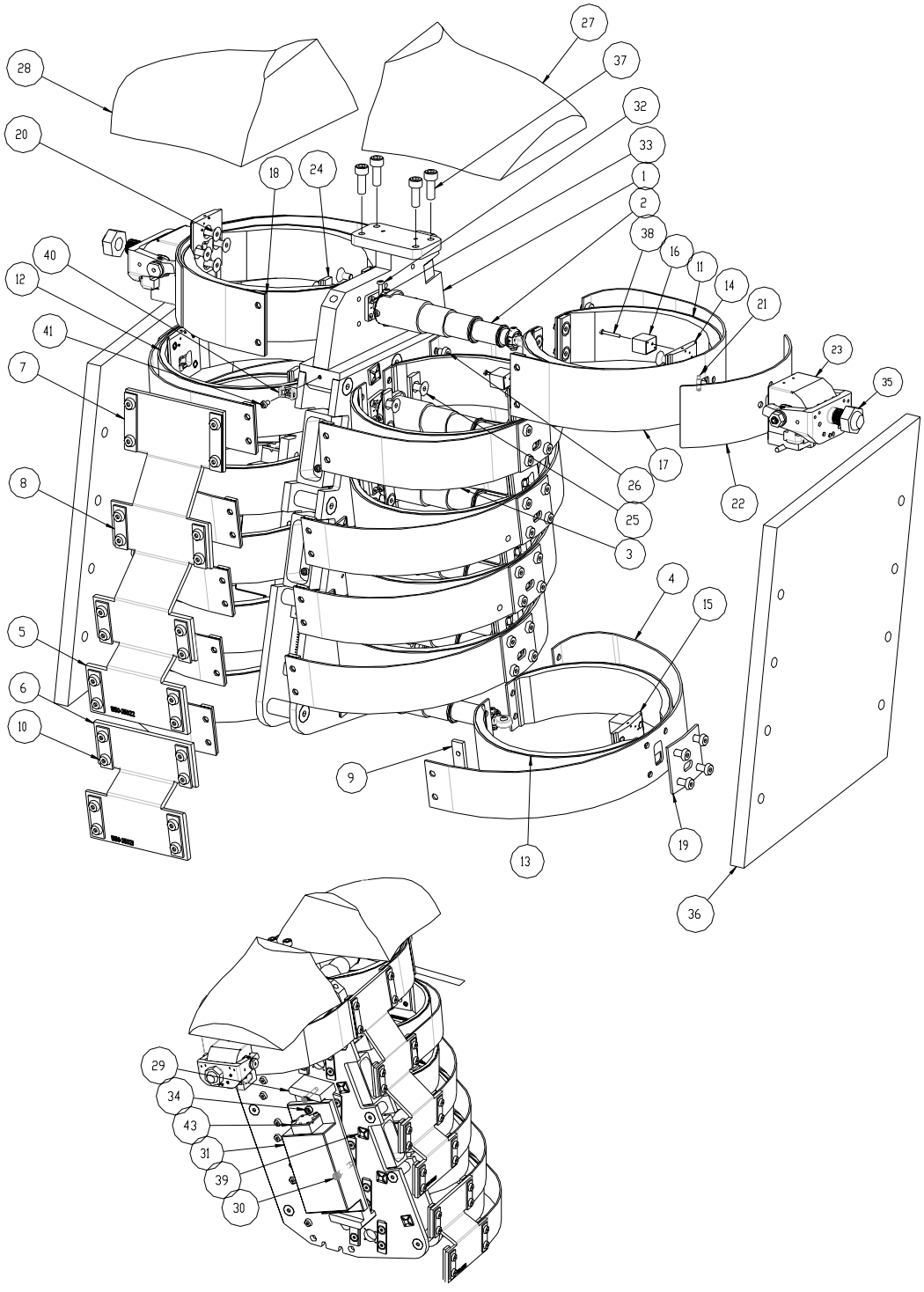


Figure 1.15 — Components of WorldSID thorax and abdomen

1.3.1.2 Parts list for shoulder

Table 1.4 lists the parts required for assembling the WorldSID shoulder (electronic drawing W50-61053), which is illustrated in Figure 1.16.

Table 1.4 — Parts list for shoulder assembly

Item number	Description	Quantity	Part number
1	Shoulder load cell structural replacement	1	W50-71092
2	Shoulder pivot shaft	1	W50-61049
3	Shoulder pivot washer	2	W50-61050
4	Shoulder clevis assembly	1	W50-61117
5	M6 hex locknut	1	5000143
6	SSNT M4 x 0,7 x 4 mm	2	5000201
Not shown	Shoulder load cell	1	W50-71090
Not shown	SSFP M4 x 0,7 x 4 mm	2	5000618
Not shown	SSFT M6 x 10	1	5000226

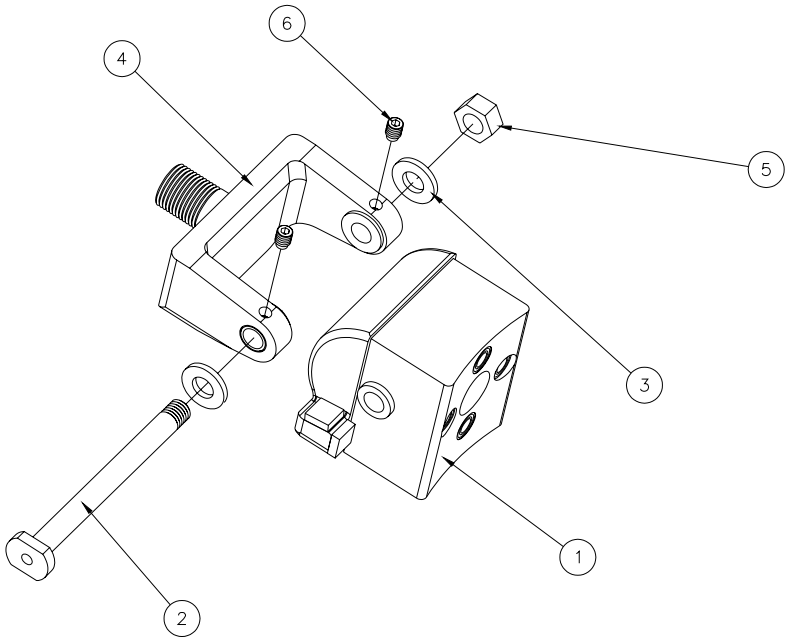


Figure 1.16 — Shoulder

1.3.1.3 Parts list for spine box assembly

Table 1.5 lists the parts required for assembling the WorldSID spine box. Part numbers correspond to those on drawing W50-31000 and shown in Figure 1.17.

Table 1.5 — Parts list for WorldSID spine box

Item number	Description	Qty	Part number
1	Mounting bracket 1	2	W50-31042
2	Upper bracket weldment, spine box, WorldSID	1	W50-31010
3	Interposer replacement	2	W50-75001
4	Side plate, left WorldSID	1	W50-31020
5	SHCS M3 x 0,5 x 10	7	5000119
6	Spacer, WorldSID	6	W50-31041
7	T12 accelerometer mount, WorldSID	1	W60-37024
8	Side plate, right WorldSID	1	W50-31030
9	SHCS M3 x 0,5 x 8	8	5000388
10	Connector housing mass replacement	2	W50-75002

Item number	Description	Qty	Part number
11	Backup plate mounting bracket	2	W50-37022
12	SHCS M4 x 0,7 x 10	4	5000151
13	FHCS M2,5 x 0,45 x 6	24	5000202
14	Ball joint assembly, IRTRACC	6	W50-31050
15	FHCS M6 x 1 x 10	18	5000204
16	Accelerometer, linear triaxial	2	Endevco 7268C-2000M1
17	SHCS M2 x 0,4 x 12,0 12,9 alloy steel	8	5000382
18	Cheese screw M2 x 16	2	5000254
19	BHCS M6 x 1 x 18	4	5000465
20	Rotational accelerometer/tilt sensor mount bracket	1	W50-37023
21	Mounting bracket #2	2	W50-31043
22	G5 mass replacement	3	W50-74307
23	Cover plate spine box	2	W50-31045
24	Accelerometer, rotational	2	Endevco 7302BM4
25	SHCS M4 x 0,7 x 25	8	5000461
26	Bracket, rotational accelerometer mount	1	W50-37029
27	Tilt sensor, dual axis (ref)	1	See dummy manufacturer information
28	FHCS M3 x 0,5 x 10	2	5000203
29	SHCS M4 x 0,7 x 8	1	5000024
30	Pin, dowel M4 x 14	2	5000053
Not shown	Linear accelerometer mass replacement	2	W50-61063
Not shown	Rotational accelerometer mass replacement	2	W50-10010
Not shown	Dual axis tilt sensor mass replacement	1	W50-10011

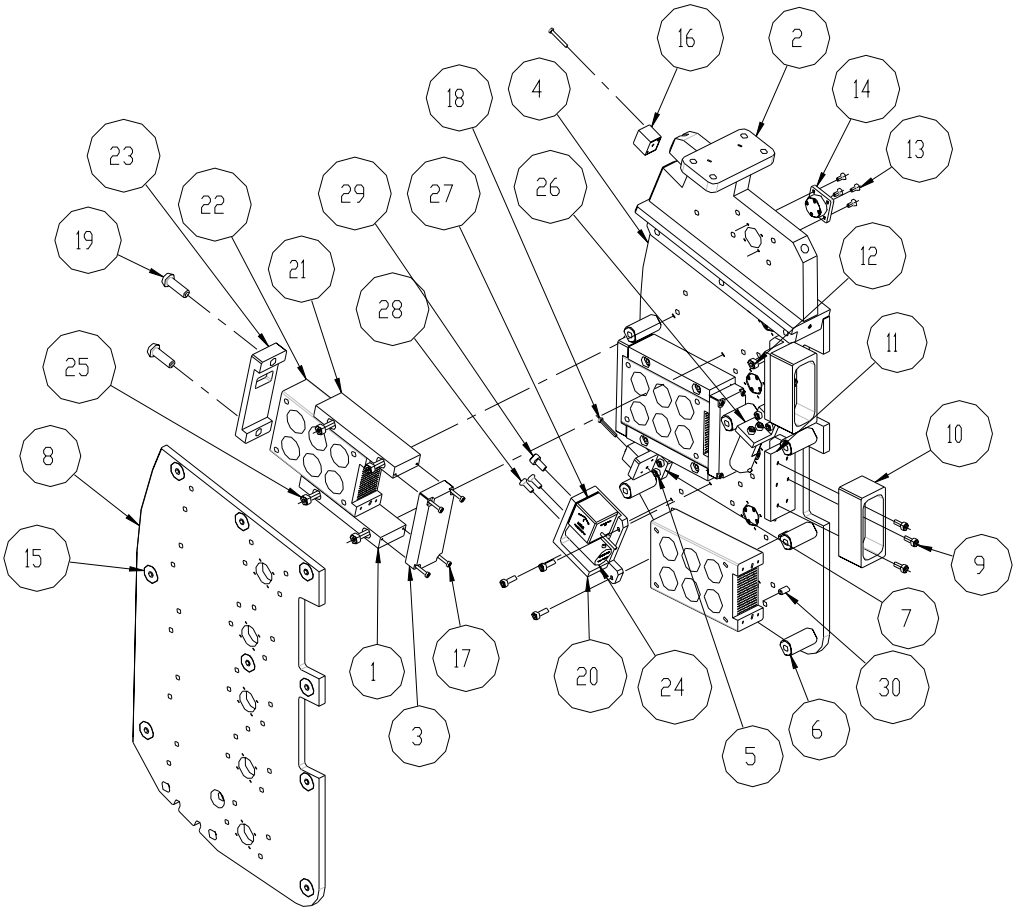


Figure 1.17 — WorldSID spine box assembly

1.3.2 Disassembling

1.3.2.1 Separation of upper and lower torso

To separate the upper and lower torso, first make sure all the cables running between the upper and lower torso are detached, these would normally include communication cables if the pelvis DAS is installed, sensor cables that were routed to the DAS in the thorax, and a ground cable. This

step may require disassembling of the sternum to access the sensor collector. Thereafter, remove the four SHCS M8, two on each side of the bottom of the spine box, to separate the upper and lower torsos.

1.3.2.2 Shoulder

As shown in Figure 1.18, remove the shoulder assembly (Figure 1.15, Item 23) by removing the four FHCS M5 x 16 (Figure 1.15, Item 20) that hold each in place.

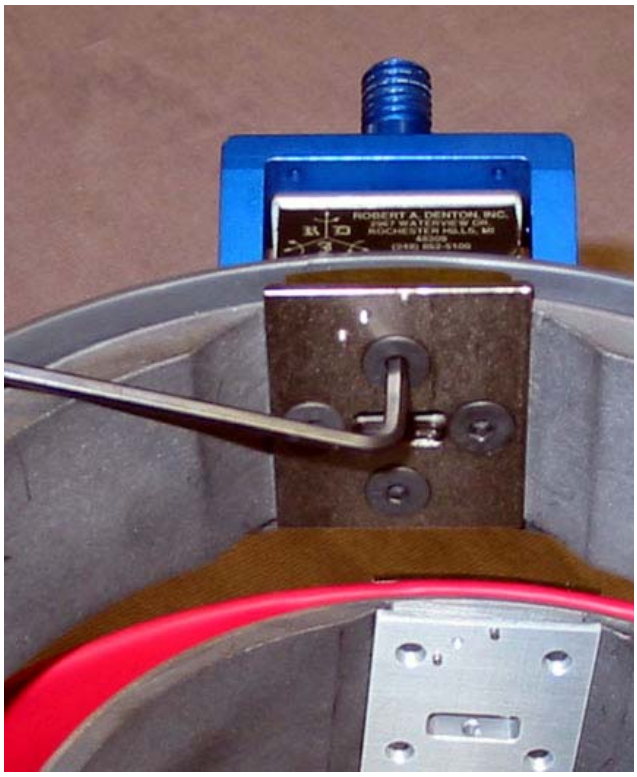


Figure 1.18 — Removing shoulder load cell assembly

To remove the clevis assembly (Figure 1.16, Item 4), take off the M6 hex nut (Figure 1.16, Item 5) with the nylon washer (Figure 1.16, Item 3) at the threaded end. Next, loosen the two SSNT M4 x 0,7 x 4 (Figure 1.16, Item 6) in the clevis assembly that hold the pivot shaft (Figure 1.16, Item 2) and the two SSFT M6 x 10 mm (in the load cell behind the clevis securing

the pivot shaft) from the load cell structural replacement then pull the shaft out of the assembly.

NOTE The shoulder load cell has two SSFP M4 x 4 mm securing the pivot shaft instead of the one SSFT M6 x 10 in the load cell structural replacement.

1.3.2.3 Thorax and abdomen

Remove the thorax pad (Figure 1.15, Item 36) by removing it from the Velcro® that holds them in place. Remove the shoulder pads (Figure 1.15, Items 27 and 28) by lifting them off of the dummy. Remove the lower neck bracket from the spine box by removing four SHCS M6 x 16 (Figure 1.15, Item 37).

Remove the shoulder rib mounting brackets (Figure 1.15, Item 14). Detach the shoulder rib IR-TRACC (Figure 1.15, Item 2) from the shoulder rib mounting bracket by removing the IR-TRACC rib mount screw (Figure 1.15, Item 21), accessed from the bottom of the shoulder rib mounting bracket.

Remove the linear triaxial accelerometer (Figure 1.15, Item 16) from the shoulder rib mounting bracket by removing the cheese screw M2 x 16 (Figure 1.15, Item 38). Detach the shoulder IR-TRACC assembly from the spine box by removing the BHCS M2,5 x 10 (Figure 1.15, Item 32).

As shown in Figure 1.19, disconnect the shoulder rib (Figure 1.15, Item 17) at the front by removing the two BHCS M5 x 10 (Figure 1.15, Item 10) that attach the left and right shoulder ribs to the sternum thorax rib (Figure 1.15, Item 3). Removing a shoulder rib sternum mounting strip (Figure 1.15, Item 7) and a threaded shoulder rib sternum mounting strip (Figure 1.15, Item 18) which are removed from each side.

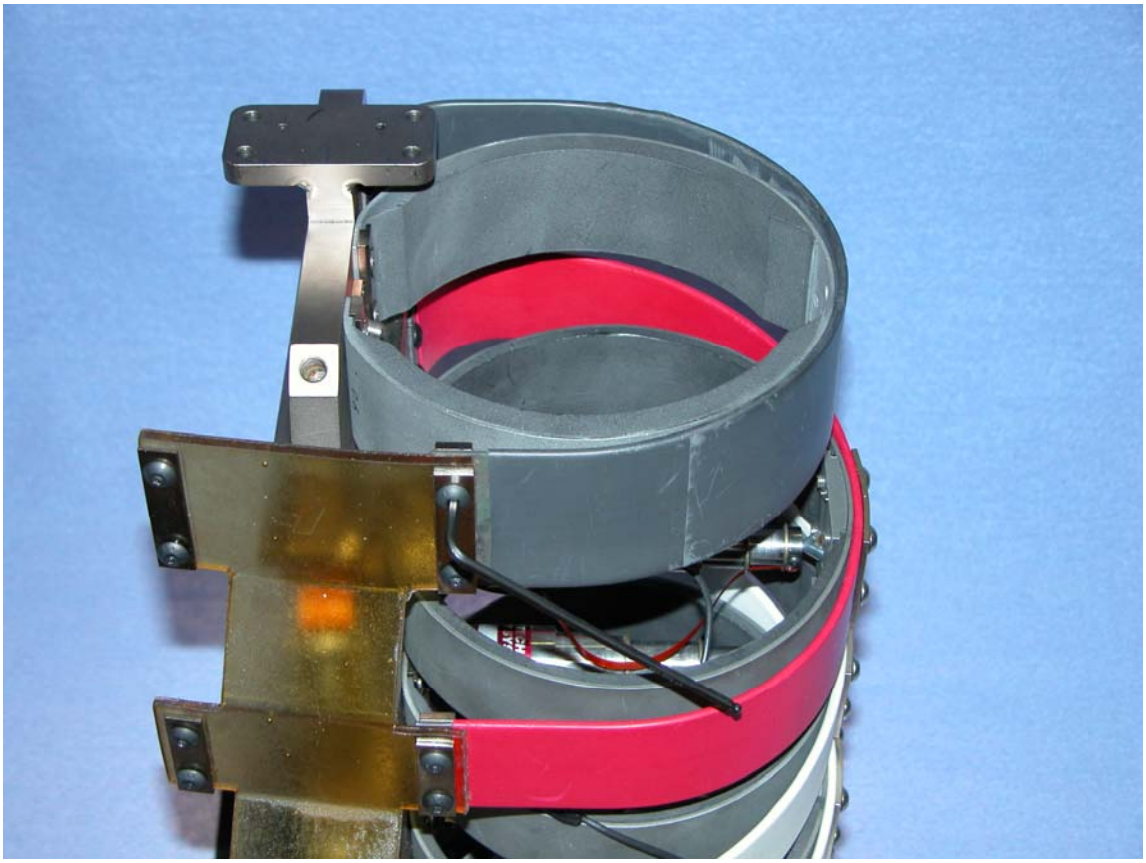


Figure 1.19 — Detaching shoulder rib at front from sternum

Detach the left and right shoulder ribs from the spine box at the rear by removing two BHCS M5 x 6 (Figure 1.15, Item 26) that hold each in place (see Figure 1.20). On the non-struck side, remove the two damping clamps (Figure 1.15, Item 24).

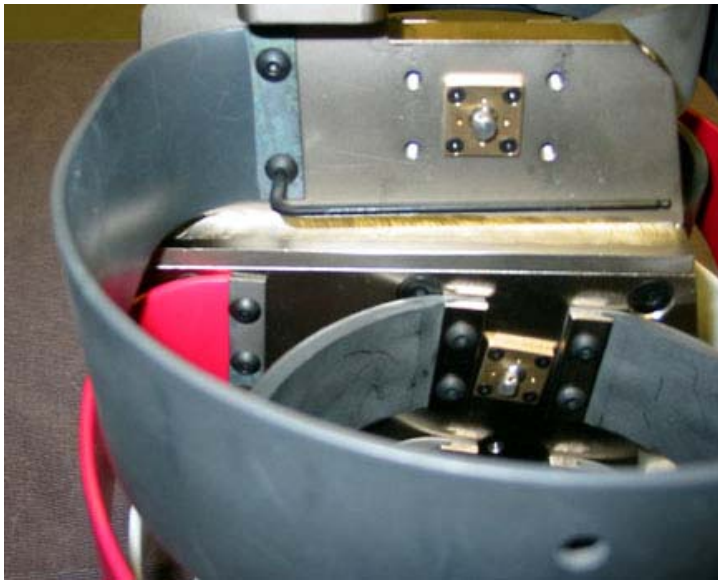


Figure 1.20 — Detaching the rib from the spine box at the rear

The procedures for disassembling the remaining ribs are similar to those for the shoulder rib, but details for the first thoracic rib are included here in order to include references to the correct item numbers. Detach the rib clamping bracket (Figure 1.15, Item 19) and the rib accelerometer mounting bracket (Figure 1.15, Item 15) by removing the four BHCS M5 x 10 (Figure 1.15, Item 10). Remove the triaxial accelerometer (Figure 1.15, Item 16) from the rib accelerometer mounting bracket (Figure 1.15, Item 15) by removing the cheese screw M2 x 16 (Figure 1.15, Item 38).

Remove the IR-TRACC (Figure 1.15, Item 2) by removing the BHCS M2,5 x 10 (Figure 1.15, Item 32) that secures it to the spine box. Detach it from the rib accelerometer bracket by removing the IR-TRACC mount screw (Figure 1.15, Item 21), which is accessed from the bottom of the rib accelerometer bracket.

Detach the thorax rib at the front by removing the four BHCS M5 x 10 (Figure 1.15, Item 10) that connect it to the sternum (Figure 1.15, Item 5). Remove the two sternum rib mounting strips (Figure 1.15, Item 8) and the two threaded rib mounting strips (Figure 1.15, Item 9). Detach the inner band of the thorax rib (Figure 1.15, Item 12) by removing the four BHCS M5

x 10 (Figure 1.15, Item 10) that hold them in place. Remove the two damping clamps (Figure 1.15, Item 24). Detach the rib from the spine box at the rear by removing two BHCS M5 x 6 (Figure 1.15, Item 26) that hold them in place.

Repeat this procedure for the second and third thorax ribs and the two abdominal ribs with the few differences in parts described here. Note that the two abdominal ribs are attached at the front to the abdominal rib coupler (Figure 1.15, Item 6), and that the inner rib bands of the two abdomen ribs (Figure 1.15, Item 13) are different than the inner bands of the three thorax ribs (Figure 1.15, Item 12). The damping material on the abdominal ribs is thicker than that on the thoracic ribs. Also, the first thorax outer rib (Figure 1.15, Item 3) is different from the thorax ribs 2 and 3 and the abdominal ribs (Figure 1.15, Item 4), which are the same.

After the ribs are removed (see Figure 1.15), detach the battery mass replacement (Figure 1.21, Item 31) from the non-struck side by removing two SHCS M5 x 18 (Figure 1.21, Item 34). Then detach the battery mounting bracket (Figure 1.21, Item 29) by removing the two SHCS M5 x 30 (Figure 1.21, Item 30) that secure it to the spine box.

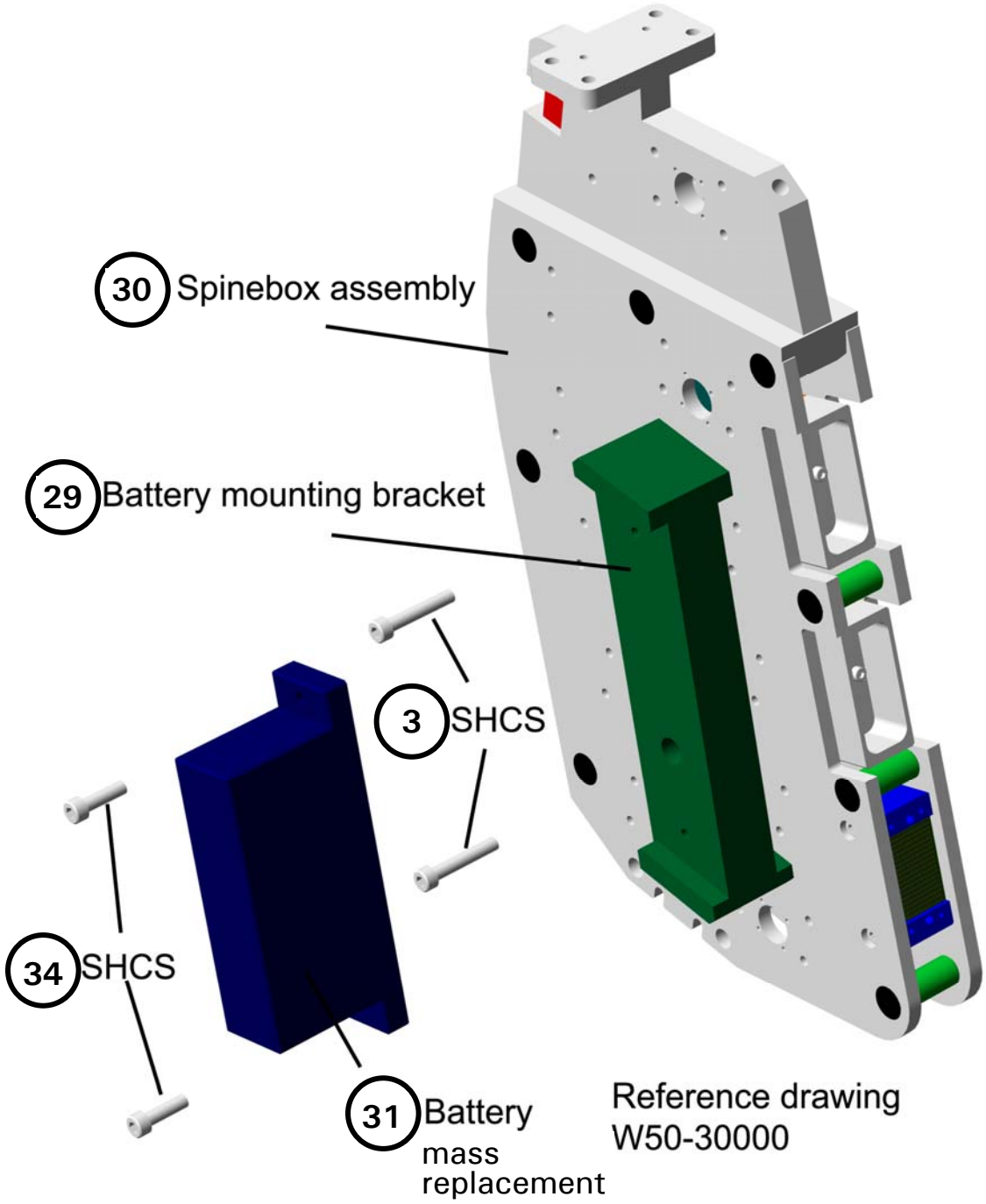


Figure 1.21 — Battery assembly

1.3.2.4 Spine box disassembling

Detach the right side plate (Figure 1.17, Item 8) from the spine box by removing ten FHCS M6 x 10 (Figure 1.17, Item 15). Note that the internal components of the spine box will now be visible (see Figure 1.23).

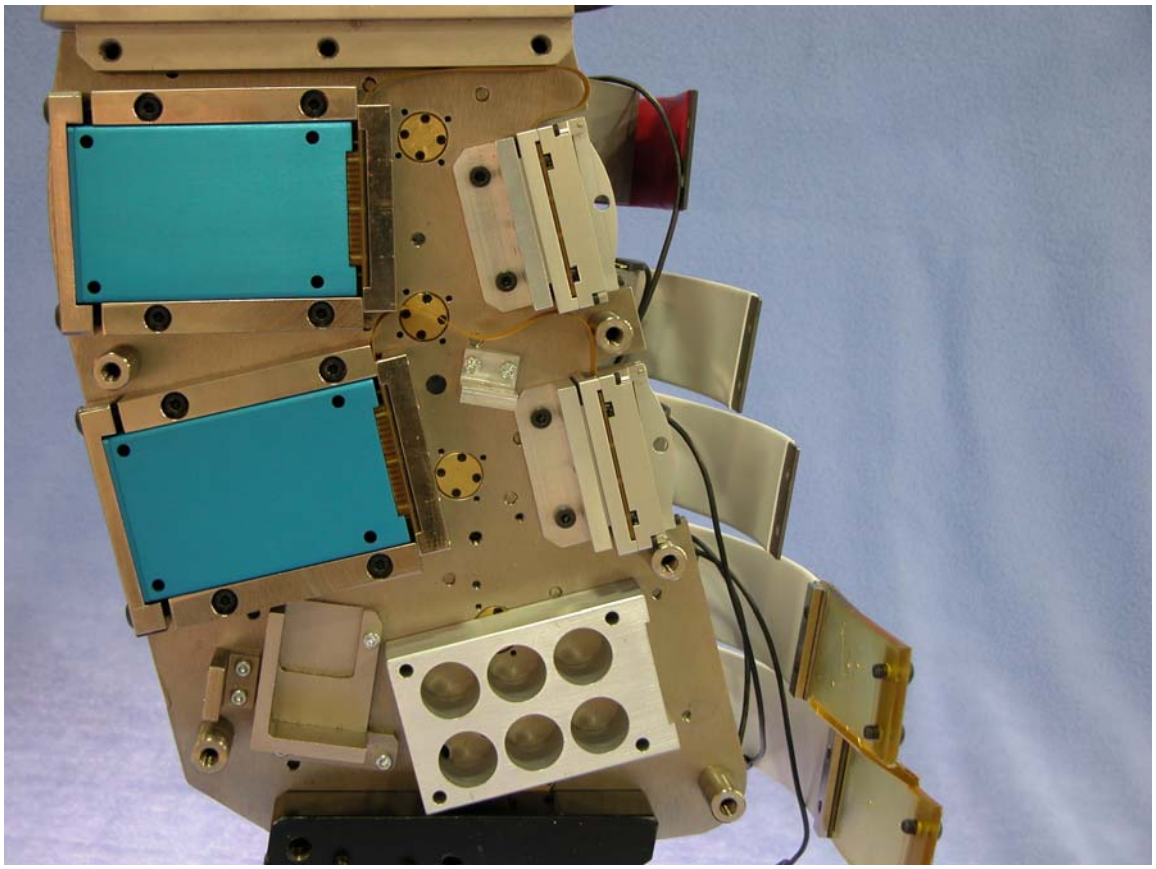


Figure 1.22 — Internal spine box assembly

Remove the T12 accelerometer mount (Figure 1.17, Item 7) from the spine box by removing the two SHCS M3 x 10 (Figure 1.17, Item 5) that secure the mount. Remove the accelerometer (Figure 1.17, Item 16) from the mount by removing a cheese screw M2 x 16 (Figure 1.17, Item 18).

Note the rotational and linear accelerometer assembly shown in Figure 1.23. To detach the rotational accelerometer assembly from the spine box, remove the three SHCS M3 x 10 (Figure 1.17, Item 5) that secure it to

the spine box. Remove the dual-axis tilt sensor (Figure 1.17, Item 27) from the rotational accelerometer bracket by removing the SHCS from the back of the bracket. Detach the two rotational accelerometers by removing the two FHCS that secure each to the bracket.

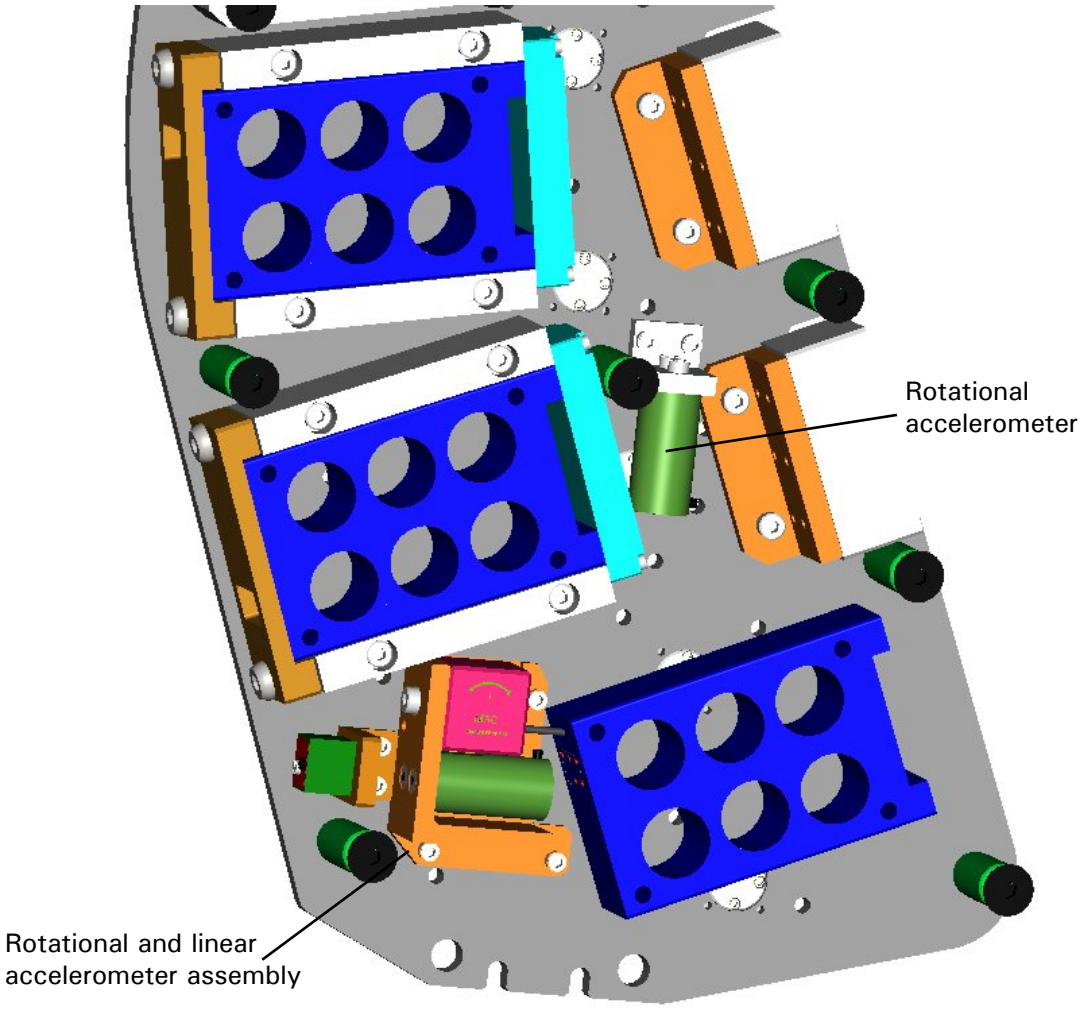


Figure 1.23 — Angular accelerometer assembling

Begin removal of the upper or middle G5 module mass replacements (Figure 1.17, Item 22) by removing two SHCS M4 x 25 (Figure 1.17, Item 25) that secure the Number 2 mounting brackets (Figure 1.17, Item 21) to the spine box weldment (Figure 1.17, Item 2). Remove two more SHCS M4 x 25 (Figure 1.17, Item 25) that secure the Number 1 mounting brackets

(Figure 1.17, Item 1) to the spine box. Remove the middle or upper G5 module mass replacement assembly (Figure 1.17, Item 22). Detach the spine box cover plate (Figure 1.17, Item 19) from the back of each G5 module mass replacement (Figure 1.17, Item 22) by removing two BHCS M6 x 18 (Figure 1.17, Item 24). Slide the G5 module mass replacement (Figure 1.17, Item 22) from between the two mounting brackets (Figure 1.17, Item 1 and 21). Detach each interposer mass replacement (Figure 1.17, Item 3) from the mounting brackets by removing the four SHCS M2 x 12 (Figure 1.17, Item 17). Remove the two backup plate mounting brackets (Figure 1.17, Item 11) from the spine box by removing the two SHCS M4 x 10 (Figure 1.17, Item 12) that hold each in place. Remove each connector housing mass replacement (Figure 1.17, Item 10) from its backup plate mounting bracket (Figure 1.17, Item 11) by removing three SHCS M3 x 8 (Figure 1.17, Item 9). Remove the lower G5 module mass replacement (Figure 1.17, Item 22) from the spine box by detaching two pin dowel M4 x 14 (Figure 1.17, Item 30).

Turn the spine box over and remove seven FHCS M6 x 10 (Figure 1.17, Item 15) to remove the seven spacers (Figure 1.17, Item 6) from the left side plate (Figure 1.17, Item 4). Remove three more of the FHCS M6 x 10 (Figure 1.17, Item 15) to separate the upper spine box bracket weldment (Figure 1.17, Item 2) from the left-side plate (Figure 1.17, Item 4).

As shown in Figure 1.24, the six IR-TRACC ball joint assemblies (Figure 1.17, Item 14) are secured to the struck side plate, each with four FHCS M2,5 x 6 (Figure 1.17, Item 13).

Figure 1.24 — IR-TRACC ball joint assemblies are mounted to the struck-side plate of the spine box

1.3.3 Assembling

1.3.3.1 Assembling thorax and abdomen

Figure 1.25 shows the color coding scheme for the WorldSID ribs and that the shoulder rib is grey, the first thoracic rib is red, and the remaining ribs (thorax number two and three, both abdominal) are white.

Note that the inner bands of the two abdominal ribs (Figure 1.15, Item 13) have a thicker layer of damping material than the inner bands of the thoracic ribs (Figure 1.15, Item 12) and that the inner band of the shoulder rib (Figure 1.15, Item 11) is different from the other inner bands.

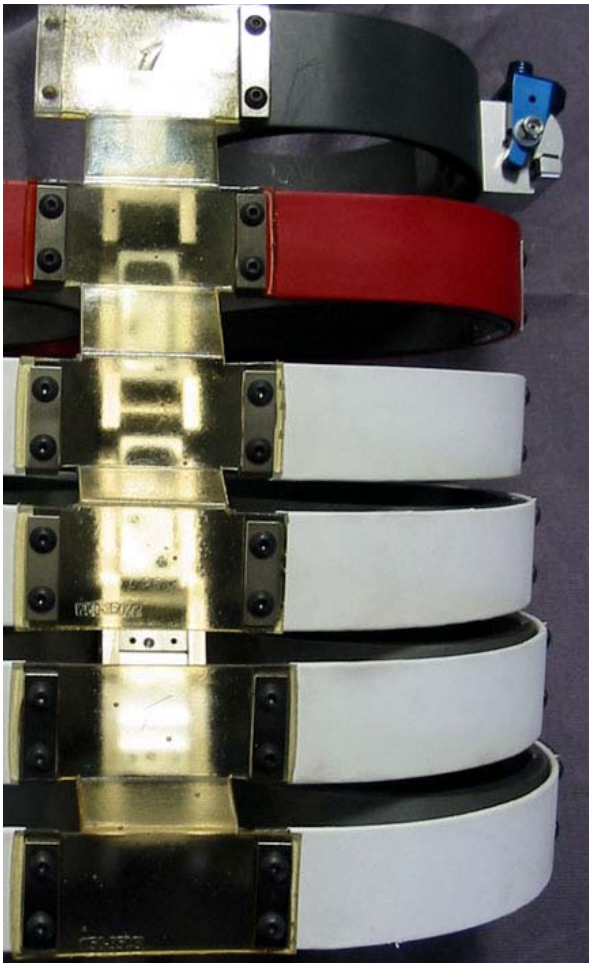


Figure 1.25 — Shoulder rib is grey, the first thoracic rib is red, and the second and third thoracic ribs and abdominal ribs are white

Begin assembly of the thorax by attaching the battery mounting bracket (Figure 1.15, Item 29) with two SHCS M5 x 30 (Figure 1.15, Item 30) that secure it to the spine box on the non-struck side. Attach the battery mass replacement (Figure 1.15, Item 31) with two SHCS M5 x 18 (Figure 1.15, Item 34).

Begin assembly of the ribs from the bottom. Attach the lower abdominal rib (Figure 1.15, Item 4) to the spine box at the rear using two BHCS M5 x 6 (Figure 1.15, Item 26). Secure the inner band of the abdomen (Figure 1.15, Item 13) with two damping clamps (Figure 1.15, Item 24) and four BHCS M5 x 10 (Figure 1.15, Item 10). To permit easier access to the connector

boxes in the spine box, install the instrumentation before attaching the ribs to the rib and abdominal couplers.

Attach the IR-TRACC (Figure 1.15, Item 2) to the spine box with a BHCS M2,5 x 10 (Figure 1.15, Item 32). Connect it to the rib accelerometer bracket (Figure 1.15, Item 15) with the IR-TRACC mount screw (Figure 1.15, Item 21), accessed from the bottom of the rib accelerometer bracket (Figure 1.15, Item 15). Connect the rib clamping bracket (Figure 1.15, Item 19) and the rib accelerometer mounting bracket (Figure 1.15, Item 15) to the inner band and rib with four BHCS M5 x 10 (Figure 1.15, Item 10). Secure the triaxial accelerometer (Figure 1.15, Item 16) to the rib accelerometer mounting bracket (Figure 1.15, Item 15) with a cheese screw M2 x 16 (Figure 1.15, Item 38).

As each IR-TRACC assembly and accelerometer is installed, route the cables toward the centre front (Figure 1.28 and Figure 1.29) of the dummy and plug them into the G5 module connectors. See Section 3 for more detailed wiring information.

Figure 26 shows the arrangement of the components in the first thoracic WorldSID rib and that all of the ribs have a similar general assembly. The inner band of the rib (Figure 1.26, Item 33) is attached to the spine box with damping clamps (Figure 1.26, Item 10) and FHCS. The rib (Figure 1.26, Item 28) is attached to the spine box (Figure 1.26, Item 13) at the rear with BHCS, and to the thorax rib sternum (Figure 1.26, Item 3) at the front using BHCS and the sternum mounting strip (Figure 1.26, Item 4) and threaded sternum mounting strip (Figure 1.26, Item 7). Attach the IR-TRACC assembly (Figure 1.26, Item 14) with a BHCS to the ball joint components which are attached to the spine box. Secure the IR-TRACC to the rib accelerometer mounting bracket (Figure 1.26, Item 32) with a special mounting screw accessed from the bottom. A linear triaxial accelerometer (Figure 1.26, Item 15) is attached to the rib accelerometer mounting bracket (Figure 1.26, Item 32), which is then secured to the inner rib, rib, and rib clamping bracket (Figure 1.26, Item 31) with a BHCS.

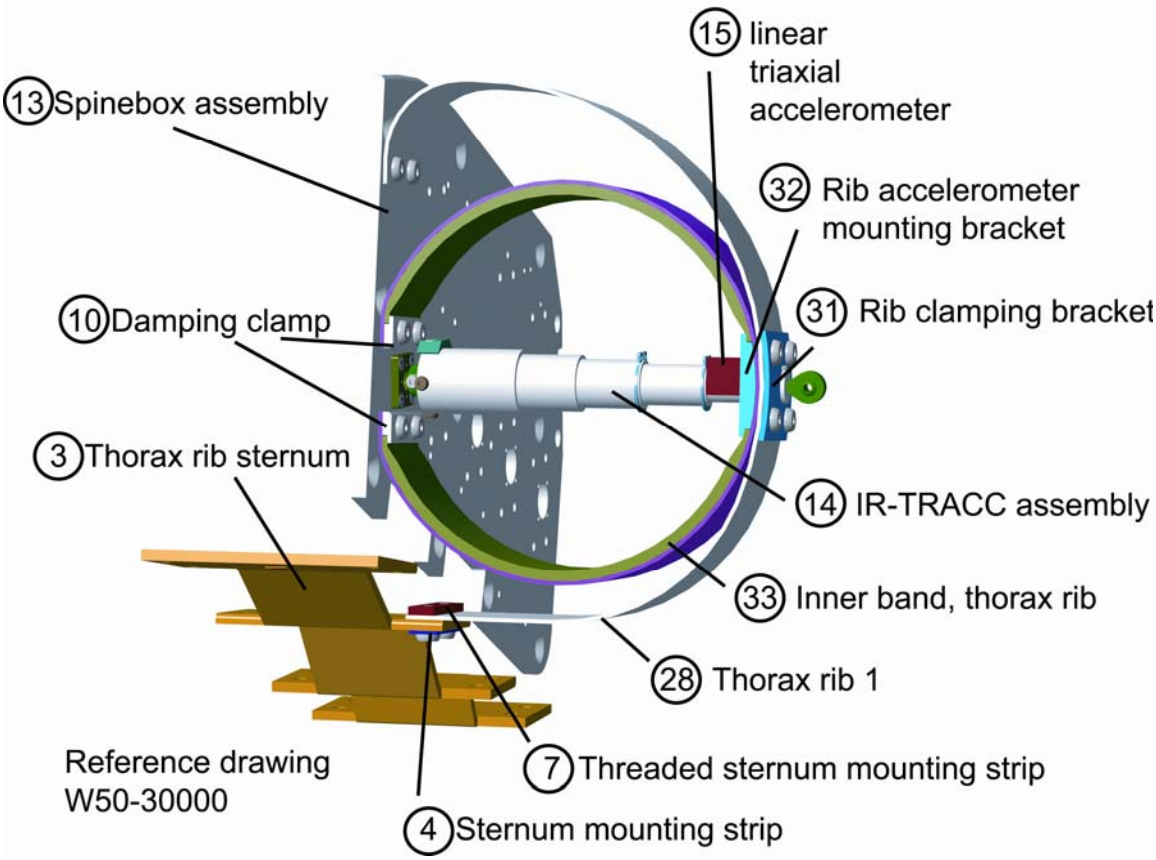


Figure 1.26 — Components of thorax rib

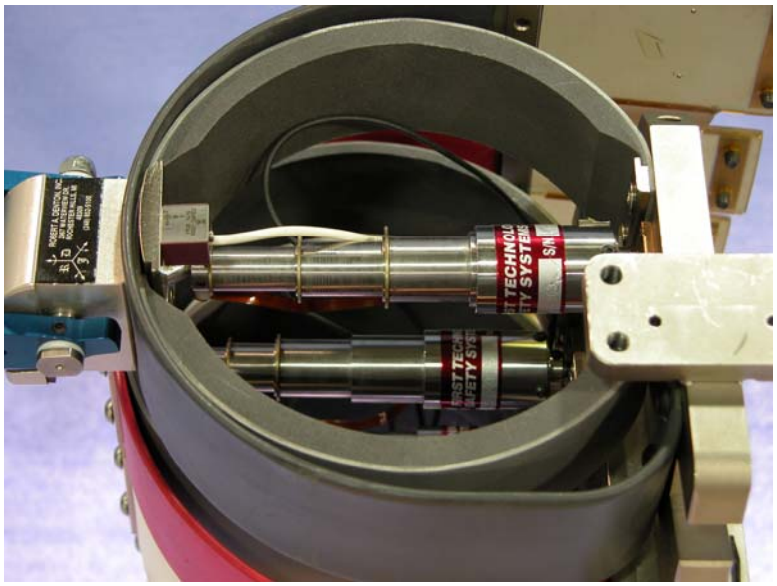


Figure 1.27 — Wire routing for rib instrumentation

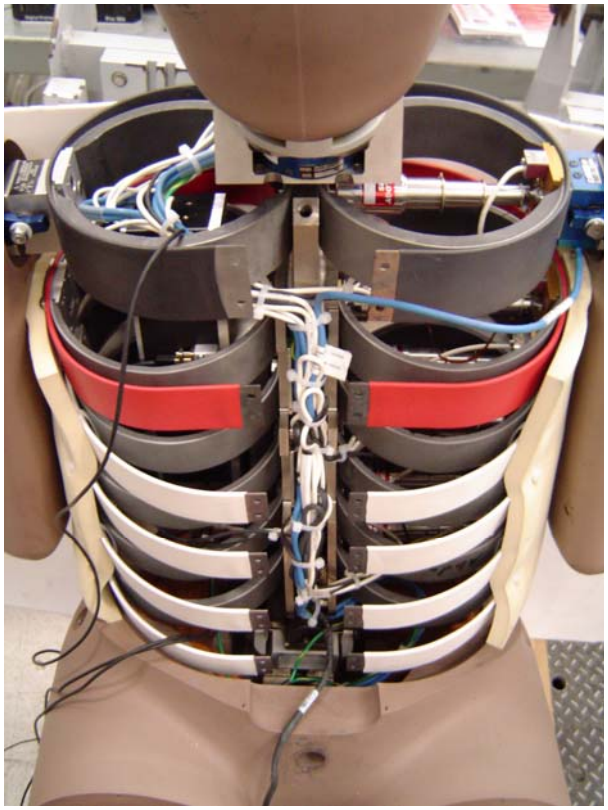


Figure 1.28 — Plugging rib instrumentation cables into the front of the G5 modules mounted in the spine box

Continue installing the ribs with the preceding procedure. Attach the shoulder rib mounting bracket (Figure 1.15, Item 14) to the shoulder rib and shoulder load cell assembly (Table 1.3, Item 23) with four FHCS M5 x 16 (Figure 1.15, Item 20).

After the instrumentation is plugged into the connectors, position a threaded rib mounting strip (Table 1.3, Item 18) behind the front holes on each rib, and place the abdominal rib coupler (Figure 1.15, Item 6) over it. Put the rib mounting strip (Figure 1.15, Item 8) over the rib coupler and secure the rib at the front with two BHCS M5 x 10 (Figure 1.15, Item 10). The installed rib couplers are shown in Figure 1.29.

Attach the lower neck bracket to the spine box with four SHCS M6 x 16 (Table 1.3, Item 37). Attach the thorax pad (Figure 1.15, Item 36) with Velcro®. Place the shoulder pads (Figure 1.15, Items 27 and 28) in position.

To install the thorax pads, check fit the pad against the dummy to make sure the pad covers the ribs and press into place, engaging the Velcro® with light pressure.

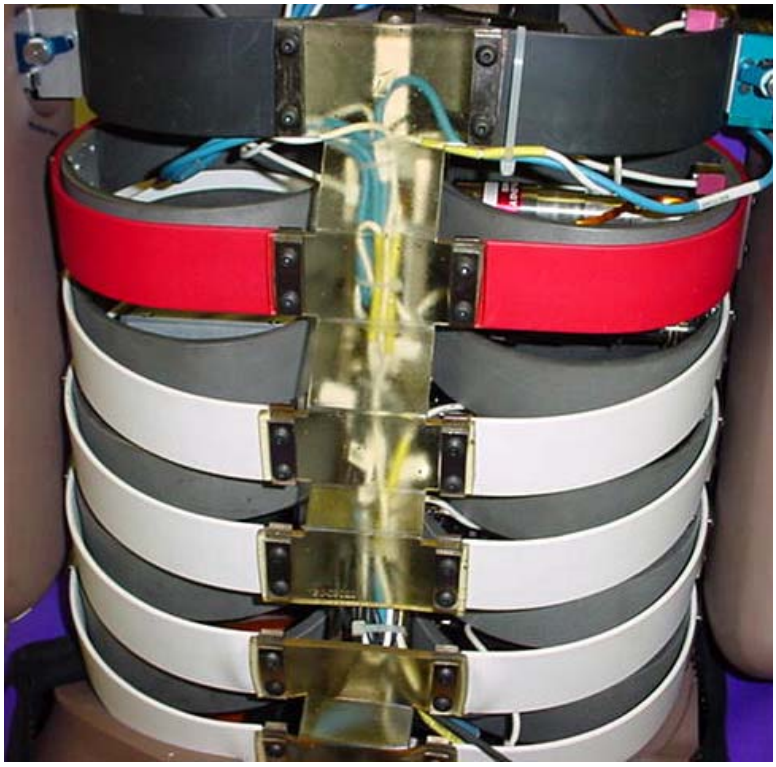


Figure 1.29 — The rib and abdominal couplers are attached to the ribs after instrumentation is plugged in

1.3.3.2 Assembling spine box

Begin assembly of the spine box by mounting the ball joints for the IR-TRACC assemblies to the side plate so they face the struck-side of the dummy. Secure each ball joint (Figure 1.17, Item 14) with four FHCS M2,5 x 6 (Figure 1.17, Item 13). Attach the seven spacers (Figure 1.17, Item 6) to the struck-side plate (Figure 1.17, Item 4 or Item 8) using seven FHCS M6 x 10 (Figure 1.17, Item 15). Attach the upper spine box bracket weldment (Figure 1.17, Item 2) to the struck-side plate with three more FHCS M6 x 10 (Figure 1.17, Item 15).

As shown in Figure 1.30, attach the lower G5 module or its mass replacement (Table 1.5, Item 22) to the spine box with four SHCS M4 x 25 (Figure 1.17, Item 25). Attach each backup plate mounting bracket (Figure 1.17, Item 11) to the spine box with two M4 x 14 pin dowels

(Figure 1.17, Item 30). Connect each interposer or its mass replacement (Figure 1.17, Item 22) to the mounting brackets Number 1 (Figure 1.17, Item 1) and Number 2 (Figure 1.17, Item 21) with four SHCS M2 x 12 (Figure 1.17, Item 17). Secure the mounting brackets/interposers to the spine box with four SHCS M4 x 25 (Figure 1.17, Item 25). Slide the G5 modules or their mass replacements (Figure 1.17, Item 22) into the mounting brackets and connect them to the interposers. Attach the spine box cover plate (Figure 1.17, Item 23) to the back of each G5 module or its mass replacement with two BHCS M6 x 18 (Figure 1.17, Item 19). Attach each connector housing or its mass replacement (Figure 1.17, Item 10) to its backup plate mounting bracket (Figure 1.17, Item 11) with three SHCS M3 x 8 (Figure 1.17, Item 9).

Next assemble the angular accelerometer assembly (Figure 1.17, Item 24). Attach the z-axis angular accelerometer to the bottom of the bracket with two FHCS. Attach the x-axis rotational accelerometer to the back of the bracket with two FHCS so it is parallel to the bottom of the bracket. Attach the dual-axis tilt sensor (Figure 1.17, Item 27) to the back of the bracket with a SHCS. Position the rotational accelerometer assembly (Figure 1.17, Item 24) on the spine box and secure it with three SHCS M3 x 10 (Figure 1.17, Item 5). Plug the cables for the rotational accelerometers sensors into a G5 module, but leave the connectors for the dual-axis tilt sensor free to be plugged into the off-board readout during dummy setup.

Attach the T12 accelerometer mount (Figure 1.17, Item 7) to the spine box with two SHCS M3 x 10 (Figure 1.17, Item 5). Attach the accelerometer (Figure 1.17, Item 16) to the mount with a cheese screw M2 x 16 (Figure 1.17, Item 18). Orient the accelerometer so that the cable points upward and can be routed between the middle G5 module and angular accelerometer assembly to be plugged into the G5 module. Attach the linear triaxial accelerometer (Figure 1.17, Item 16) to the top of the spine box weldment with a cheese screw M2 x 16 (Figure 1.17, Item 18). Plug the cable for the upper accelerometer into the G5 module after the ribs are installed.

Attach the other side plate (Figure 1.17, Item 4 or 8) to the spine box with ten FHCS M6 x 10 (Figure 1.17, Item 15). Make sure the cables from the T12 or angular accelerometer assembly are not pinched by the side plate.

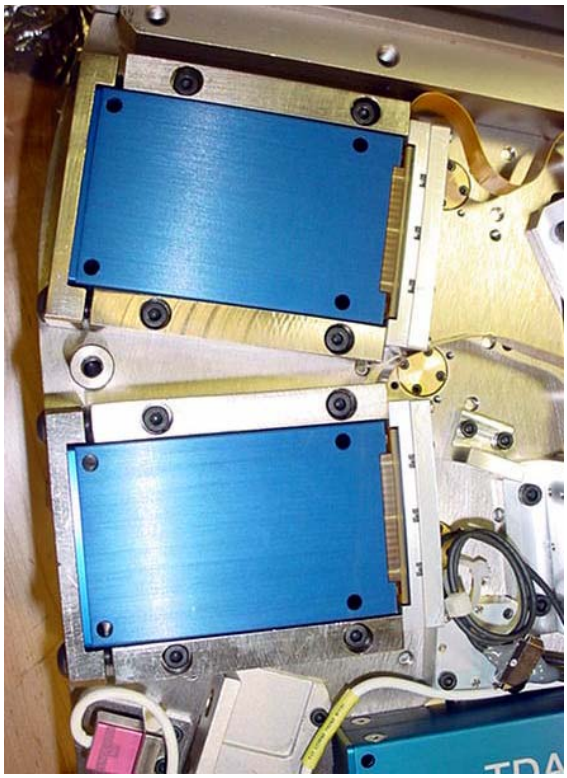


Figure 1.30 — Installation of G5 modules

1.3.4 Instrumentation mounting

1.3.4.1 Thorax instrumentation

The thorax instrumentation for the WorldSID includes an IR-TRACC deflection measurement assembly for each struck-side rib, plus a triaxial accelerometer attached to the inner struck side of each rib. Figure 1.31 illustrates the configuration for the assembly of the rib with instrumentation. The IR-TRACC assembly (Figure 1.31, Item 14) is attached to the spine box with a BHCS M2,5 (Figure 1.31, Item 11), and that the other end of the IR-TRACC assembly is attached to the rib accelerometer mounting bracket (Figure 1.31, Item 32) with an IR-TRACC rib mount screw (Figure 1.31, Item

19) accessed from the bottom of the rib. A linear triaxial accelerometer (Figure 1.31, Item 15) is secured to the rib accelerometer mounting bracket (Figure 1.31, Item 32) with a cheese screw M2 x 16 (Figure 1.31, Item 37), and that the rib accelerometer mounting bracket (Figure 1.31, Item 32) is secured to the inner band of the rib (Figure 1.31, Item 33), the thorax rib (Figure 1.31, Item 28), and the rib clamping bracket (Figure 1.31, Item 31) with four BHCS M5 x 10 (Figure 1.31, Item 1).

A battery to power the G5 modules is part of the thorax assembly and that additional instrumentation attached to the spine box is described in the disassembly/assembly section for the spine box. A shoulder load cell is also available for use with the WorldSID.

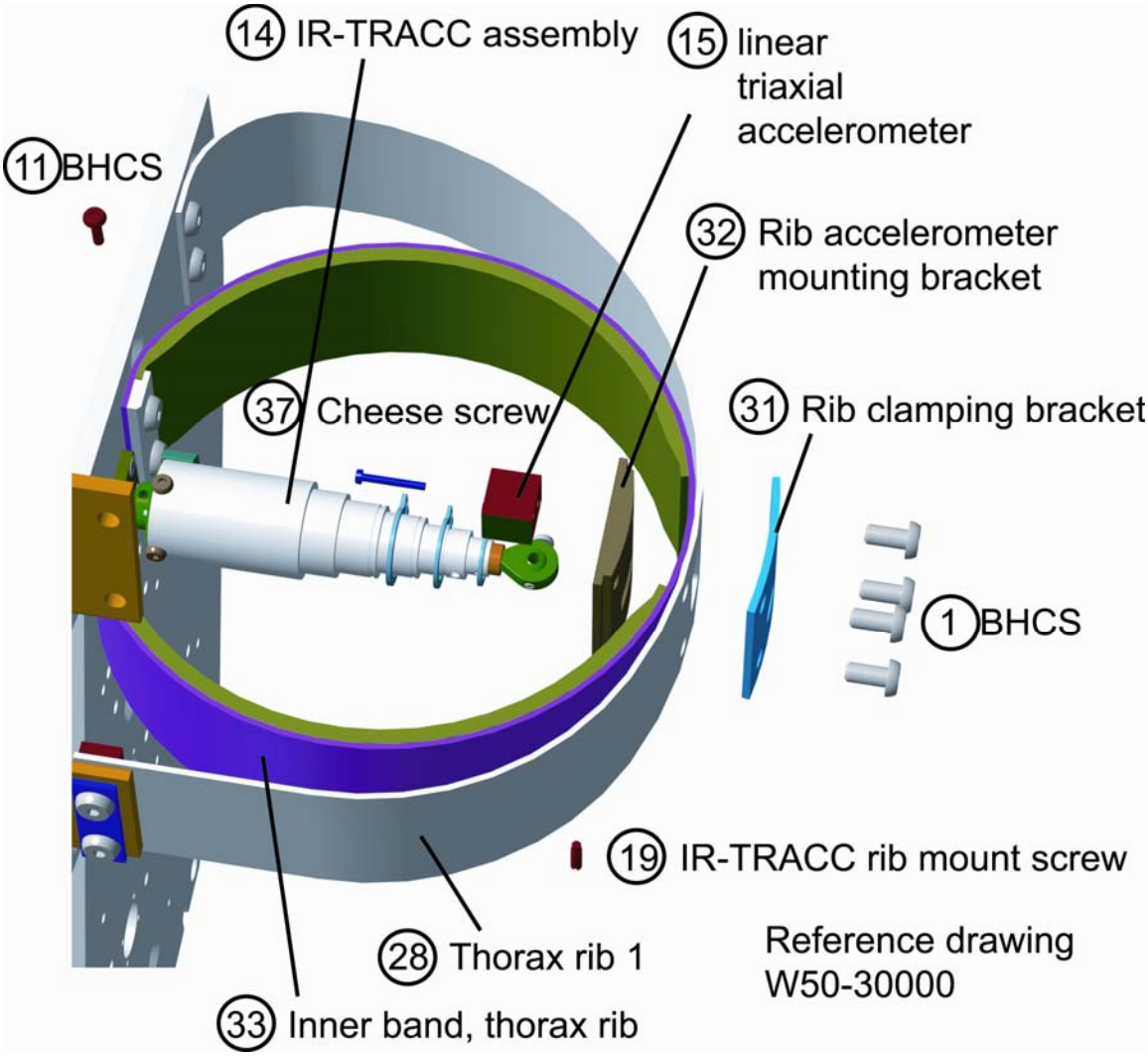


Figure 1.31 — WorldSID rib instrumentation

1.3.4.2 Spine box instrumentation

The spine box includes mounting positions for two G5 DAS modules, one of which is shown in Figure 1.32. Note that for both of these, an interposer connector (see Figure 1.33) is attached to the mounting brackets, and the DAS module is plugged into this connector. The connector for each DAS (see Figure 1.34), which is linked to the interposer connector, is secured to a bracket mounted to the spine box. The arrangement of the DAS and connectors is shown in Figure 1.35. Note that for the lower G5 module,

the connector is mounted adjacent to the module, so the module plugs in directly to the connector and no interposer is used.

Figure 1.32 — G5 DAS module

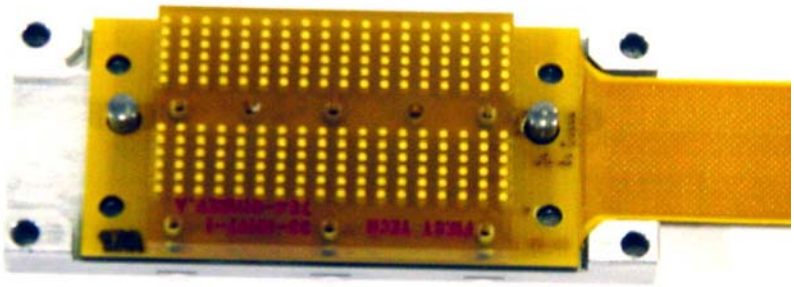


Figure 1.33 — Interposer connector

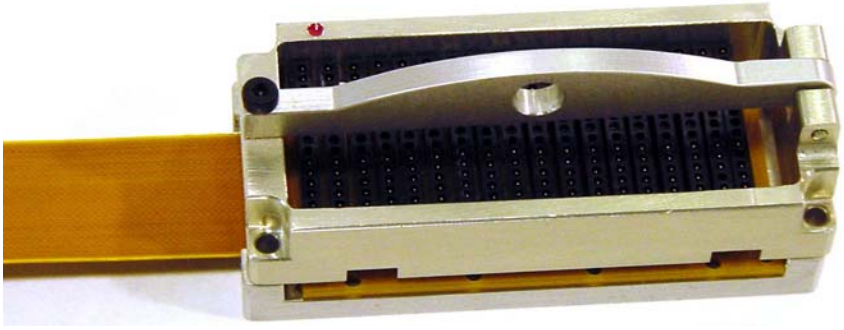


Figure 1.34 — DAS connector

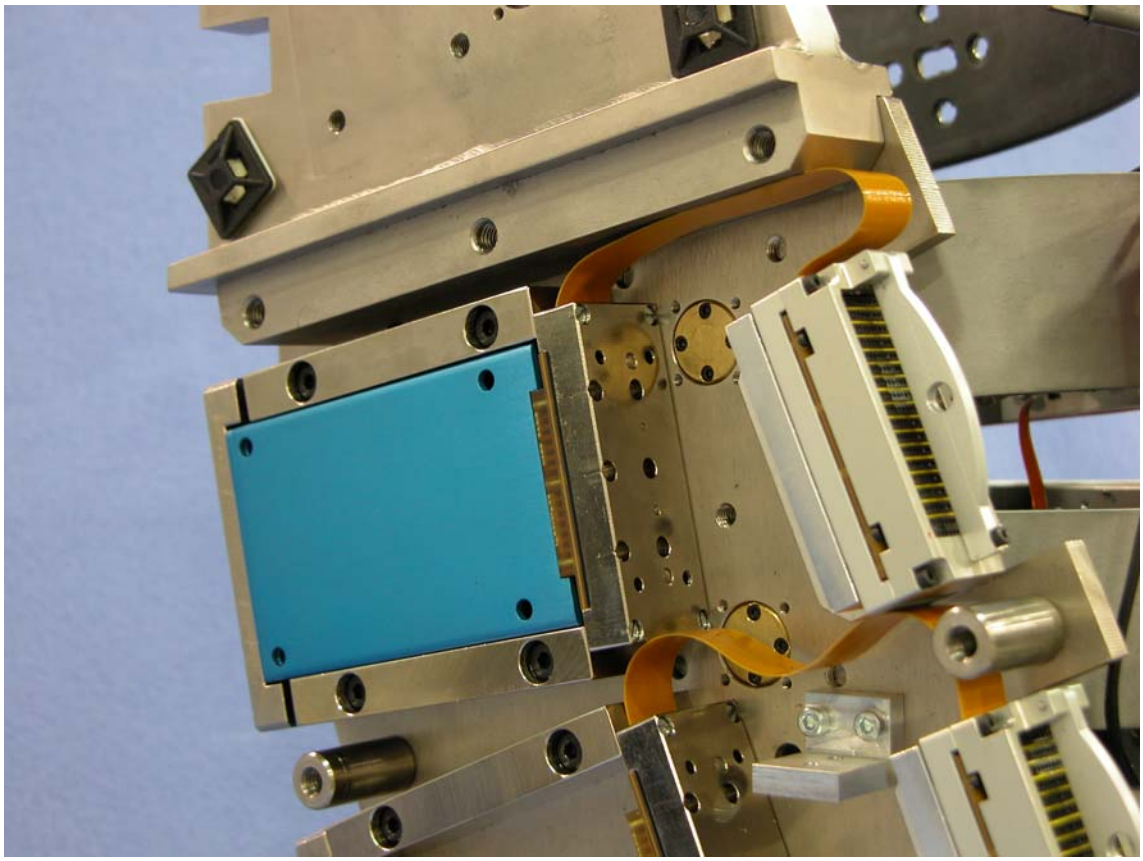


Figure 1.35 — Arrangement of DAS, interposer connector, and connector

Other instrumentation in the spine box includes a linear triaxial accelerometer mounted directly to the spine box near the top, and that a second linear triaxial accelerometer is mounted to a bracket attached to the spine box near the location of the T12 thoracic vertebra. An angular accelerometer assembly, which includes rotational accelerometers to measure x- and z-axis angular acceleration, plus a dual-axis tilt sensor, is mounted near the bottom of the spine box, and in addition, the ball joint portions of six IR-TRACC assemblies are mounted to the spine box plate on the struck-side of the dummy.

1.4 Full arm

1.4.1 Parts list

1.4.1.1 Parts list for full arm

The parts and assemblies required for assembling the WorldSID full arm (W50-61000 (left); W50-61001 (right)) are the upper arm assembly, lower arm assembly (see Figure 1.36, Items 1 and 9 respectively), moulded hand (Figure 1.36, Item 10), shoulder assembly (Item 22; not included with assembly, shown for reference only) and moulded shoulder bumper (Figure 1.36, Item 19), potentiometer, pivot adjustment hardware, and strain relief hardware.

Table 1.6 lists the parts required for assembling the WorldSID full arm, which is illustrated in Figure 1.36.

Table 1.6 — Parts list for full arm

Item number	Description	Qty	Part number
1	Upper arm assembly, left	1	W50-61002
not shown	Upper arm assembly, right	1	W50-61003
2	Elbow shaft assembly	1	W50-61028
3	Elbow potentiometer mass replacement	1	W50-61123
4	M3 flat washer	2	5000181
5	BHCS M3 x 0,5 x 10 mm	2	5000178
6	BHCS M4 x 0,7 x 6 mm	1	5000179
7	M4 flat washer	1	5000155
8	Cable clamp	1	5000191
9	Lower arm assembly	1	W50-61034
10	Moulded hand assembly, left	1	W50-61037
not shown	Moulded hand assembly, right	1	W50-61069
11	Spring washer	1	W50-61022
12	SHSS M6 x 25 mm	1	5000163
13	BHCS M10 x 1,5 x 20 mm	1	5000176
14	Clamping washer (steel)	1	W50-61014

Item number	Description	Qty	Part number
15	Compression washer (rubber)	1	W50-61016
16	Friction washer	1	W50-52064
17	Cable guide	4	W50-61030
18	BHCS M3 x 0,5 x 6 mm	8	5000171
19	Shoulder bumper assembly	1	W50-61110
20	LHSHCS M3 x 0,5 x 12 mm	2	5000620
21	SSNT M3 x 0,5 x 3 mm	1	5000190
21	Flexion-extension stop assembly	1	W50-61054
22	Full arm clevis assembly	1	W50-61051
23	SSHDP M6 x 1,0 x 6 mm	1	5000165
Not shown	Upper arm flesh, left	1	W50-61099
Not shown	Upper arm flesh, right	1	W50-61098
Not shown	Lower arm flesh	1	W50-61100
Not shown	Elbow potentiometer (optional)	1	W50-61027

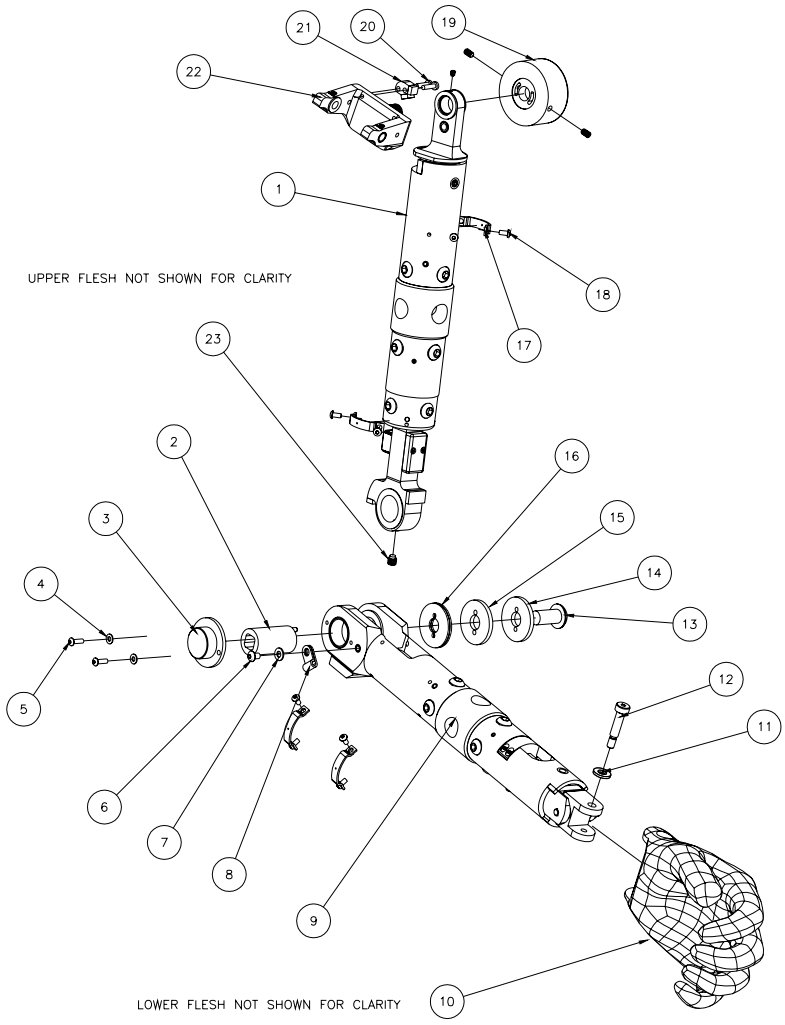


Figure 1.36 — Full arm, exploded

1.4.1.2 Parts list for shoulder arm

Table 1.7 lists the parts for assembling the WorldSID shoulder-arm, which is illustrated in Figure 1.37.

Table 1.7 — Parts list for shoulder-arm

Item number	Description	Qty	Part number
1	Shoulder load cell	1	W50-71090
not shown	Shoulder load cell structural replacement	1	W50-71092
2	Shoulder clevis assembly	1	W50-61051
3	SSNT M3 x 0,5 x 3 mm	1	5000190
4	Shoulder bumper	1	W50-61110
5	SSFP M4 x 0,7 x 6 mm	2	5000464
6	Spring plunger	1	5000256
7	Arm tube assembly	1	W50-61012
8	BHCS M6 x 1,0 x 16 mm	1	5000072
9	SSNT M6 x 1,0 x 6 mm	1	5000621

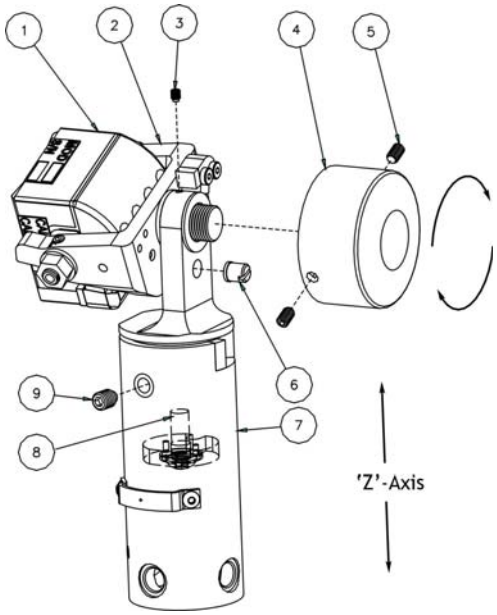


Figure 1.37 — Shoulder-arm detail

1.4.1.3 Parts list for upper arm

Table 1.8 lists the parts required for assembling the WorldSID upper arm, which is illustrated in Figure 1.38.

Table 1.8 — Parts for upper arm

Item number	Description	Qty	Part number
1	Upper arm "Z" pivot assembly, left Upper arm “Z” pivot assembly, right	1	W50-61006 W50-61111
2	Upper arm tube assembly	1	W50-61012
3	Modified button head cap screw	12	W50-61042
4	Wrist washer	1	W50-61019
5	Spring washer	1	W50-61022
6	BHCS M6 x 1,0 x 16 mm	1	5000072
7	Universal arm load cell	1	W50-71070
not shown	Arm load cell structural replacement	1	W50-61041
8	Upper arm extension tube assembly	1	W50-61004
9	SHCS M2 x 0,4 x 18 mm	2	5000164
10	Accelerometer mass replacement	1	W50-61063
11	Elbow load cell	1	W50-71060
Not shown	Elbow structural replacement	1	W50-61065
Not shown	Triaxial linear accelerometer	1	Endevco 7268C-2000M1

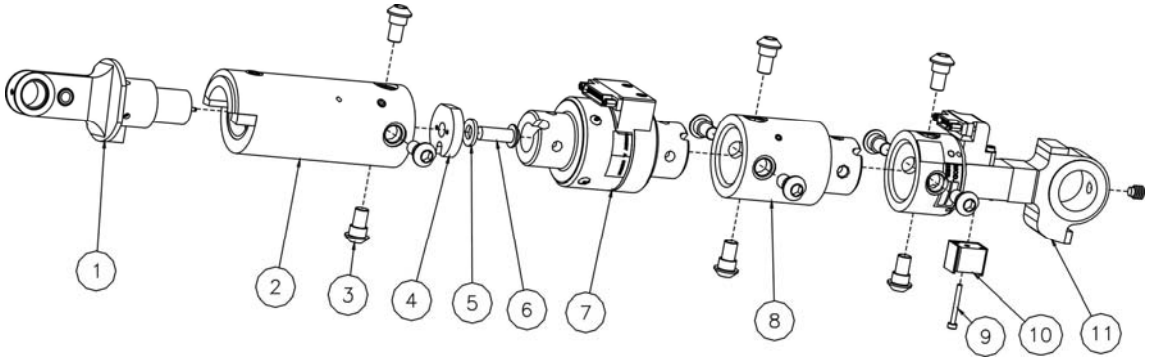


Figure 1.38 — Upper arm, exploded

1.4.1.4 Parts list for elbow

Table 1.9 lists the parts required for assembling the WorldSID elbow, which is illustrated in Figure 1.39.

Table 1.9 — Parts list for elbow

Item number	Description	Quantity	Part number
1	BHCS M3 x 0,5 x 10	2	5000178
2	M3 flat washer	2	5000181
3	Elbow potentiometer assembly	1	W50-61027
4	Elbow clevis assembly	1	W50-61029
5	SSHDP M6 x 1,0 x 6 mm	1	5000165
6	Friction washer assembly	1	W50-52064
7	Compression washer	1	W50-61016
8	Clamping washer	1	W50-61014
9	BHCS M10 x 1,5 x 20 mm	1	5000176
10	Elbow load cell	1	W50-71060
11	Elbow shaft assembly	1	W50-61028
Not shown	Elbow load cell structural replacement	1	W50-61065

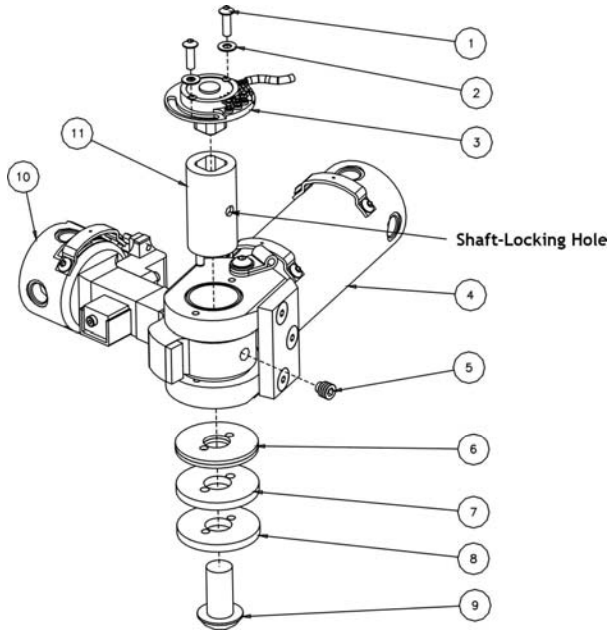


Figure 1.39 — Elbow section

1.4.1.5 Parts list for lower arm

Table 1.10 lists the parts required for assembling the WorldSID lower arm, which is illustrated in Figure 1.40.

Table 1.10 — Parts for lower arm

Item number	Description	Qty	Part number
1	Elbow clevis assembly	1	W50-61029
2	Modified BHCS	8	W50-61042
3	Arm load cell (optional)	1	W50-71070
Not shown	Arm load cell structural replacement	1	W50-61041
4	BHCS M6 x 1,0 x 16 mm	1	5000072
5, 11	Spring washer	2	W50-61022
6	Wrist washer	1	W50-61019
7	Lower arm tube assembly	1	W50-61035
8	SHCS M3 x 0,5 x 12 mm	1	5000070

Item number	Description	Qty	Part number
9	Wrist pivot assembly	1	W50-61020
10	Wrist clevis assembly	1	W50-61033
12	SHSS M6 x 25 mm	2	5000163
13	Wrist pivot bumper	2	W50-61046
14	SSNT M6 x 1,0 x 6 mm	1	5000622
15	SHCS M2 x 0,4 x 18 mm	1	5000164
16	Accelerometer mass replacement	1	W50-61063
17	Accelerometer mount bracket	1	W50-61039
18	SHCS M2,5 x 0,45 x 8 mm	4	5000458
Not shown	Triaxial linear accelerometer	1	Endevco 7268C-2000M1

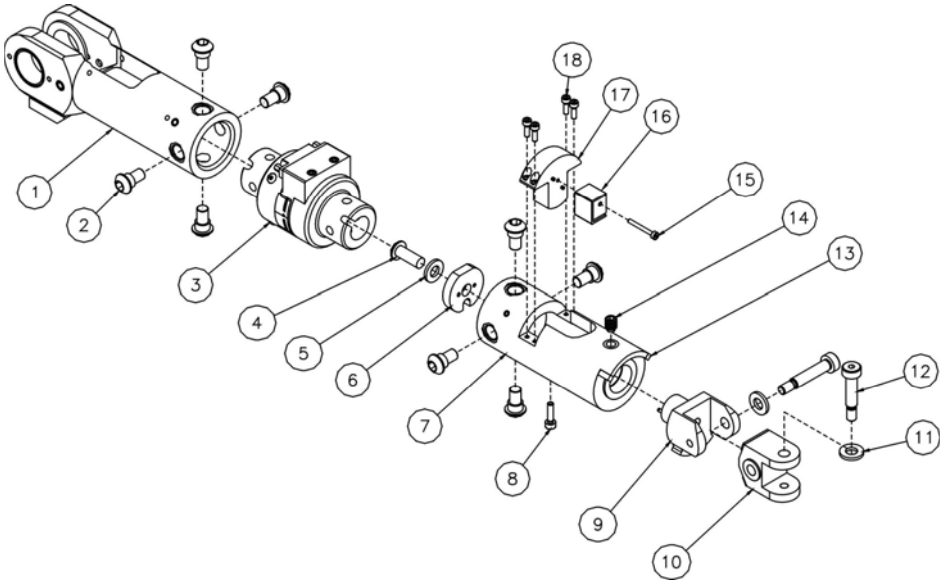


Figure 1.40 — Lower arm, exploded

1.4.1.6 Parts list for wrist

Table 1.11 lists the parts required for assembling the WorldSID wrist, which is illustrated in Figure 1.41.

Table 1.11 — Parts list for wrist

Item number	Description	Quantity	Part number
1	Wrist clevis	1	W50-61033
2	Wrist pivot assembly	1	W50-61020
3	Lower arm tube assembly	1	W50-61036
4	SSNT M6 x 1,0 x 6 mm	1	5000621
5	SHCS M2 x 0,4 x 18 mm	1	5000164
6	Wrist accelerometer mount	1	W50-61039
7	SHCS M2,5 x 0,45 x 8 mm	4	5000458
8	Wrist washer	1	W50-61019
9	Spring washer	2	W50-61022
10	BHCS M6 x 1 x 16 mm	1	5000072
11	SHCS M3 x 0,5 x 12 mm	1	5000173
12	SHSS M6 x 25 mm	1	5000163

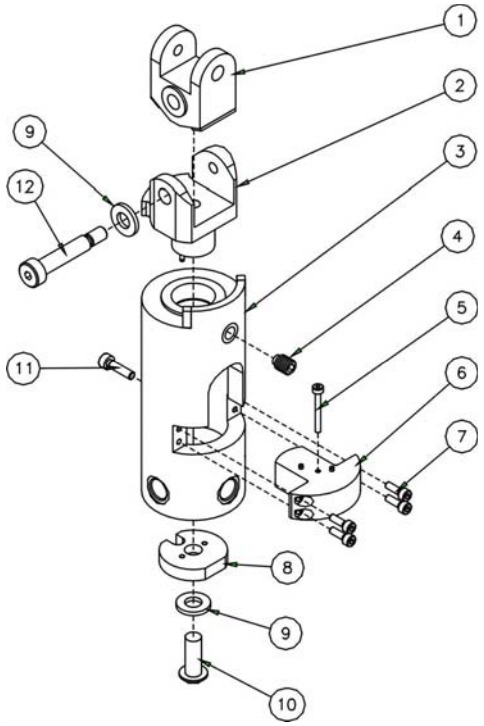


Figure 1.41 — Wrist

1.4.2 Disassembling

1.4.2.1 Full arm

To remove the arm assembly from the shoulder assembly, loosen the two-friction adjustment set screws (SSFP M4 x 0,7 x 6 mm, Figure 1.37, Item 5) in the shoulder bumper (Figure 1.37, Item 4). Unthread the shoulder bumper from the shoulder clevis. Remove the SSNT M3 x 0,5 x 3 mm on the top of the "Z" pivot assembly. Separate the arm assembly from the shoulder assembly.

Remove the hand assembly by taking out the SHSS M6 x 25 mm (Figure 1.36, Item 12) at the hand-wrist pivot joint. Watch for the spring washer (Figure 1.36, Item 11) to fall out of the assembly as the screw is removed. This washer is made of soft plastic (urethane) and thus the screw head may damage it. Inspect and replace as necessary. Inspect the hand bumpers, checking for cuts in the bumper material or signs that the bumper adhesive may be failing.

Remove the upper arm flesh by opening the Velcro® on the inboard side of the upper arm flesh and then pulling the arm flesh open and off of the arm.

Remove the lower arm flesh by opening the Velcro® holding the flaps at the elbow closed and moving them over the potentiometer assembly and friction adjustment screw. Hold the upper arm and pull the flesh towards the wrist to remove it from the lower arm.

Disassemble the lower arm from the upper by first disconnecting the connector from the lower arm load cell. Remove the cable guides that are held (Figure 1.36, Item 17) in position using two BHCS M3 x 0,5 x 6 mm (Figure 1.36, Item 18) for each clamp. Remove the potentiometer assembly from the elbow joint by taking out the BHCS M4 x 0,7 x 6 mm and M4 flat washer (Figure 1.36, Items 6 and 7) holding the potentiometer wiring cable in position. Remove the two BHCS M3 x 0,5 x 10 mm and M3 flat washer (Figure 1.36, Items 5 and 4) securing the potentiometer body in position and slide out the potentiometer from the body of the elbow shaft assembly (Figure 1.36, Item 2).

Remove the BHCS M10 x 1,5 x 20 mm (Figure 1.36, Item 13) from the elbow shaft assembly along with the three joint friction adjustment washers (Figure 1.36, Item 14, 15 and 16). Remove the SSHDP M6 x 1,0 x 6 mm (Figure 1.36, Item 23) securing the elbow shaft assembly in the elbow joint and slide the elbow shaft assembly out of the elbow and separate the upper and lower arm assemblies.

1.4.2.2 Disassembling upper arm

Disconnect the cables to the arm and elbow load cells and remove the accelerometer.

To remove the elbow load cell (Figure 1.38, Item 11) take out the four modified BHCS (Figure 1.38, Item 3) that attach it to the upper arm

extension tube (Figure 1.38, Item 8). The elbow load cell also contains the mounting position for the triaxial linear accelerometer. Note that the accelerometer is held in place using a SHCS M2 x 0,4 x 18 mm (Figure 1.38, Item 9) on the rear side of the load cell.

Remove all the modified BHCS's and separate the arm load cell (Figure 1.38, Item 7) from the arm extension tube (Figure 1.38, Item 8) and the upper arm tube assembly (Figure 1.38, Item 2) from the arm load cell.

To remove the "Z" pivot (Figure 1.38, Item 1), loosen the SSNT M6 x 0 x 6 mm friction adjustment screw (Figure 1.37, Item 9) and take out the BHCS M6 x 1 x 16 mm (Figure 1.38, Item 6) and the spring washer (Figure 1.38, Item 5) and wrist washer (Figure 1.38, Item 4). Pull the "Z" pivot out of the upper arm tube assembly.

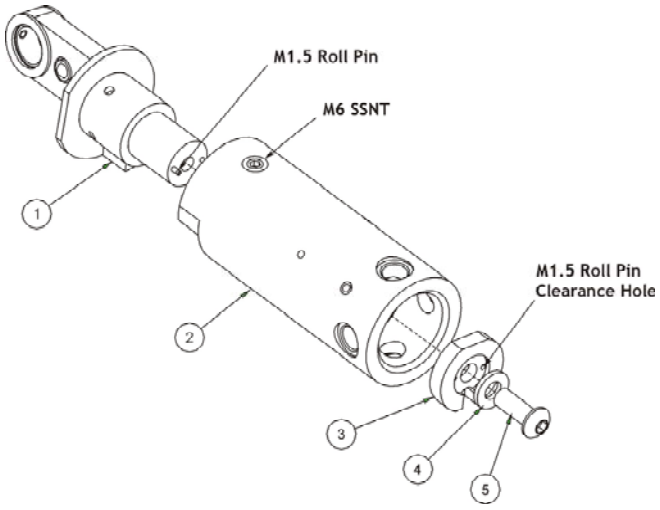


Figure 1.42 — 'Z' Pivot and upper arm tube

While the components are disassembled make a thorough inspection of bearing and mating surfaces. Ensure that wear or damage will not affect the performance of the arm assembly. Refer to Figure 1.42. Inspect the M1,5 roll pins in the end of the "Z" pivot (Figure 1.42, Item 1) to make sure they are not bent.

1.4.2.3 Disassembling elbow

The elbow joint is disassembled by removing the BHCS M10 x 1,5 x 20 mm (Figure 1.39, Item 9) at the elbow pivot. This BHCS M10 provides the tension necessary for the 1-to-2-G-setting in the elbow. When this screw is removed the clamping, compression and friction washers (Figure 1.39, Items 8, 7, and 6 respectively) can be pulled from the assembly.

Loosen or remove the SSHDP M6 x 1 x 6 mm (Figure 1.39, Item 5) from the elbow load cell and the elbow shaft assembly (Figure 1.39, Item 11) can be pulled from the elbow joint. With the shaft assembly removed the elbow load cell and clevis assembly can be pulled apart.

The elbow potentiometer (Figure 1.39, Item 3) can be removed by taking out the two BHCS M3 x 0,5 x 10 mm (Figure 1.39, Item 1) and the associated M3 flat washers (Figure 1.39, Item 2).

1.4.2.4 Disassembling lower arm

Before disassembling the lower arm assembly, remove the triaxial linear accelerometer located in the wrist assembly. Remove the accelerometer mounting bracket (Figure 1.40, Item 17). Hold the bracket in place by four SHCS M2,5 x 0,45 x 8 mm (Figure 1.40, Item 18) and one SHCS M3 x 0,5 x 12 mm (Figure 1.40, Item 8). Hold the 7268C triaxial linear accelerometer in position using a SHCS M2 x 0,4 x 18 mm (Figure 1.40, Item 15).

To begin disassembly, after disconnecting all cables, remove the modified BHCS (Figure 1.40, Item 2) that secure the elbow clevis (Figure 1.40, Item 1) and arm load cell (Figure 1.40, Item 3) and separate these two components. Remove the modified BHCS screws that attach the arm load cell and the wrist assembly, pull the two sections apart.

1.4.2.5 Disassembling wrist

The wrist assembly (W50-61035) is shown in Figure 1.41.

To remove the wrist pivot and clevis assemblies, take out the BHCS M6 x 1 x 16 mm (Figure 1.41, Item 10) that holds the wrist pivot assembly in the wrist assembly. Remove the wrist washer (Figure 1.41, Item 8) and the spring washer (Figure 1.41, Item 9). These two washers are the same as the parts in the upper arm assembly (Figure 1.38, Items 4 and 5). Loosen the SSNT M6 in the wrist assembly (Figure 1.41, Item 4) and pull the wrist pivot assembly (Figure 1.41, Item 2) from the wrist assembly.

Take out the SHSS M6 x 25 mm (Figure 1.41, Item 12) and the rubber washer (Figure 1.41, Item 9). Separate the wrist pivot and wrist clevis assemblies (Figure 1.41, Items 2 and 1 respectively).

Inspect the rubber bumpers (W50-61038) on the wrist clevis to ensure there is no damage to the material and that they are securely fixed in position. If the bumpers should come loose or fall off, re-glue with Loctite® 414, "Super-Glue", or equivalent cyanoacrylate based adhesive.

1.4.3 Assembling the arm

1.4.3.1 General

In general the procedure for assembling the arm is substantially the opposite of the procedure for disassembling it. The following descriptions are provided to assist the user to more efficiently assemble the WorldSID arm.

1.4.3.2 Assembling the upper arm

To assemble the arm to the upper torso, install the arm on the shoulder load cell clevis. Push the arm onto the shoulder clevis (Figure 1.37, Item 2) until it fully contacts the clevis face. Thread the shoulder bumper (Figure 1.37, Item 4) onto the shoulder clevis. Thread the bumper as a coarse adjustment for the arm's 1-to-2-g-setting. Tighten the SSNT M3 x 0,5 x 3 mm (Figure 1.37, Item 3) to fine adjust.

Note that inside the upper arm tube there are three components that are involved in the adjustment of "Z"-pivot joint: the wrist washer (Figure 1.38, Item 4), spring washer (Figure 1.38, Item 5) and a BHCS M6 x 1 x 16 mm (Figure 1.38, Item 6).

Slide the "Z"-pivot assembly (Figure 1.38, Item 1) into the upper arm tube (Figure 1.38, Item 2). Install the wrist washer into the tube as shown in Figure 1.42, orient the washer so that the through holes for the M1,5 pins are aligned with the pins on the "Z"-Pivot. Place the spring washer on the BHCS M6 (Figure 1.42, Item 5) and thread the screw into the base of the "Z"-Pivot. Tighten the BHCS M6 and spring washer until they contact the wrist washer and then turn it 1/8 turn tighter. Do not over tighten this joint; the wrist pivot must be able to rotate.

1.4.3.3 Assembling elbow

To reassemble the elbow section, align the elbow load cell (Figure 39, Item 10) and elbow clevis (Figure 1.39, Item 4) so that the elbow shaft assembly (Figure 1.39, Item 11) can be inserted into the elbow pivot hole. Line up the shaft-locking hole with the SSHDP M6 x 1 x 6 mm (Figure 1.39, Item 5). This screw locks the elbow shaft to the elbow load cell so that the potentiometer attached to the elbow clevis can measure the angular displacement of the elbow load cell about the lower arm assembly.

Install the friction washer assembly (Figure 1.39, Item 6) on the elbow shaft. Press the washer over the pins onto the elbow shaft completely. Install the next two washers, (Figure 1.39, Items 7 and 8) on the elbow shaft and secure all three in place with a BHCS M10 x 1,5 x 20 mm (Figure 1.39, Item 9). Use this screw to adjust the joint tension to 1-to-2-g-setting. Do this adjustment with the complete arm assembly.

Attach the elbow potentiometer assembly to the elbow clevis assembly using two BHCS M3 x 0,5 x 10 and two M3 flat washers (Figure 1.39, Items 1 and 2 respectively). To adjust the potentiometer “zero” position align

the elbow load cell body with the elbow clevis body, and then connect the potentiometer to the data acquisition system to be used for testing. Loosen the two BHCS M3 (Figure 1.39, Item 1) securing it to the elbow clevis and rotate the potentiometer body until 0 volts output is achieved. If there is not sufficient angular displacement available to achieve 0 volts, remove the two BHCS M3 and their associated washers, then lift the potentiometer assembly out of the elbow shaft. Rotate the potentiometer insert (see Figure 1.43) 90°, replace the unit on the elbow clevis, and check the output again.

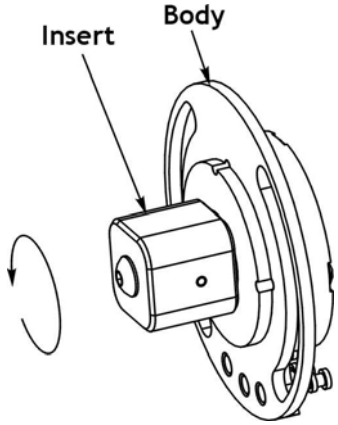


Figure 1.43 — Elbow potentiometer

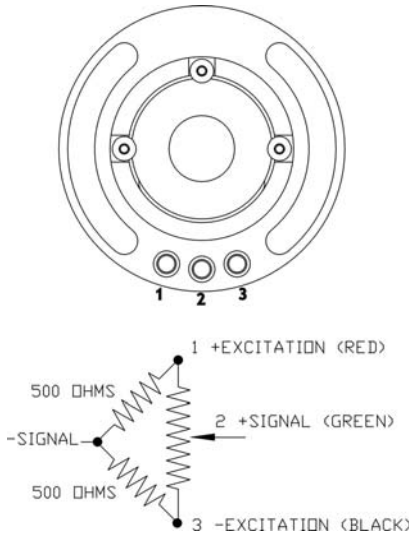


Figure 1.44 — Elbow potentiometer wiring

1.4.3.4 Assembling lower arm

Attach the arm load cell (Figure 1.40, Item 3) (or structural replacement) to the elbow clevis assembly (Figure 1.40, Item 1) using four modified BHCS M6, torque to 10 Nm.

The wrist assembly is attached to the arm load cell using four modified BHCS M6 (Figure 1.40, Item 2) torqued to 10 Nm.

1.4.3.5 Assembling wrist

Inspect the hand bumpers (W50-61048). If they are loose or missing, reinstall using Loctite® 414, “Super-Glue” or equivalent cyanoacrylate based adhesive.

The wrist assembly (see Figure 1.41) has the same type of joint as the upper arm "Z"-pivot. Re-assemble the wrist assembly by installing the wrist pivot (Figure 1.41, Item 2) into the lower arm tube (Figure 1.41, Item 3) and then aligning the wrist washer (Figure 1.41, Item 8) on to the M1,5 pins. After the wrist washer is installed insert the spring washer (Figure 1.41, Item 9) and an BHCS M6 x 1 x 16 (Figure 1.41, Item 10) into the tube and the screw is tightened until the BHCS and spring washer contact the wrist washer. Then turn the screw one-eighth (1/8) turn tighter. Use the SSNT M6 x 1 x 6 mm (Figure 1.41, Item 4) to control rotational friction for the 1-to-2-g-setting.

Fit the wrist-mounted triaxial linear accelerometer on the accelerometer mount (Figure 1.41, Item 6). The mount is secured in place with four SHCS M2,5 x 0,45 x 8 mm (Figure 1.41, Item 7) and one SHCS M3 x 0,5 x 12 mm (Figure 1.41, Item 11). Attach the accelerometer with an SHCS M2 x 0,4 x 18 mm (Figure 1.41, Item 5).

Attach the wrist clevis assembly (Figure 1.41, Item 1) to the wrist pivot with a spring washer (Figure 1.41, Item 9) and an SHSS M6 x 25 mm

(Figure 1.41, Item 12). Tighten this screw to approximately a 1-to-2-g-setting, so that there is some stiffness to the joint without “locking” the joint.

1.4.4 Adjusting the arm

1.4.4.1 General

The arm assembly friction is adjusted at several points along the arm to ensure the biomechanical performance of the assembly during testing, and that all joints are adjusted to a 1-to-2-G-setting.

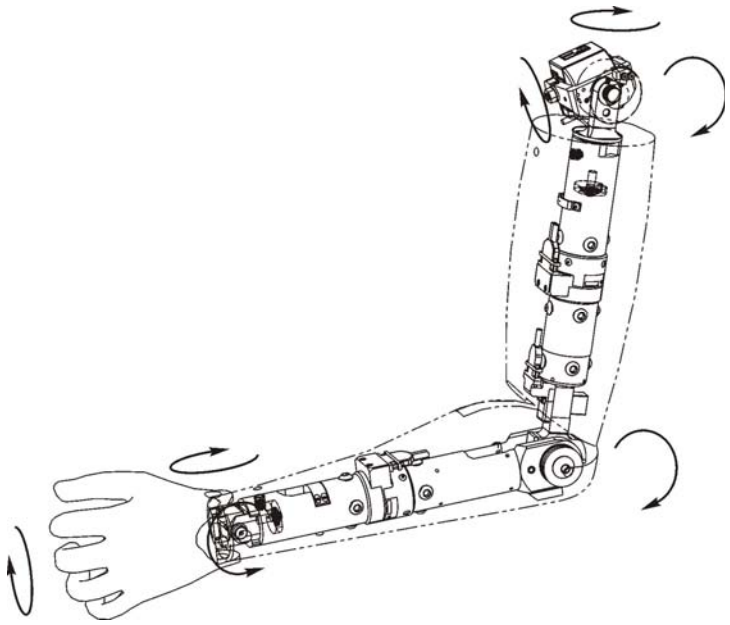


Figure 1.45 — Arm joint rotation

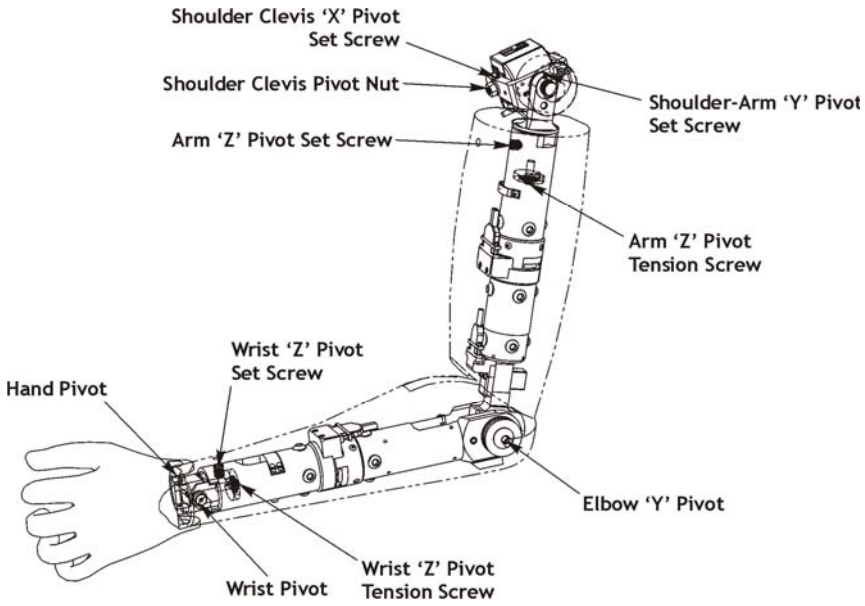

Shoulder Clevis 'X' Pivot Set Screw
Shoulder Clevis Pivot Nut
Arm 'Z' Pivot Set Screw
Shoulder-Arm 'Y' Pivot Set Screw
Arm 'Z' Pivot Tension Screw
Wrist 'Z' Pivot Set Screw
Hand Pivot
Elbow 'Y' Pivot
Wrist 'Z' Pivot Tension Screw
Wrist Pivot

Figure 1.46 — Arm joint tension points

Figure 1.45 shows the feasible rotations at each joint.

Perform the following procedures while the arm is attached to the dummy.

1.4.4.2 Adjusting the shoulder x-axis pivot

Note the following:

- The shoulder clevis pivots about the x-axis on the shoulder pivot shaft (Figure 1.16, Item 2).

- The full arm assembly should be able to support itself in the horizontal position, parallel to the floor and perpendicular to the dummy's mid-plane.

- A light force (1 to 2 G) applied to the hand should move the arm assembly to the at rest position (against the upper torso).

Adjust the shoulder assembly movement by tightening the M6 hex locking nut (Figure 1.16, Item 5) until the arm almost stays fixed when raised to the side horizontally (parallel to floor, perpendicular to torso side). Make the final 1-to-2-G-setting by means of the two SSNT M4 x 0,7 x 4 mm (Figure 1.16, Item 6).

1.4.4.3 Adjusting the arm z-axis pivot rotation

Ensure that the upper arm z-axis pivot is properly assembled prior to undertaking the adjustment procedure. Note that the spring washer (Figure 1.38, Item 5) in the z-axis pivot joint can cause some variability from assembly to assembly.

Extend the complete arm laterally until it is parallel to the floor. Tighten the shoulder-arm joint until the arm is locked in this position. Bend the arm at the elbow so that the lower arm is perpendicular to the upper but still parallel to the floor. If the z-axis pivot is properly adjusted the lower arm should remain parallel to the floor but move easily when a downward force of 1-to-2-G-setting is applied, and if it does not, the 'Z'-pivot must be adjusted using the friction adjustment screw (Figure 1.37, Item 9).

1.4.4.4 Adjusting the shoulder-arm y-axis pivot rotation

Fully extend the arm from the dummy's upper torso, toward the front of the torso, so that the complete arm is straight and parallel to the floor. Note the following:

- The assembly should be approximately parallel to the dummy's midsagittal plane.

- If properly adjusted, the arm will maintain this position without support and will move freely if a downward force of 1 G is applied.

Tighten the bumper on the arm pivot shaft to ensure proper engagement of the spring plunger mechanism (see Figure 1.37, Item 6). Loosen the two set screws that lock the bumper in position (see Figure 1.37, Item 5). Loosen the arm pivot set screw located at the top of the arm 'Z'-pivot. Rotate the bumper in a clockwise direction until the arm is almost able to support its own mass without falling. Adjust the set screw M3 (Figure 1.37, Item 3) until the arm will not drop when moved to the horizontal but will fall with only a slight touch of the hand.

1.4.4.5 Adjusting the elbow y-axis pivot rotation

Position the upper arm perpendicular to the floor and parallel to the upper torso. Position the lower arm assembly so that it is parallel to the floor and perpendicular to the upper arm. Tighten the elbow pivot screw (see Figure 1.47) so that the lower arm remains parallel to the floor until a downward force of about 1 to 2 G is applied.

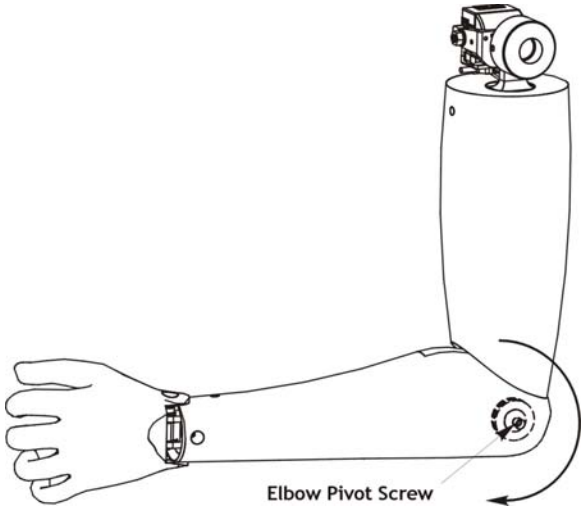


Figure 1.47 — Elbow adjustment

If tightening the elbow pivot screw does not provide enough friction to maintain the 1-2 G adjustment, inspect the joint to ensure that it is properly assembled. Note that the locking screw (see Figure 1.48) must be installed so that it secures the elbow pivot shaft assembly to the elbow assembly and the locking hole in the elbow pivot shaft assembly must be aligned with the locking screw.

Inspect the three washers used with the elbow pivot screw. The washers must be installed in the order shown in Figure 1.48 and the friction washer must have the friction material toward the elbow clevis assembly. Check the compression washer (neoprene material) for deformation or other damage and replace as necessary.

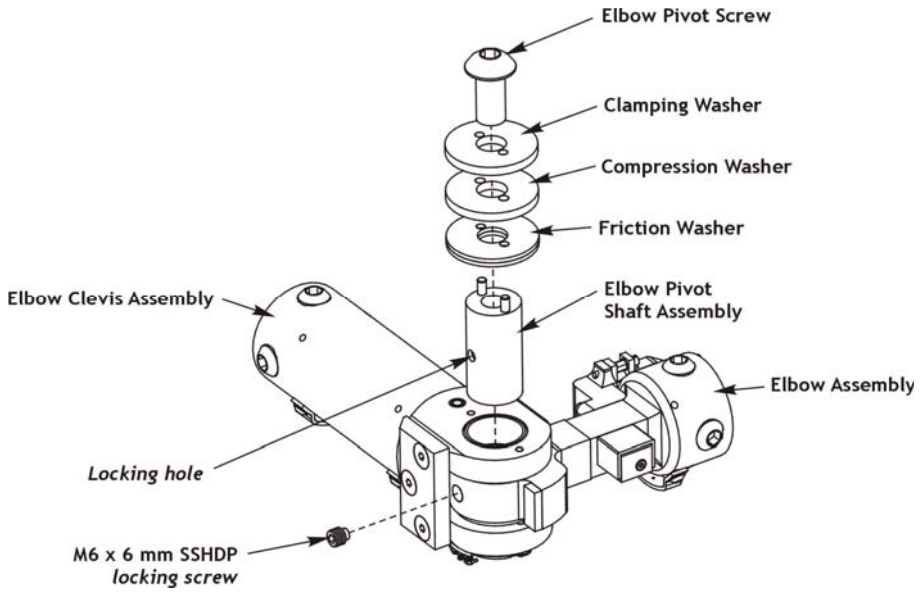


Figure 1.48 — Elbow friction adjustment

1.4.4.6 Adjusting the wrist and hand pivot rotations

Note the following:

- The wrist adjustments are not easily done due to the lack of mass of the components.

- This joint is adjusted to approximate a 1-to-2-G-setting.

Rotate the hand and tighten the modified SHSS M6 x 25 mm until there is an appropriate friction in the Wrist-Hand joint.

1.4.5 Changing full arm from left to right side impact

To convert the instrumented arm from left-side impact to right-side impact, or vice versa, several parts have to be exchanged. Replace the 'Z'-pivot (Figure 1.49, Item 1), hand (Figure 1.49, Item 4) and upper arm flesh

(not shown) with their corresponding components. For example, replace the left hand with the right hand and so on.

Move the cable clamp (Figure 1.49, Item 2) on the elbow load cell, the potentiometer assembly (Figure 1.49, Item 3), the BHCS M10 at the elbow joint (Figure 1.49, Item 5) with its associated washers (Figure 1.49, Items 6, 7, 8), and the lower arm assembly cable clamps (Figure 49, Item 2). Attach the potentiometer on the inside surface of the arm, closest to the torso. Position Figure 1.49, Items 5, 6, 7, and 8 on the outboard side, away from the torso.

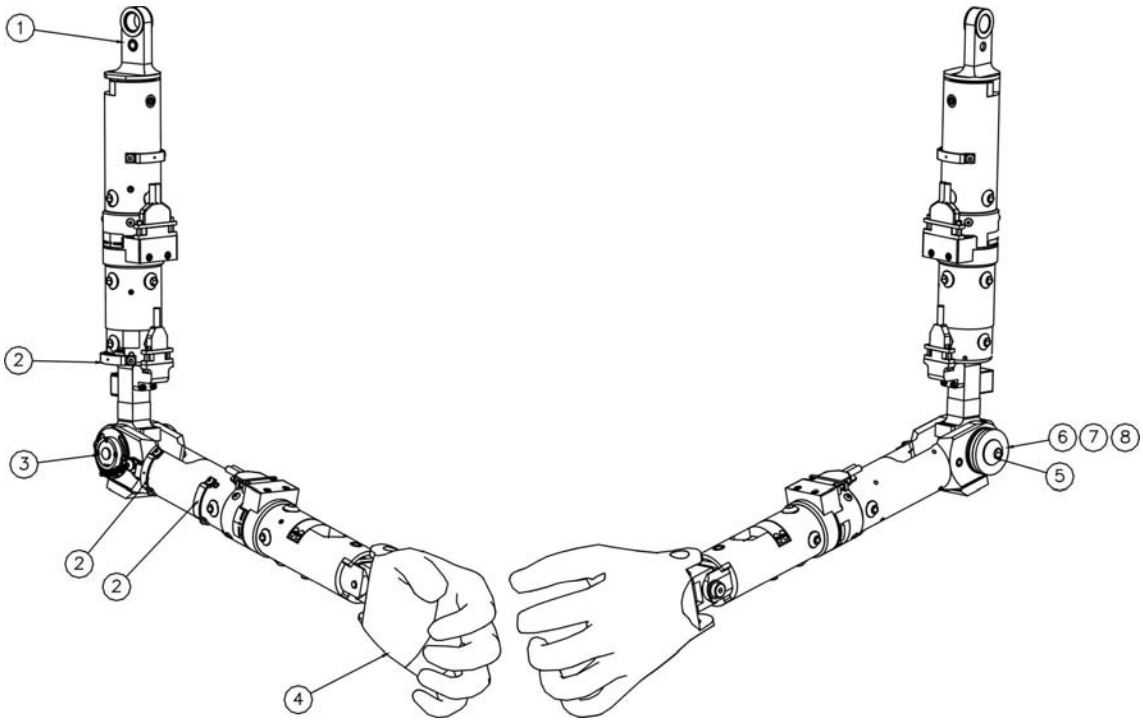


Figure 1.49 — Change-over components

1.5 Half arm

1.5.1 Parts list for half arm

The half arm is moulded as one piece which consists of a plastic bone, vinyl skin and urethane foam. The bone has a spring plunger for locating the arm position. The locknut is used to adjust the 1-to-2-G-settings. The part number for the half arm is shown in Table 1.12.

Table 1.12 — Parts list for WorldSID

Item number	Description	Quantity	Part number
1	Half arm assembly	2	W50-62000

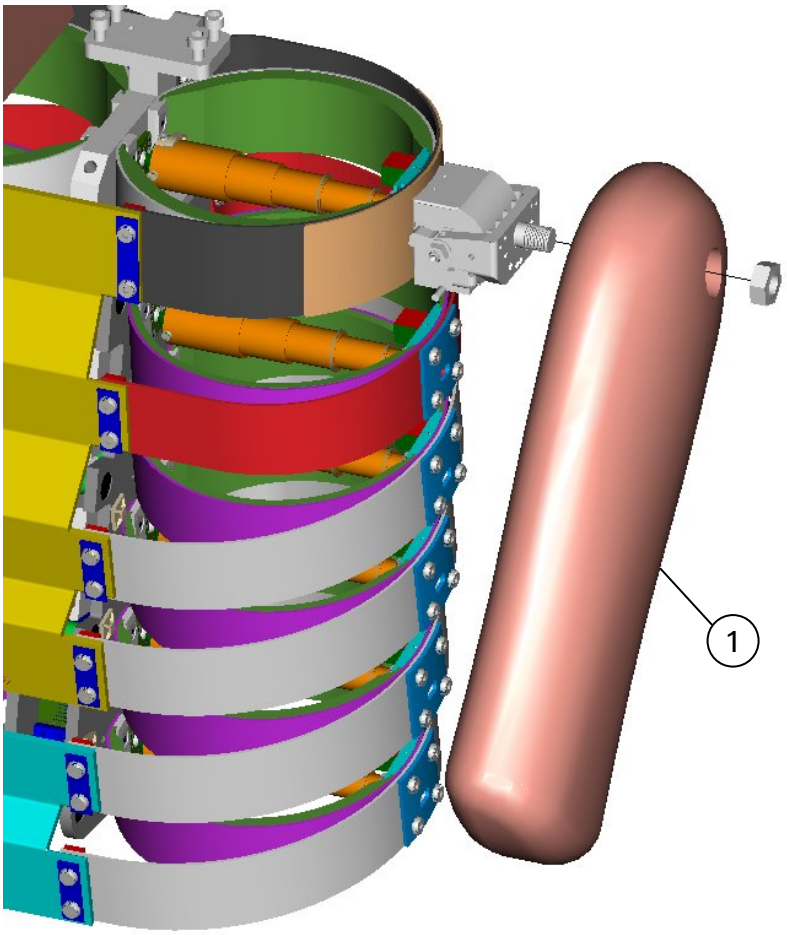


Figure 1.50 — Arm assembly

1.5.2 Disassembling

Remove the half arm from the shoulder by removing the locknut with a socket wrench.

1.5.3 Assembling

Attach the half arm to the shoulder using the locknut and a socket wrench, adjusting the joint to a 1-to-2-G-setting.

1.6 Pelvis

1.6.1 Parts list for pelvis

Table 1.13 lists the parts required for assembling the WorldSID pelvis. Note that part numbers refer to those on drawing W50-40000 and in Figure 1.51, and that Figures 1.52 through Figure 1.56 illustrate different views of the pelvis components.

Table 1.13 — Parts list for WorldSID pelvis

Item number	Description	Qty	Part number
1	Pelvis flesh	1	W50-42019
2	Interposer mass replacement	1	W50-75001
3	G5 module mass replacement	1	W50-74307
4	Pelvis docking station	1	W50-41042
5	Moulded pubic buffer	2	W50-42510
6	Pubic load cell structural replacement	1	W50-71052
7	Connector housing mass replacement	1	W50-75002
8	Left sacroiliac load cell interface	1	W50-42016
9	Left pelvis bone	1	W50-42010
10	Lumbar bushing	6	W50-41019
11	Lumbar lower clamping plate	2	W50-41021
12	Lumbar upper clamping plate	1	W50-41022
13	Rubber lumbar spine	1	W50-41018
14	SHCS M8 x 18	4	5000209
15	BHCS M5 x 0,8 x 25	4	5000466
16	FHCS M6 x 1 x 16	4	5000090
17	Lower lumbar mounting bracket weldment	1	W50-41030
18	Dual-axis tilt sensor	1	See dummy manufacturer information
19	Pelvis instrumentation cover plate	1	W50-42031
20	Linear triaxial accelerometer	1	Endevco 7268C-2000M1
21	Pelvis instrumentation bracket	1	W50-42030

Item number	Description	Qty	Part number
22	Right sacroiliac load cell interface	1	W50-42017
23	DAS cover	1	W50-41041
24	Sacroiliac load cell structural replacement	1	W50-71975
25	Lumbar spine load cell structural replacement	1	W50-71122
26	Sacroiliac load cell backing plate	2	W50-42002
27	Right pelvis bone	1	W50-42011
28	Lumbar mounting wedge	1	W50-41026
29	Hip joint socket	2	W50-42005
30	Hip joint inner ring	2	W50-42007
31	Hip socket retainer	2	W50-42008
32	Trochanter assembly, right	1	W50-51022
Not numbered	Trochanter assembly, left	1	W50-51023
33	FHCS M6 x 1 x 20	6	5000036
34	FHCS M6 x 30	8	5000265
35	BHCS M6 x 1 x 16	2	5000072
36	FHCS M3 x 0,5 x 10	4	5000203
37	SHCS M4 x 0,7 x 8	1	5000024
38	SHCS M4 x 0,7 x 14	3	5000549
39	Cheese screw M3 x 6	4	5000222
40	Flat washer M8 (8,9 ID x 18,8 OD x 2,3 thick)	2	5000123
41	SHCS M2 x 0,4 x 10	4	5000215
42	SHCS M3 x 0,5 x 8	11	5000388
43	Flat washer M4 (4,3 ID x 9,0 OD x 0,7 thick)	6	5000155
44	BHCS M4 x 0,7 x 16	6	5000153
45	SHCS M6 x 1 x 10	16	5000457
46	Hex head screw M8 x 10	2	5000569
47	BHCS M6 x 1 x 20	6	5000438
48	Cheese screw M2 x 16	1	5000254
49	MSSFP M4 x 6	6	5000464
Not shown	Dual axis tilt sensor mass replacement	1	W50-10011

Item number	Description	Qty	Part number
Not shown	Linear triaxial accelerometer mass replacement	1	W50-61063
Not shown	Pubic symphisis load cell	1	W50-71051
Not shown	Lumbar spine load cell assembly	1	W50-71120
Not shown	Sacro-iliac load cell assembly	1	W50-71130

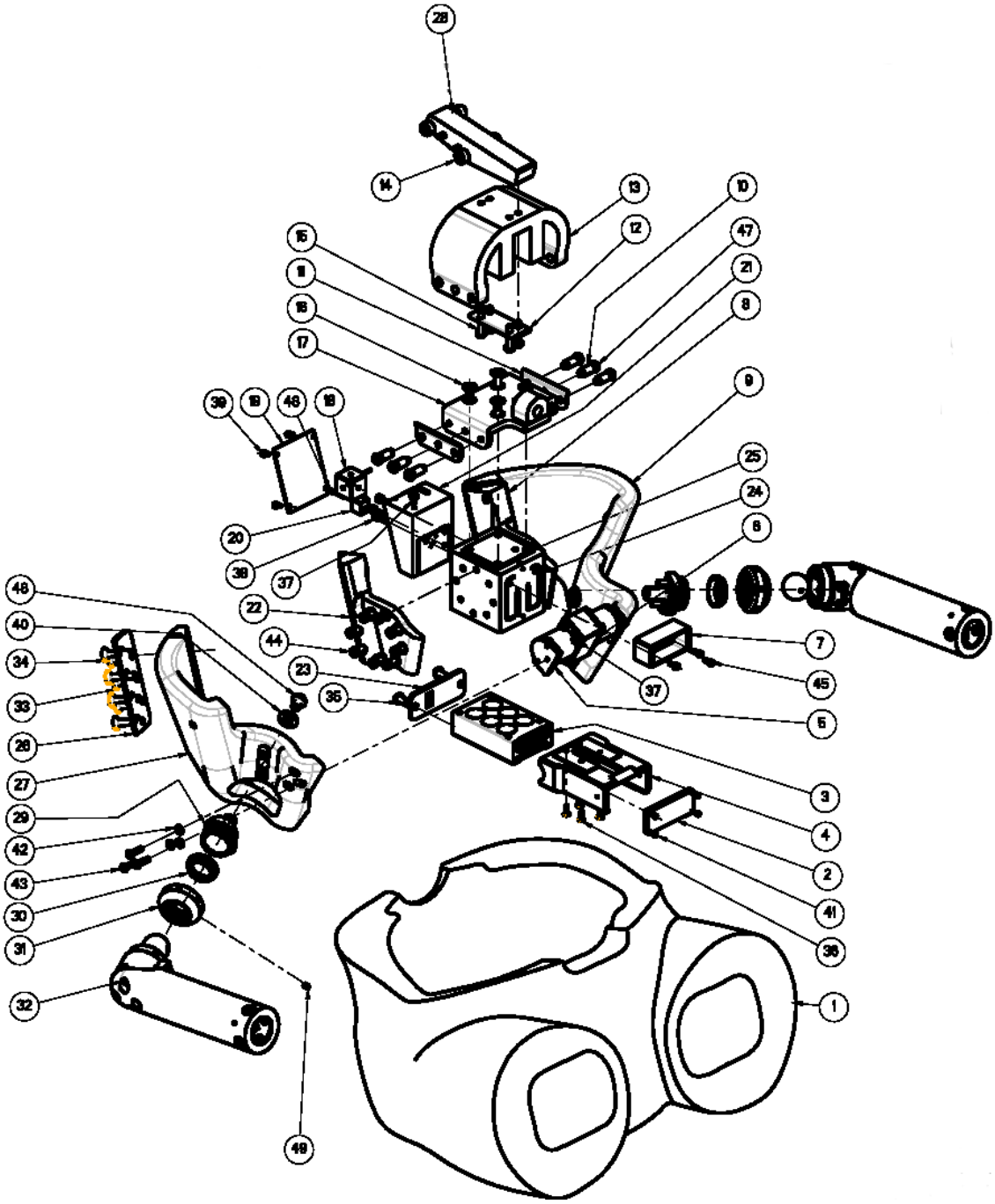


Figure 1.51 — WorldSID pelvis components

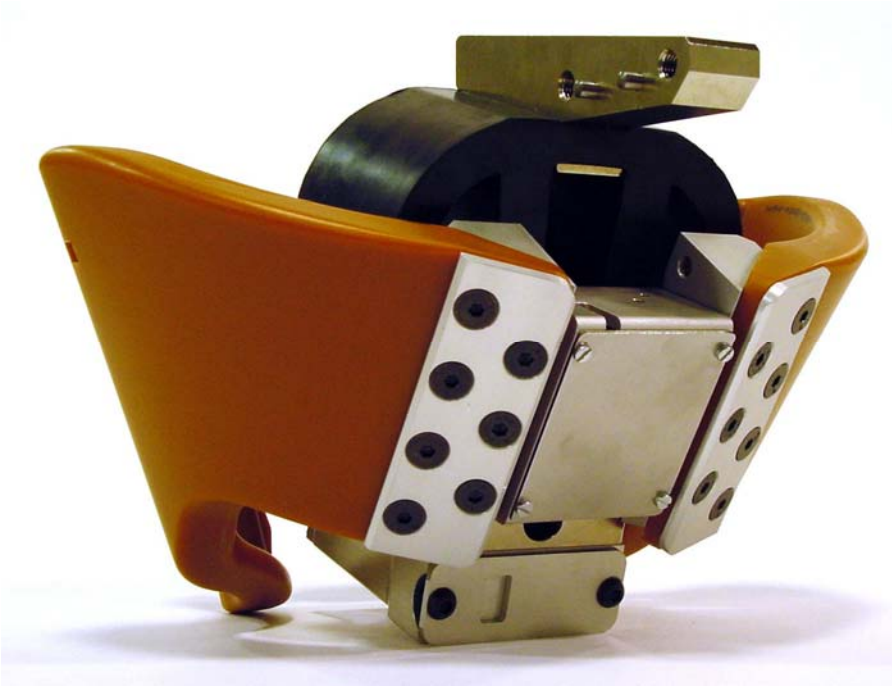


Figure 1.52 — Rear view of pelvis assembly

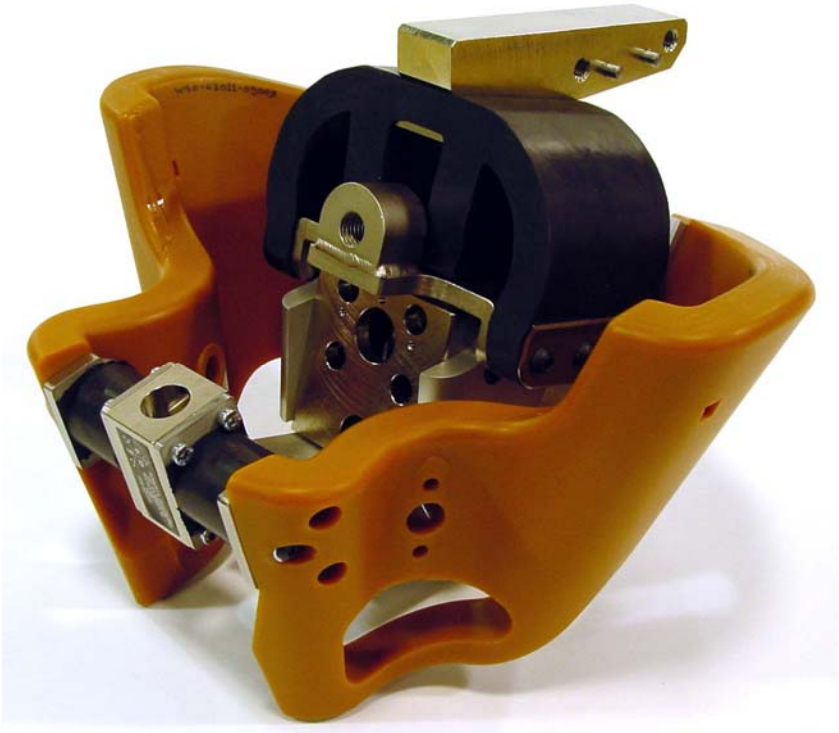


Figure 1.53 — Front view of pelvis assembly

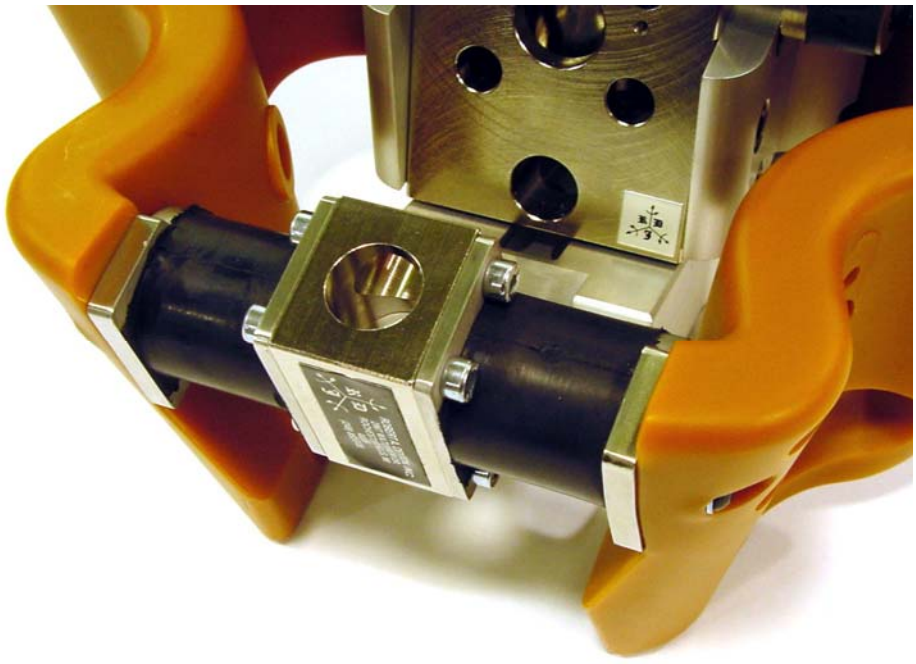


Figure 1.54 — Close-up view of pubic assembly

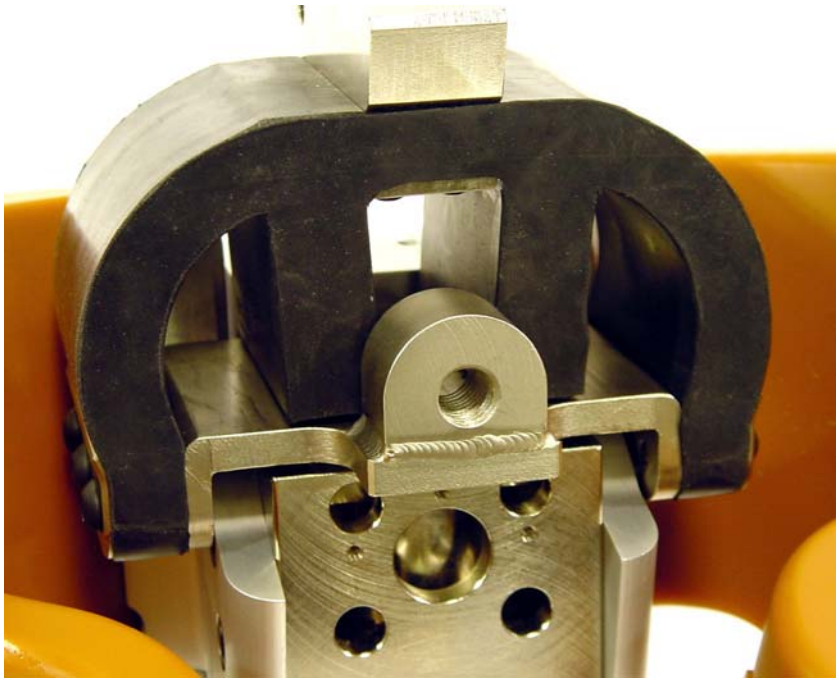


Figure 1.55 — Close-up view of lumbar assembly

1.6.2 Disassembling

As shown in Figure 1.56, remove the spine box from the pelvis assembly by removing four SHCS M8 x 18 (Figure 1.56,Item 14) that connect it to the lumbar mounting wedge (Figure 1.56,Item 28).

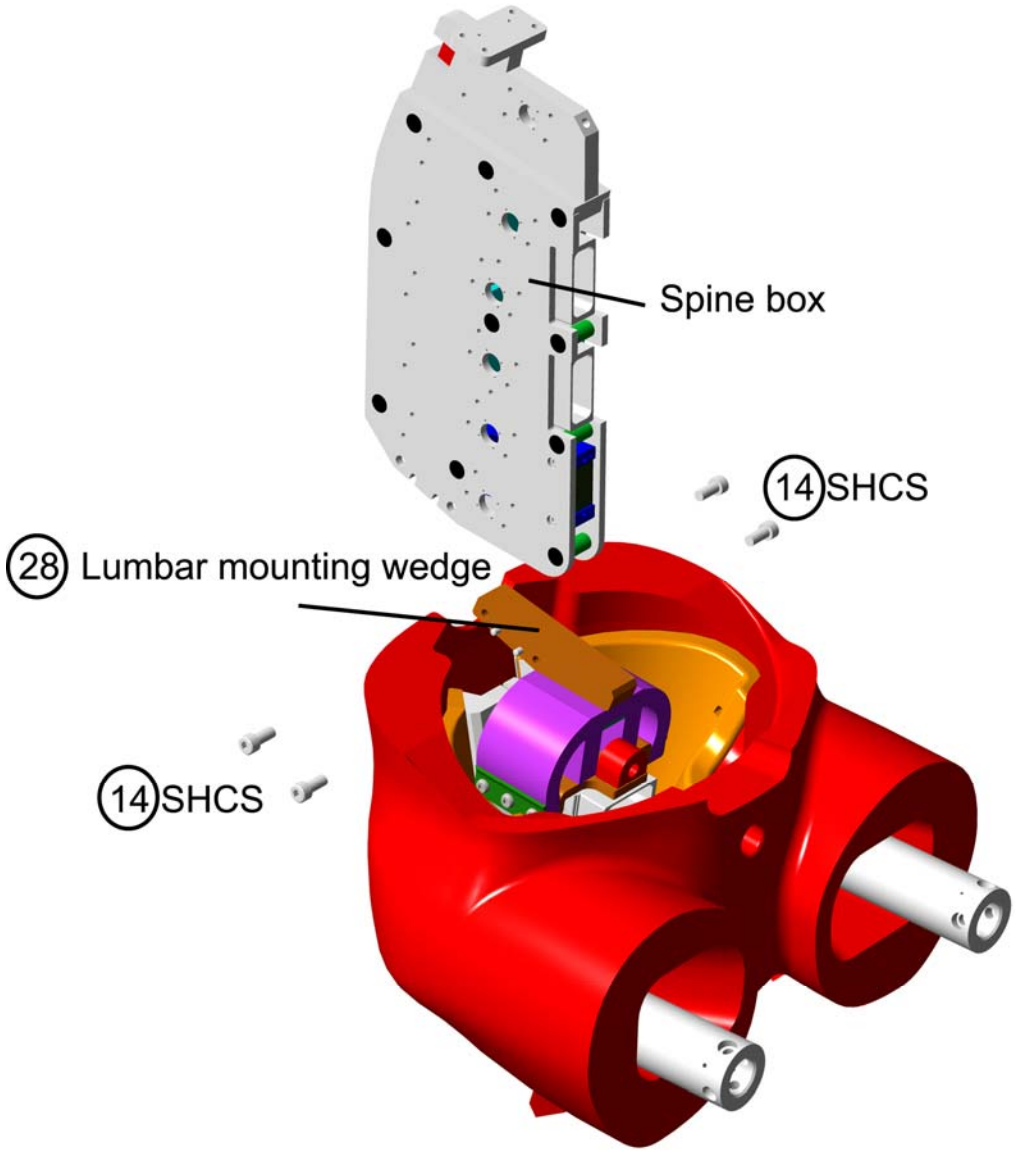


Figure 1.56 — Removing spine box from the pelvis

Detach the femur assemblies by removing the hex head screws M8 x 10 (Figure 1.57, Item 46) that attach each to the pelvis assembly (see Figure 1.57). They are accessible from the interior of the pelvis bone and can be removed with a box end wrench.

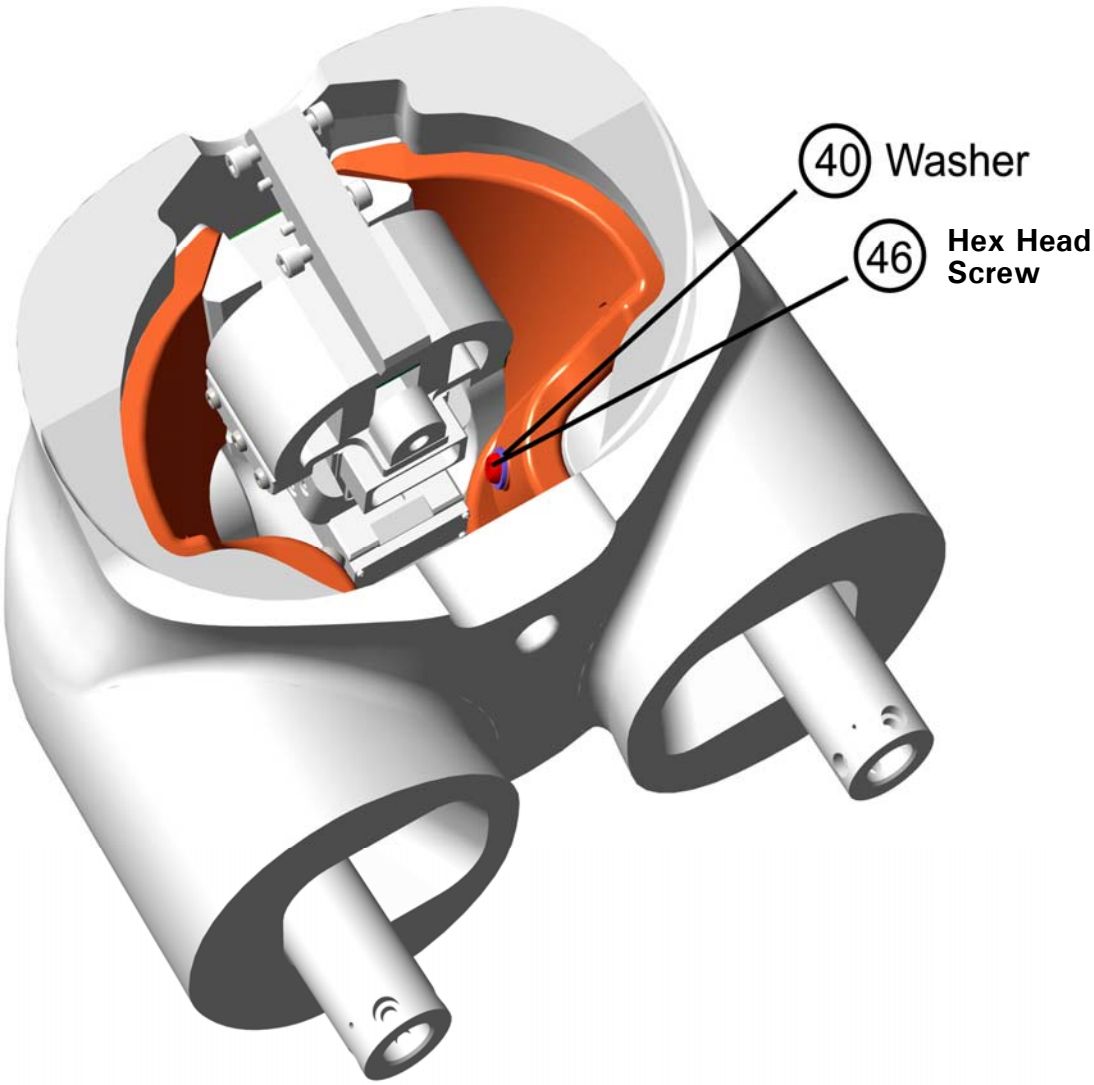


Figure 1.57 — Detaching the femur assemblies

Remove the pelvis flesh (Figure 1.51, Item 1) by peeling it away from the pelvis (see Figure 1.58).

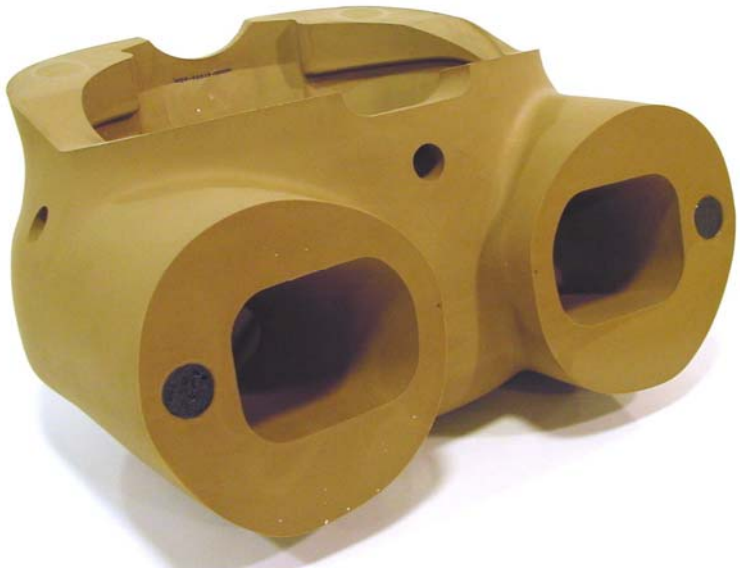


Figure 1.58 — Pelvis flesh

As shown in Figure 1.59, remove the sacroiliac load cell backing plates (Figure 1.51, Item 26) by removing the four FHCS M6 x 30 (Figure 1.51, Item 34) and three FHCS M6 x 20 (Figure 1.51, Item 33) that secure them. Separate the two pelvis bones (Figure 1.51, Items 9 and 27), connected by the pubic buffers (Figure 1.51, Item 5) and pubic load cell (Figure 1.51, Item 6) from the lumbar instrumentation assembly.

Figure 1.59 — Removing sacroiliac backing plates to separate the pelvic bone-pubis assembly

Detach the moulded pubic buffers (Figure 1.51, Item 5) from the moulded pelvis by removing the three M4 x 16 (Figure 1.51, Item 44) and M4 flat washers (Figure 1.51, Item 43) that hold each in place (see Figure 1.60).

Figure 1.60 — Separating moulded pelvis bone from pubis assembly

Detach the pubic buffers from the pubic load cell structural replacement (Figure 1.51, Item 6) by removing four SHCS M4 x 8 (Figure 1.51, Item 37) from each side (see Figure 1.61.)

Figure 1.61 — Separating pubic buffers from pubic load cell structural replacement

As shown in Figure 1.62, detach the lumbar spine (Figure 1.51, Item 13), remove the six BHCS M6 x 20 (Figure 1.51, Item 47) and six lumbar bushings (Figure 1.51, Item 10) that attach it to the lower lumbar mounting bracket weldment (Figure 1.51, Item 17). Remove the two lower lumbar clamping plates (Figure 1.51, Item 11).

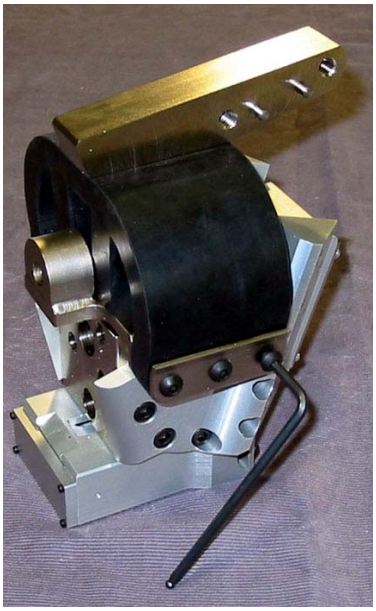


Figure 1.62 — Detaching the lumbar spine

Remove the upper lumbar clamping plate (Figure 1.51, Item 12) from the lumbar spine by removing the four BHCS M5 x 25 (Figure 1.51, Item 15) that secure it (see Figure 1.63). Remove the lumbar mounting wedge (Figure 1.51, Item 28).

Figure 1.63 — Separating the upper lumbar clamping plate and lumbar mounting wedge from the lumbar spine

As shown in Figure 1.64, remove the lower lumbar mounting bracket weldment (Figure 1.51, Item 17) from the lumbar load cell structural replacement (Figure 1.51, Item 25) by removing four FHCS M6 x 16 (Figure 1.51, Item 16).

Figure 1.64 — Removing the lower lumbar mounting bracket weldment

Detach the left and right sacroiliac load cell interfaces (Figure 1.51, Items 22 and Item 8) by removing the eight SHCS M6 x 10 (Figure 1.51, Item 45) that hold each in place (see Figure 1.65).

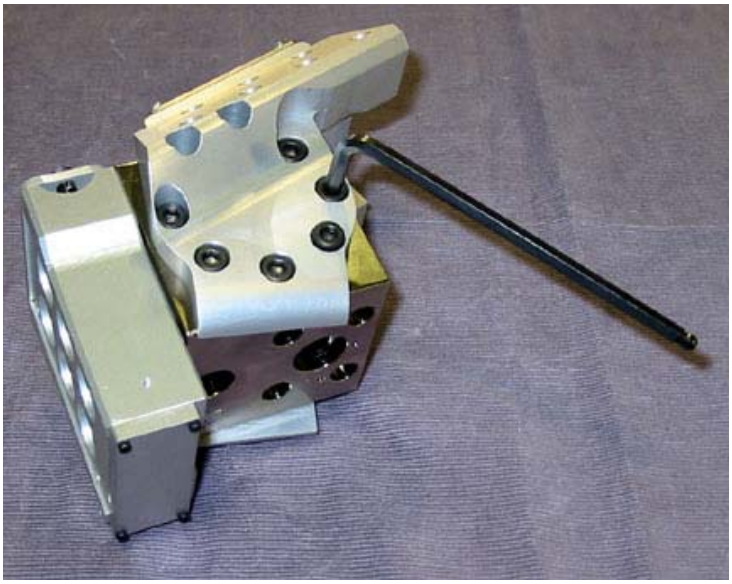


Figure 1.65 — Removing the sacroiliac load cell interface

As shown in Figure 1.66, remove the pelvis instrumentation cover plate (Figure 1.51, Item 19) by removing four cheese screws M3 x 6 (Figure 1.51, Item 39).

Figure 1.66 — Removing pelvis instrumentation cover plate

Detach the pelvis instrumentation bracket (Figure 1.51, Item 21) from the sacroiliac load cell structural replacement (Figure 1.51, Item 24) by removing three SHCS M4 x 14 (Figure 1.51, Item 38) accessed from the back (see Figure 1.67).

Figure 1.67 — Removing the pelvis instrumentation bracket

Remove the connector mass replacement (Figure 1.51, Item 7) from the front of the sacroiliac load cell structural replacement by removing three SHCS M3 x 8 (Figure 1.51, Item 42). As shown in Figure 1.68, detach the DAS cover (Figure 1.51, Item 23) by removing two BHCS M6 x 16 (Figure 1.51, Item 35). Slide out the G5 module mass replacement (Figure 1.51, Item 3).

Figure 1.68 — Removing the DAS cover

Figure 1.69 illustrates detachment of the pelvis docking station (Figure 1.51, Item 4) by removing four M3 x 10 FHCS (Figure 1.51, Item 36).

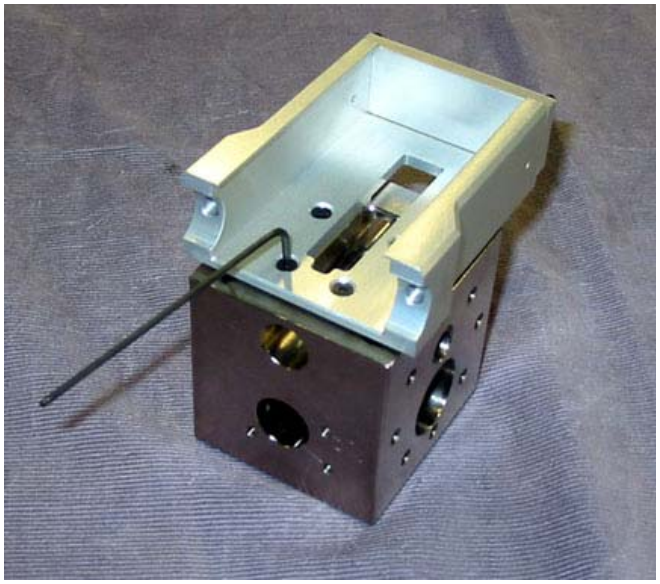


Figure 1.69 — Removing the docking station

As shown in Figure 1.70, detach the interposer mass replacement (Figure 1.51, Item 2) by removing four SHCS M2 x 10 (Figure 1.51, Item 41).

Figure 1.70 — Removing interposer mass replacement

As shown in Figure 1.71, separate the structural replacements for the sacroiliac and lumbar spine load cells by removing the four SHCS M6 x 30 (Figure 1.51, Item 34) accessed from the bottom.

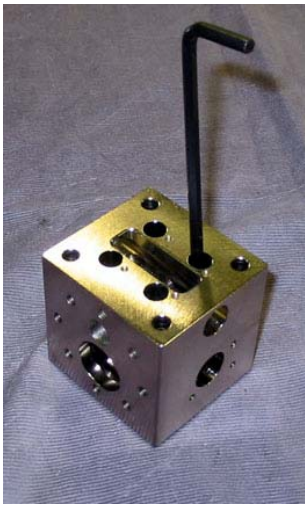


Figure 1.71 — Separating the sacroiliac and lumbar spine load cell structural replacements

1.6.3 Assembling the pelvis

In general the procedure for assembling the pelvis is substantially the opposite of the procedure for disassembling it. The following descriptions are provided to assist the user to more efficiently assemble the WorldSID pelvis.

Join the lumbar spine load cell or its mass replacement (Figure 1.51, Item 25) to the sacroiliac load cell or its mass replacement (Figure 1.51, Item 24) using four SHCS M6 x 30 (Figure 1.51, Item 34). The connectors are at the bottom of the load cells and face the front of the dummy. Install the interposer or its mass replacement (Figure 1.51, Item 2) to the pelvis docking station (Figure 1.51, Item 4) with four SHCS M2 x 10 (Figure 1.51, Item 41). Secure the docking station to the bottom of the sacroiliac load cell with four FHCS M3 x 10 (Figure 1.51, Item 36). Slide the DAS unit (Figure 1.51, Item 3) into the docking station and connect it to the interposer. Install the DAS cover (Figure 1.51, Item 23) with two BHCS M6 x 16 (Figure 1.51, Item 35). Secure the connector or its mass replacement (Figure 1.51, Item 7) to the front of the sacroiliac load cell with three SHCS M3 x 8 (Figure 1.51, Item 42).

Mount the linear triaxial accelerometer (Figure 1.51, Item 20) to the pelvis instrumentation bracket (Figure 1.51, Item 21) using a cheese screw M2 x 16 (Figure 1.51, Item 48) accessed from the back. Attach the dual-axis tilt sensor (Figure 1.51, Item 18) with an SHCS M4 x 8 (Figure 1.51, Item 37) accessed from the top. Secure the pelvis instrumentation bracket (Figure 1.51, Item 21) to the sacroiliac load cell or its structural replacement (Figure 1.51, Item 24) with three SHCS M4 x 14 (Figure 1.51, Item 38). Mount the pelvis instrumentation cover plate (Figure 1.51, Item 19) with four cheese screws M3 x 6 (Figure 1.51, Item 39). Ensure that the wires for the accelerometer and tilt sensor exit the slot in the top of the instrumentation bracket. Route the accelerometer wire over the non-struck sacroiliac load cell interface towards the front of the dummy.

Attach the left and right sacroiliac load cell interfaces (Figure 1.51, Item 22 and Item 8) with eight SHCS M6 x 10 (Figure 1.51, Item 45) that hold each in place. Connect the lumbar mounting bracket weldment (Figure 1.51, Item 17) to the lumbar load cell or its structural replacement (Figure 1.51, Item 25) with four FHCS M6 x 16 (Figure 1.51, Item 16). Place the lumbar mounting wedge (Figure 1.51, Item 28) on top of the lumbar spine, lining up the threaded holes on the bottom with those in the lumbar spine. Place the upper lumbar clamping plate (Figure 1.51, Item 12) over the holes in the lumbar spine and secure it with four BHCS M5 x 25 (Figure 1.51, Item 15).

Place the assembled lumbar spine (Figure 1.51, Item 13) over the lumbar mounting bracket. Position a lower lumbar clamping plate (Figure 1.51, Item 11) over the holes in the side of the lumbar spine so the curve of the plate matches the curve in the rubber, with the radius edge facing down. Secure the lumbar spine and clamping plate to the mounting bracket with three BHCS M6 x 20 (Figure 1.51, Item 47) and three lumbar bushings (Figure 1.51, Item 10). Repeat the procedure for the other side of the lumbar spine.

Connect the pubic buffers to the pubic load cell or its structural replacement (Figure 1.51, Item 6) with four SHCS M4 x 8 (Figure 1.51, Item 37) on each side. Attach the moulded pubic buffers (Figure 1.51, Item 5) to the moulded pelvis with three M4 x 16 (Figure 1.51, Item 44) and M4 flat washers (Figure 1.51, Item 43) on each side. Position the central assembled portion of the pelvis within the moulded pelvis/pubic assembly. Attach each sacroiliac load cell backing plates (Figure 1.51, Item 26) with four FHCS M6 x 30 (Figure 1.51, Item 34) and three FHCS M6 x 20 (Figure 1.51, Item 33). Use the shorter screws on the inboard holes.

If the pelvis DAS module is being used, plug in the connectors for the lumbar, pubic, and sacroiliac load cells and the pelvis triaxial accelerometer (see Figure 1.72). Make sure the connectors for the tilt sensor are free so they can be connected to the off-board readout later. If a pelvis DAS is not

used, route the wires toward the front along the non-struck side so they can be plugged into the lower G5 module on the spine box.

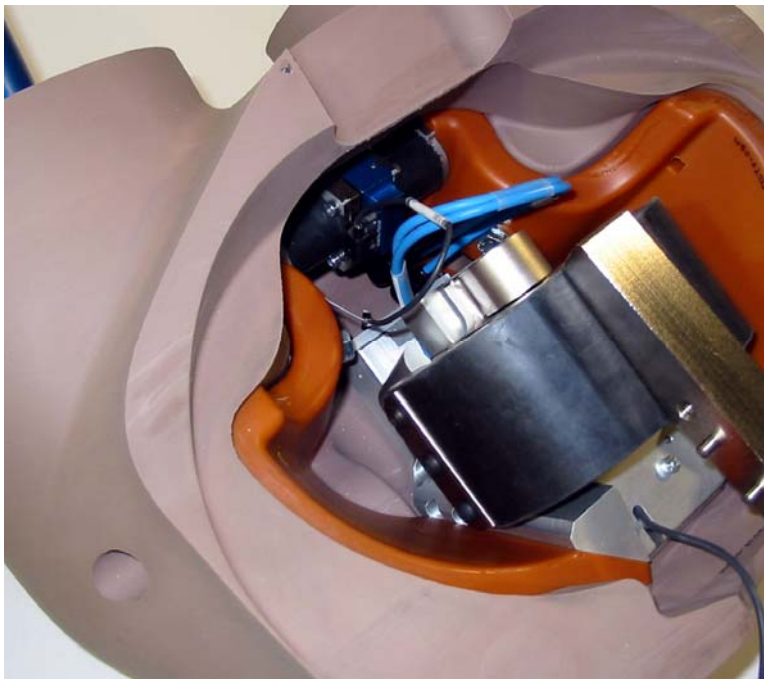


Figure 1.72 — Routing of wires for pelvis instrumentation

Place the pelvis into the pelvis flesh, placing the pubic assembly in first, then adjusting the flesh over the pelvic bones. Make sure the flesh is correctly positioned over the pelvis by checking that access holes in the pelvis flesh line up with screws in the pelvis.

When assembling the hip joint as shown in Figure 1.51, apply grease to the hip joint inner ring (Figure 1.51, Item 30) and the hip joint socket (Figure 1.51, Item 29) before tightening the hip socket retainer (Figure 1.51, item 31). Insert the hip joint assembly through the front access hole in the pelvis flesh. Secure from the inside of the pelvis with a M8 x 10 bolt (Figure 1.51, Item 46). Place the assembled spine box over the lumbar wedge (Figure 1.51, Item 28) and secure with four SHCS M8 x 18 (Figure 1.51, Item 14).

1.6.4 Instrumentation mounting

The pelvis instrumentation for the WorldSID includes pubic, sacroiliac, and lumbar spine load cells, and that a G5 module can be mounted to the bottom of the pelvis assembly. The pelvis instrumentation cavity can be equipped with a linear triaxial accelerometer and a dual-axis tilt sensor.

1.7 Full leg assembly

1.7.1 Parts list

1.7.1.1 General

The full leg assembly includes the femoral neck assembly, the upper leg assembly, the knee assembly, the lower leg assembly and the ankle-foot assembly.

1.7.1.2 Parts for femoral neck assembly

Table 1.14 lists the parts required for assembling the WorldSID femoral neck assembly, which is illustrated in Figure 1.73.

Table 1.14 — Parts list for femoral neck (W50-51034)

Item number	Description	Quantity	Part number
1	SSCP M4 x 0,7 x 6 mm	1	5000076
2	Femoral neck ball	1	W50-51038
3	LWSHCS M6 x 1,0 x 12 mm	4	5000072
4	Femoral neck base	1	W50-51035

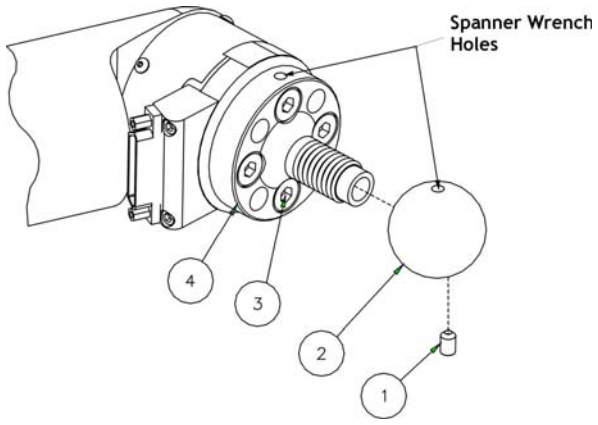


Figure 1.73 — Femoral neck

1.7.1.3 Parts list for upper leg assembly

Table 1.15 lists the parts required for assembling the WorldSID upper leg, which is illustrated in Figure 1.74.

Table 1.15 — Parts for upper leg

Item number	Description	Quantity	Part number
1	LWSHCS M6 x 1,0 x 12 mm	4	5000194
2	Femoral neck assembly	1	W50-51034
3	Femoral neck load cell (optional)	1	W50-71080
not shown	Femoral neck load cell structural replacement	1	W50-71965
4	DAS mass replacement assembly	1	W50-51053
5	Modified BHCS	12	W50-61042
6	Knee assembly, right	1	W50-52001
not shown	Knee assembly, left	1	W50-52019
7	Leg tube assembly	1	W50-51068
8	Leg load cell (optional)	1	W50-71010
not shown	Leg load cell structural replacement	1	W50-51060
9	Trochanter assembly, right	1	W50-51022
not shown	Trochanter assembly, left	1	W50-51023
10	BHCS M6 x 1,0 x 16 mm	4	5000072

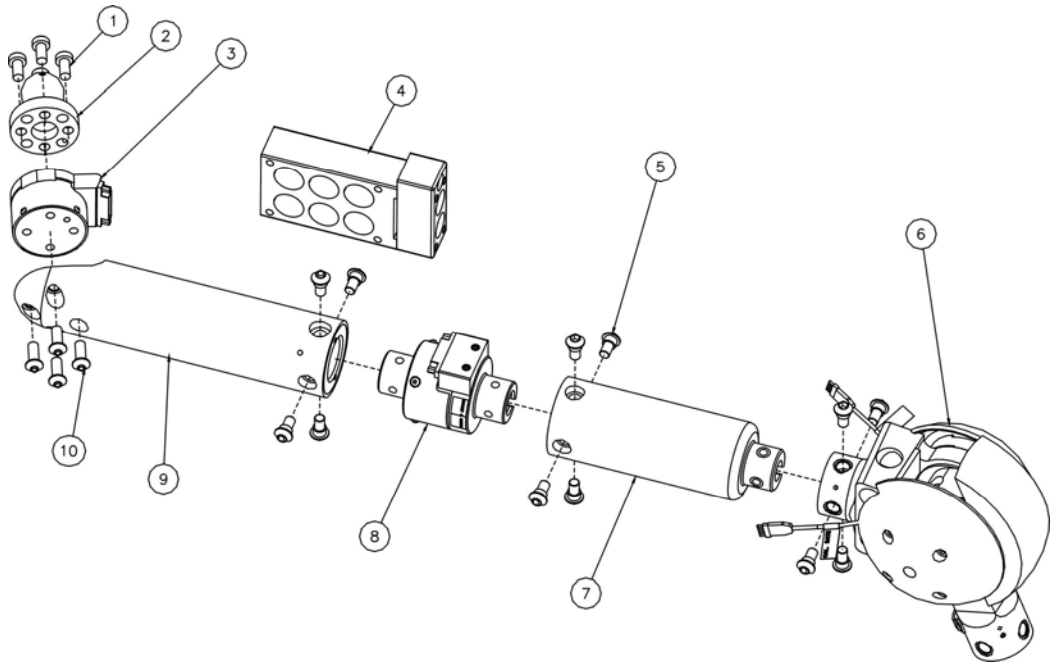


Figure 1.74 — Upper leg assembly

1.7.1.4 Parts list for knee assembly

Table 1.16 lists the parts required for assembling the WorldSID knee, which is illustrated in Figure 1.75.

Table 1.16 — Parts list for knee

Item number	Description	Quantity	Part number
1	SHCS M4 x 0,7 x 10 mm	16	5000151
2	Knee cover	2	W50-52004
3	Knee contact load cell structural replacement	2	W50-52015
Not shown	Knee contact load cell (optional)	2	W50-71020
4	Rotary potentiometer (optional)	1	W50-61027
5	BHCS M3 x 0,5 x 6 mm	2	5000171
6	BHCS M3 x 0,5 x 6 mm	2	5000171
7	Cable guide	1	W50-61030
8	Knee pivot shaft assembly	1	W50-52008
9	Knee clevis assembly, right	1	W50-52009
not shown	Knee clevis assembly, left	1	W50-52021

Item number	Description	Quantity	Part number
10	Friction washer	1	W50-52064
11	Compression washer (rubber)	1	W50-61016
12	Clamping washer (steel)	1	W50-61014
13	BHCS M10 x 1,5 x 20 mm	1	5000176
14	Knee pad mould assembly	1	W50-52010
15	BHCS M4 x 0,7 x 12 mm	6	5000005
16	Knee bone assembly	1	W50-52002
17	SSHDP M6 x 1,0 x 12 mm	1	5000185
Not shown	Rotary potentiometer mass replacement	1	W50-61123

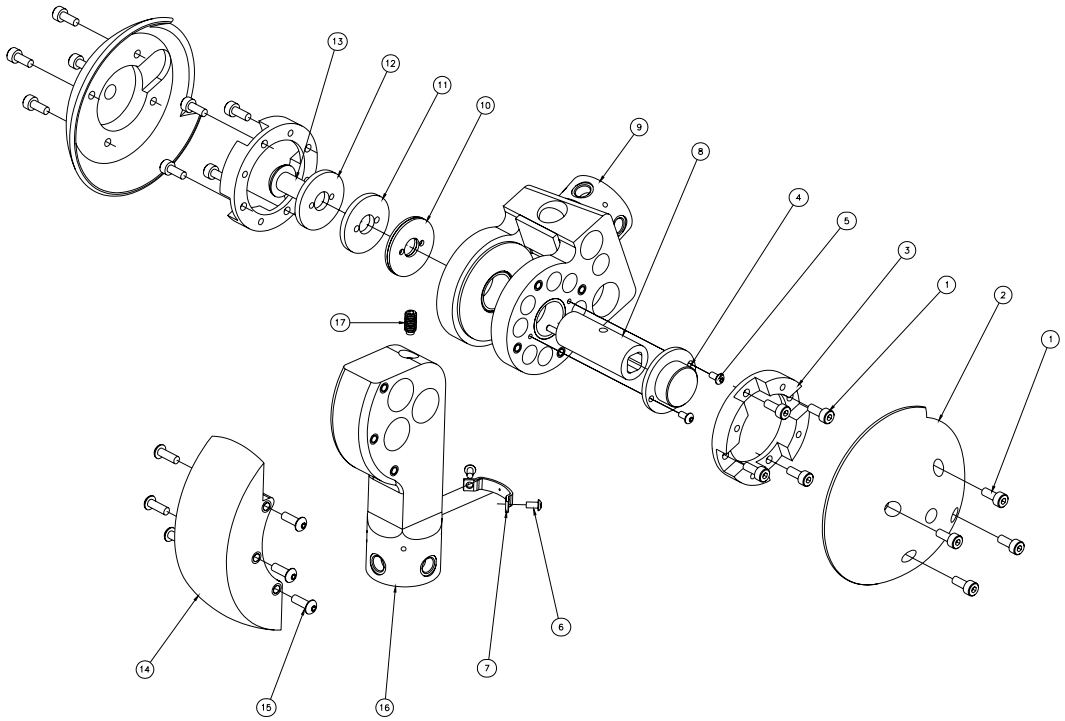


Figure 1.75 — Knee

1.7.1.5 Parts list for lower leg tube assembly

Table 1.17 lists the parts required for assembling the WorldSID lower leg tube, which is illustrated in Figure 1.76.

Table 1.17 — Parts list for lower leg tube

Item number	Description	Quantity	Part number
1	Leg load cell (optional)	2	W50-71010
not shown	Leg load cell structural replacement	2	W50-51060
2	Modified button head cap screw	8	W50-61042
3	Lower leg tube	1	W50-53001
4	SSCP M6 x 1,0 x 8 mm	3	5000622
5	z-axis radial limit screw	1	W50-54041
6	'Z'-pivot pin	1	W50-54009
7	z-axis anti-rattle washer	1	W50-54024
8	z-axis rotational washer	1	W50-54010
9	z-axis nut	1	W50-54023
10	BHCS M3 x 0,5 x 6 mm	4	5000171
11	Cable guide	2	W50-61030
12	Leg flesh orienting block	1	W50-54038
13	SHCS M6 x 1,0 x 12 mm	1	5000281

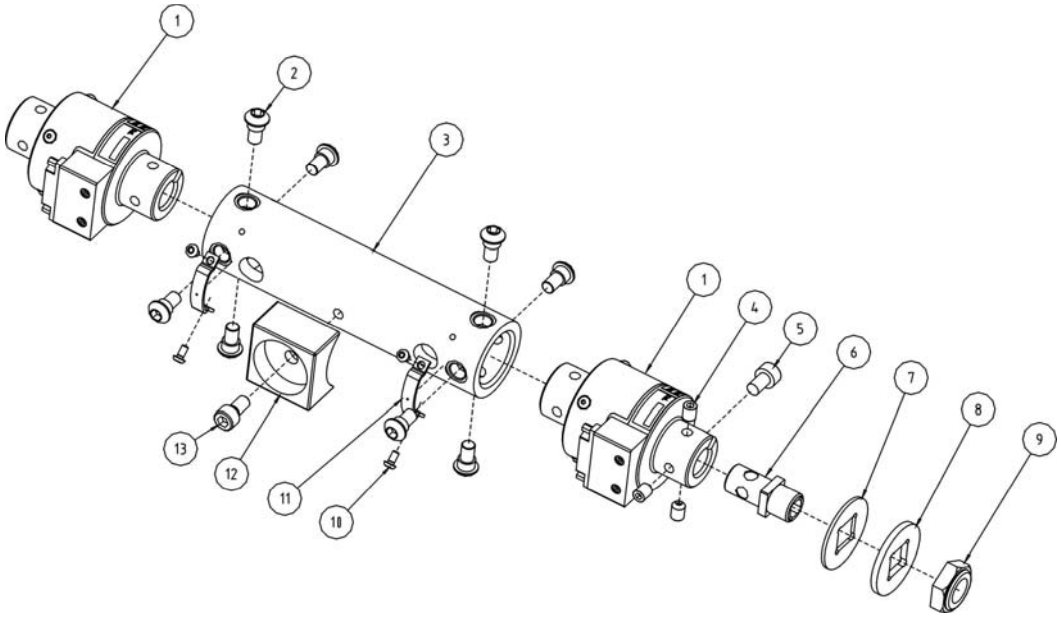


Figure 1.76 — Lower leg tube assembly

1.7.1.6 Parts list for ankle-foot

Table 1.18 lists the parts required for assembly of the WorldSID ankle-foot, which is illustrated in Figure 1.77.

Table 1.18 — Parts list for ankle-foot

Item	Description	Quantity	Part number
1	Leg load cell (optional)	1	W50-71010
Not shown	Leg load cell structural replacement	1	W50-51060
2	Ankle assembly	1	W50-54054
3 Not shown	Moulded foot assembly, right Moulded foot assembly, left	1	W50-55005 W50-55004
4	SHCS M5 x 0,8 x 16	4	5000020

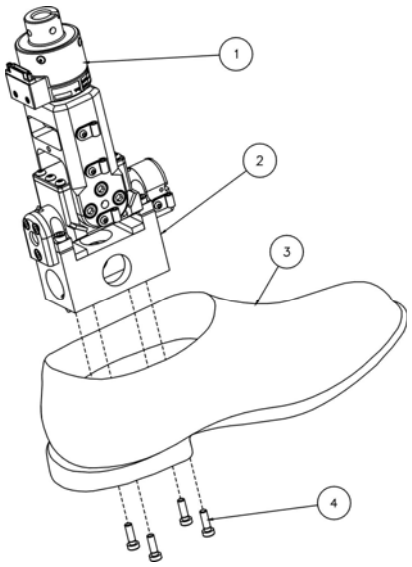


Figure 1.77 — Foot and ankle

1.7.1.7 Parts list for ankle

Table 1.19 lists the parts required for assembly of the WorldSID ankle, which is illustrated in Figure 1.78.

Table 1.19 — Parts list for ankle

Item number	Description	Quantity	Part number
1	SSNT M6 x 1,0 x 6,0	1	5000621
2	Clevis assembly	1	W50-54047
3	SHCS M6 x 1,0 x 12 mm	6	5000281
4	Y-axis potentiometer assembly (optional)	1	W50-54052
5, 14, 25	SSNT M3 x 0,5 x 3	4	5000190
6	Left flexion centre assembly	1	W50-54048
7	SSCP M3 x 0,5 x 4 mm	1	5000470
8	SHCS M5 x 0,8 x 16 mm	4	5000020
9	Retainer bracket	2	W50-54014
10	BHCS M4 x 0,7 x 10 mm	6	5000010
11	Ankle joint cover	1	W50-54015

Item number	Description	Quantity	Part number
12	Ankle joint assembly	1	W50-54045
13	Front bearing assembly	1	W50-54042
15	SHCS M5 x 0,8 x 12 mm	6	5000002
16	X-axis potentiometer (optional)	1	W50-54012
17	Cable clamp, 1/8"	4	5000191
18	BHCS M3 x 0,5 x 6 mm	4	5000171
19	X-version assembly	1	W50-54044
20	Rear bearing assembly	1	W50-54043
21	X-version resistive element	8	W50-54035
22	Resistive element (Dorsi. & Plantar.)	8	W50-54036
23	Right flexion centre assembly	1	W50-54049
24	z-axis potentiometer assembly (optional)	1	W50-54051
26	Stop pad	4	W50-54022
27	Compression pad	2	W50-54021
Not shown	Ankle potentiometer mass replacement	3	W50-54013

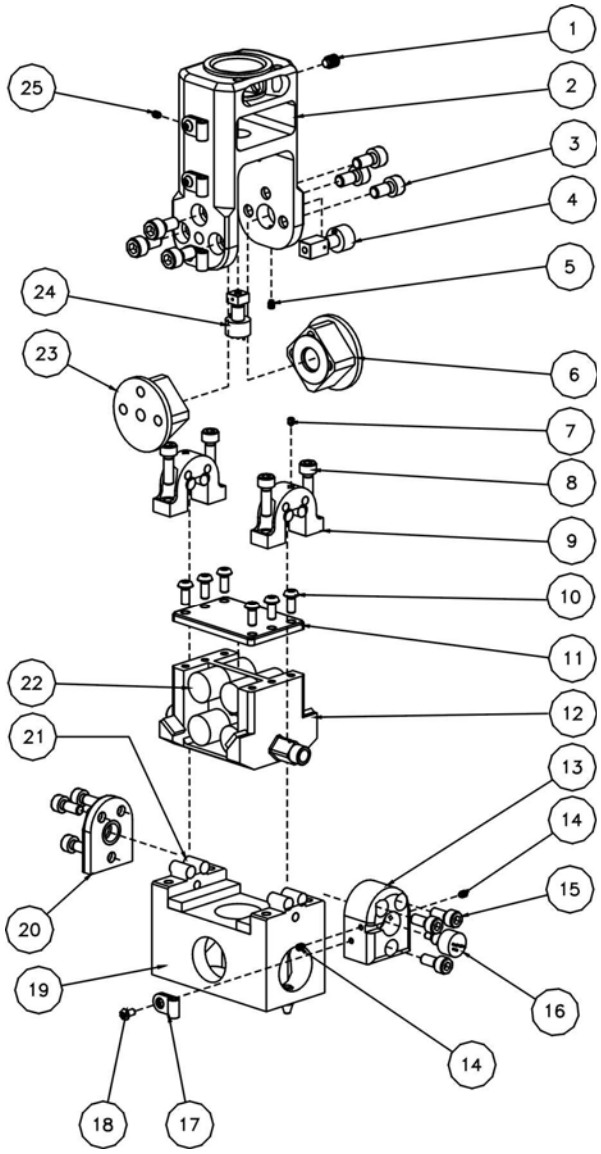


Figure 1.78 — Ankle assembly

1.7.2 Disassembling

1.7.2.1 Femoral neck

Disassemble the femoral neck by loosening the SSCP M4 x 0,7 x 6 mm (Figure 1.73, Item 1) that holds the femoral ball in place and unthread the ball (Figure 1.73, Item 2) from the femoral neck base (Figure 1.73, Item 4). Use a spanner wrench to turn the ball (modified 25 mm to 28 mm diameter;

W50-51001) and a spanner wrench 40 mm to 42 mm (W50-51002) to hold the femoral neck base (Figure 1.73, Item 4). Be careful not to damage the surface of the ball during disassembly and re-assembly.

Remove the four LWSHCS M6 x 1,0 x 12 mm (Figure 1.73, Item 3) that attach the assembly to the femoral neck load cell (Figure 1.74, Item 3). Note that these screws can be removed without removing the ball using a modified hex key wrench (W50-51003).

1.7.2.2 Upper leg

Disconnect all the cable connectors and remove the cable guides.

Remove the femoral neck load cell (Figure 1.74, Item 3) by taking out the four BHCS M6 x 1,0 x 16 (Figure 1.74, Item 10) that attach it to the trochanter assembly (Figure 1.74, Item 9).

Remove the twelve modified BHCS (Figure 1.74, Item 5) that respectively attach the trochanter (Figure 1.74, Item 9) to the leg load cell (Figure 1.74, Item 8), the leg tube assembly (Figure 1.74, Item 7) to the leg load cell and the leg tube assembly (Figure 1.74, Item 7) to the knee assembly (Figure 1.74, Item 6). Separate these assemblies.

1.7.2.3 Knee

Detach the lower leg assembly by removing the four modified BHCS that attach the knee assembly to the leg load cell at the upper tibia position (Figure 1.76, Item 1).

Remove the knee covers (Figure 1.75, Item 2) by removing the four SHCS M4 x 0,7 x 10 mm (Figure 1.75, Item 1) holding each cover in place. Remove the potentiometer assembly (Figure 1.75, Item 4) by taking out the BHCS M3 x 0,5 x 6 mm (Figure 1.75, Item 5) at each side of the potentiometer. The knee contact load cell structural replacement

(Figure 1.75, Item 3) is positioned directly beneath the knee cover and is removed by taking out four SHCS M4 x 0,7 x 10 mm (Figure 1.75, Item 1) for each load cell. Note that the screw used to secure the knee covers is the same size screw used to secure the knee contact load cell or its structural replacement.

Remove the knee bone (Figure 1.75, Item 16) by taking out the SSHDP M6 x 1,0 x 12 mm (Figure 1.75, Item 17). Remove the BHCS M10 x 1,5 x 20 mm (Figure 1.75, Item 13) along with the associated washers (Figure 1.75, Item 12, 11 and 10). Inspect these washers for damage and wear. The middle washer (Figure 1.75, Item 11) is the compression washer and is made from a soft neoprene rubber. Note that because it is a soft material permanent compression and/or tearing could occur. If the part is permanently compressed or damaged in any way it should be replaced.

Remove the knee pivot shaft (Figure 1.75, Item 8) by sliding it out of the assembly. Slide the knee bone out of the knee clevis assembly. Remove the knee pad (Figure 1.75, Item 14) from the knee bone by taking out the six BHCS M4 x 0,7 x 12 mm (Figure 1.75, Item 15) (three on each side) that hold it in position. Inspect the knee pad for tearing and/or cuts in the material.

1.7.2.4 Lower leg

Remove the BHCS M3 x 0,5 x 6mm (Figure 1.76, Item 10). Remove the cable guides (Figure 1.76, Item 11) and disconnect the cables from the load cells. Remove the upper tibia load cell by removing four modified BHCS (Figure 1.76, Item 2) and separating the leg load cell (Figure 1.76, Item 1) from the lower leg tube (Figure 1.76, Item 3).

Remove the z-axis radial limit screw (Figure 1.76, Item 5) to remove the lower tibia leg load cell (Figure 1.76, Item 1). Loosen the NTSS M6 x 6 mm (Figure 1.78, Item 1). Use this set screw to adjust the z-axis rotational friction for the lower tibia load cell. Disconnect the cables from both of the

tibia loads. Using a modified 22 mm open-end wrench (W50-51004), hold the z-axis nut (Figure 1.76, Item 9) in place while rotating the leg tube and load cell assembly until the lower tibia leg load cell can be pulled from the ankle assembly. Remove the anti-rattle and rotational washers (Figure 1.76, Items 7 and 8) from the assembly.

Remove the four SHCS M5 x 0,8 x 16 mm that secure the foot to the ankle assembly (Figure 1.77, Item 4) to remove the moulded foot.

1.7.2.5 Ankle

Remove the Y-Axis potentiometer (Figure 1.78, Item 4), if equipped, by loosening the SSNT M3 x 0,5 x 3 mm (Figure 1.78, Item 5) holding it in place. Pull the potentiometer from the assembly. Remove the six BHCS M4 x 0,7 x 10 mm (Figure 1.78, Item 10) that attach the ankle joint cover (Figure 1.78, Item 11) to the ankle joint assembly (Figure 1.78, Item 12).

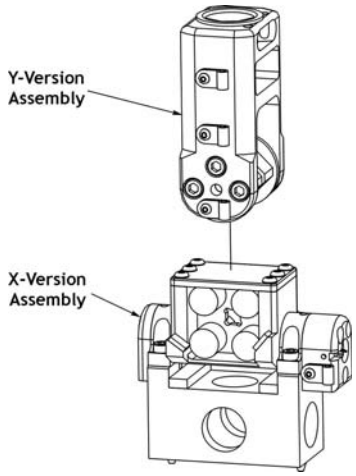


Figure 1.79 — Ankle

Lift the Y-version assembly off the X-version assembly. Note that when the two assemblies separate, the resistive elements (Figure 1.78, Item 22) will fall out of the assembly. With the two assemblies separated, take apart

each assembly. Check the resistive elements for signs of permanent deformation, crushing or cracks.

To remove the z-axis potentiometer assembly (Figure 1.78, Item 24), first loosen the SSNT M3 x 0,5 x 3 mm (Figure 1.78, Item 25) that holds it in position. If the potentiometer is connected to a cable, first release the cable from the cable clamps located along the side of the clevis assembly (Figure 1.78, Item 2). Then move it downward out of the clevis assembly.

NOTE When reinstalling each potentiometer, do not over tighten the set screw on the body of the potentiometer or the device may be damaged. Tighten it just enough to hold it in position securely.

To disassemble the X-version assembly, start by taking out the four SHCS M5 x 0,8 x 16 mm (Figure 1.78, Item 8) that secure the retainer brackets (Figure 1.78, Item 9). With the retainer brackets removed, remove the ankle joint assembly (Figure 1.78, Item 12) from the assembly.

Note that while removing the retainer brackets the X-version resistive elements (Figure 78, Item 21) could fall out. Check the resistive elements for crushing, deformation or cracks.

Check the stop pads (Figure 1.78, Item 26) and compression pads (Figure 1.78, Item 27) for tears and deformation. Re-secure the pads using Loctite 414, “Super Glue” or equivalent cyanoacrylate based adhesive, if they come loose.

1.7.3 Assembling the leg

In general the procedure for assembling the leg is substantially the opposite of the procedure for disassembling it. The following descriptions are provided to assist the user to more efficiently assemble the WorldSID leg.

1.7.3.1 Assembling the femoral neck

Thread the femoral neck ball on to the femoral neck base until tight (see Figure 1.73). Tighten the ball on to the base using a modified 25 mm to 28 mm spanner wrench (W50-51001) to turn the ball and a spanner wrench 40 mm to 42 mm (W50-51002) to hold the femoral neck base (Figure 1.73, Item 4). Be careful not to damage the surface of the ball during disassembly and re-assembly. Secure the ball by tightening the SSCP M4 (Figure 1.73, Item 1) to 2 Nm torque.

1.7.3.2 Assembling the upper leg

Attach the femoral neck load cell assembly (Figure 1.74, Item 3) to the trochanter assembly (Figure 1.74, Item 9). Ensure that the base of the load cell is aligned with the dowel pin in the trochanter before tightening the four BHCS M6 x 1 x 16 mm (Figure 1.74, Item 5). Torque the BHCS M6 to 10 Nm.

Attach the trochanter assembly and the leg tube assembly (Figure 1.74, Item 7) to the upper leg load cell (Figure 74, Item 8) using eight modified BHCS M6 (Figure 1.74, Item 5), four at each side of the load cell. Torque the modified BHCS M6 to 10 Nm.

The knee assembly (Figure 1.74, Item 6) is attached to the leg tube assembly using four modified BHCS M6. The left and right knee assemblies are different.

1.7.3.3 Assembling the knee

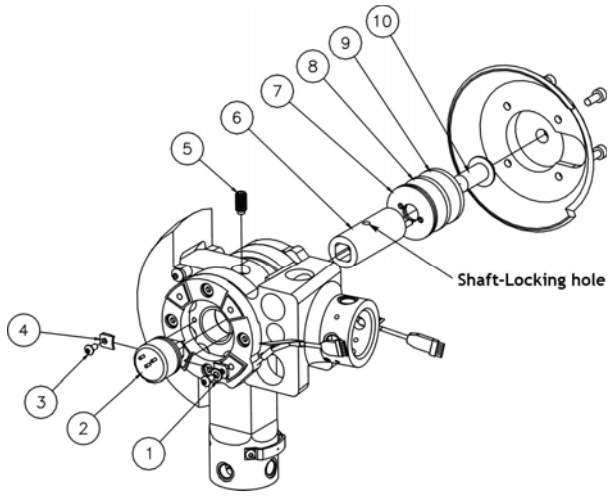


Figure 1.80 — Knee assembling

To assemble the knee, start by placing the knee bone (Figure 1.75, Item 16) in the knee clevis (Figure 1.75, Item 9) and push the knee pivot shaft (Figure 1.75, Item 8) into the pivot hole. Align the shaft-locking hole with the SSHDP M6 x 1 x 12 (Figure 1.75, Item 17). Tighten the SSHDP M6 so that the knee pivot shaft is locked in place. Note that if the pivot shaft is not locked into the knee bone the shaft will not rotate with the knee bone during testing. Once the pivot shaft is in place, install the friction, compression and clamping washers (Figure 1.80, Item 7, 8, and 9, respectively). The friction washer (Figure 1.80, Item 7) is made up of two disks; one disk is steel and the other is a commercial braking material. Push the friction washer on to the pivot shaft pins so that the braking material side of the washer is against the knee clevis. Install the compression and clamping washers and secure them with a BHCS M10 x 1,5 x 20 mm (Figure 1.80, Item 10), which is the adjustment for the 1-to-2-g-setting adjustment of the knee section.

To install the knee potentiometer, place the potentiometer insert into the square hole end of the knee pivot shaft (see Figure 1.82). Insert the two BHCS M3 x 0,5 x 6 mm (Figure 1.75, Item 5) into the potentiometer clips

and thread them into the knee clevis. Tighten these two BHCS M3 so that the potentiometer body is secure and will not rotate.

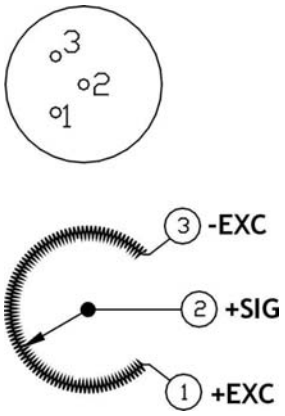


Figure 1.81 — Knee potentiometer wiring

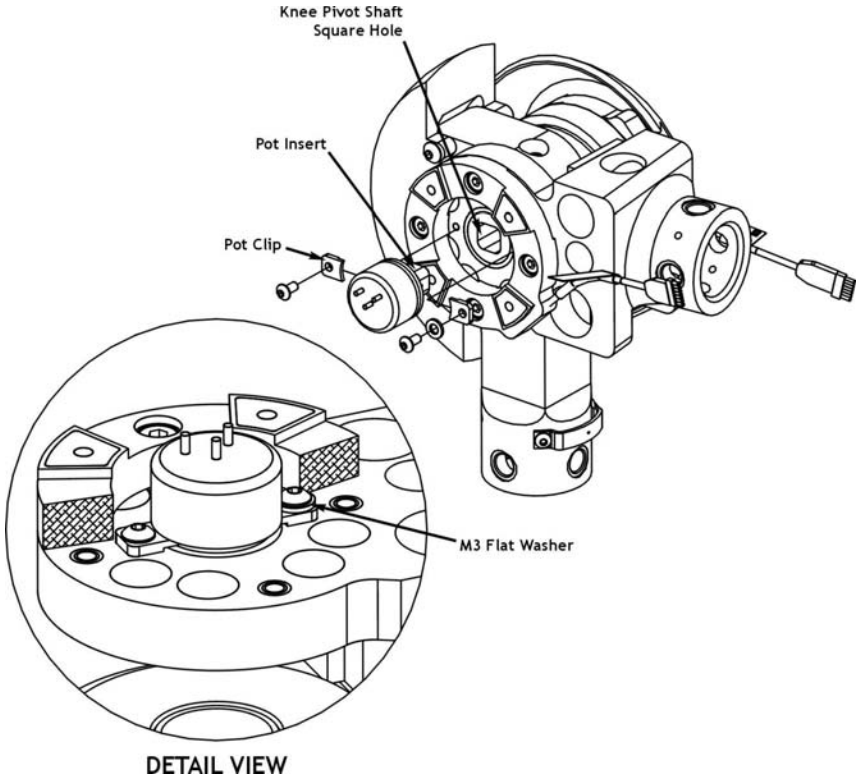


Figure 1.82 — Knee potentiometer installation

Attach the knee contact load cell (Figure 1.75, Item 3), using four SHCS M4 x 0,7 x 10 mm for each load cell (Figure 1.75, Item 1). Install the load cell directly on to the knee clevis and install the M4 screws in the counter bored holes. Tighten these M4 screws to 5 Nm, using the M4 “star” pattern (see Figure 1.83) so as to distribute the load equally across the load cell.

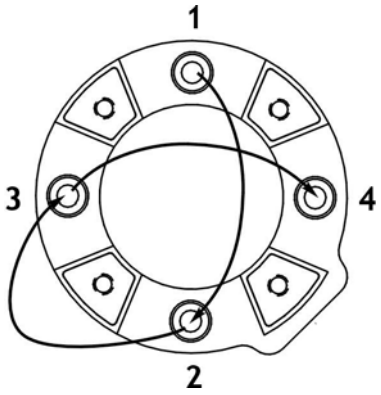


Figure 1.83 — Torquing the knee contact load cell

Attach the knee covers (Figure 1.75, Item 2) and pad (Figure 1.75, Item 14). Attach the knee covers directly to the knee contact load cells with four SHCS M4 x 0,7 x 10. Re-attach the knee covers using the same “star” pattern as the knee contact load cell (see Figure 1.83). Attach the knee pad using six BHCS M4 x 0,7 x 12 mm (Figure 1.75, Item 15).

1.7.3.4 Assembling the lower leg

The lower leg load cells (Figure 1.76, Item 1) are attached to the lower leg tube using four modified BHCS M6 (Figure 1.76, Item 2) for each load cell. Torque these modified BHCS to 10 Nm. Both the upper and lower leg load cells are W50-71010 and can be positioned interchangeably but must be annotated so that the correct sensitivities are used. The load cells shall be installed with the connectors positioned toward the knee end of the assembly.

The ankle 'Z'-pivot pin (Figure 1.76, Item 6) is installed in the lower load cell. The 'Z'-pivot pin is secured in position using three SSCP M6 x 1 x 8 mm (Figure 1.76, Item 4) installed in the load cell and aligned with the drill points in the pin. A fourth screw (Figure 1.76, Item 5) is installed after the ankle assembly is installed along with the anti-rattle washer, rotational washer and nut (Figure 1.76, Items 7, 8, and 9 respectively). The fourth screw is known as the z-axis radial limit screw." This "limit screw" is a modified SHCS M6 and is installed on the anterior of the lower leg to control the radial travel of the ankle.

The ankle assembly (Figure 1.77, Item 2) is attached to the lower leg assembly with the Z-pivot pin, anti-rattle washer, rotational washer and z-axis nut (Figure 1.76, Items 6, 7, 8, and 9 respectively) (see Figure 1.89 for a clearer diagram of the ankle to lower leg assembly. These components must be in place in the ankle before the lower leg assembly can be attached.

Once the lower leg assembly is installed on the ankle, the washers and nut can be tightened until the z-axis movement is eliminated. Then, with the leg flesh orienting block (Figure 1.76, Item 12) positioned toward the rear (posterior) of the assembly, install the z-axis radial limiting screw (Figure 1.76, Item 5 or Figure 1.89).

1.7.3.5 Assembling the ankle

The ankle assembly is made up of two sections: 'X' version and 'Y' version. The upper section is the 'Y' version assembly. The lower section of the ankle assembly is the 'X' version assembly (see Figure 1.79 and Figure 1.85).

Place the resistive elements, two on each side (Figure 1.85, Item 4), on the ankle joint assembly (Figure 1.85, Item 5), slide the 'Y' version assembly on to the ankle joint assembly. Check periodically for damage to the Teflon® washers attached to the inner surfaces of the 'Y' version left and right flexion centre assemblies (Figure 1.78, Items 6 and 23).

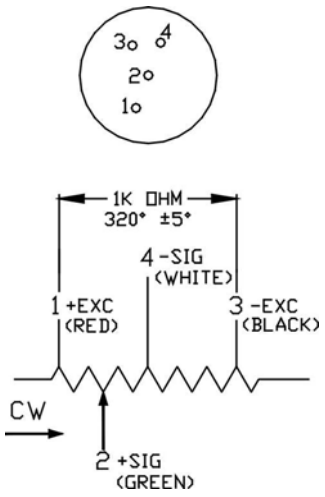


Figure 1.84 — Ankle potentiometer wiring

With the 'Y' version assembly positioned on the ankle joint assembly, place the remaining four resistive elements on top of the left and right flexion centre assemblies and install the ankle joint cover (Figure 1.85, Item 3). In order to compress the resistive elements sufficiently to be able to insert the six BHCS M4 x 0,7 x 10 mm to attach to the cover, two SHCS M4 x 0,7 x 18 mm are used. Tighten the two SHCS M4 (Figure 1.85, Item 1) until the BHCS M4 x 0,7 x 10 mm can be installed and then replace the two SHCS with BHCS M4.

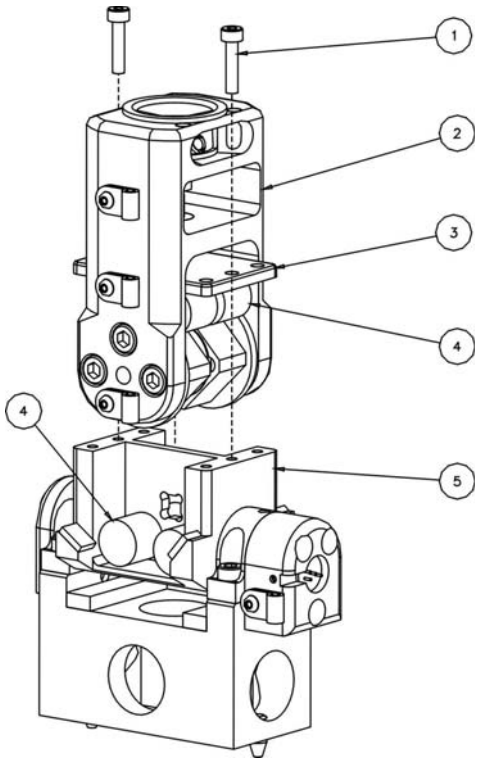


Figure 1.85 — 'X' and 'Y' version assembling

Install the potentiometer (W50-54012) into the 'X' version assembly by loosening the three screws (Figure 1.78, Item 15) and inserting the potentiometer into the hole at the front side of the ankle assembly (see Figure 1.86). Do not over-tighten the two SSNT M3 x 0,5 x 3 mm set screws that secure the potentiometer body or there may be damage to the potentiometer. Note that there is an SSCP M3 x 0,5 x 4 mm (Figure 1.78, Item 7) that secures the potentiometer shaft.

To install the y-axis potentiometer, this section must be assembled on to the 'X' version assembly. Insert the potentiometer body into the appropriate mounting hole shown in Figure 1.86 and tighten the SSNT M3 x 0,5 x 3 mm. Do not over tighten this set screw or the potentiometer will be damaged. Note that the SSNT M3 x 0,5 x 3 mm need only be tightened enough to secure the body and keep it from moving.

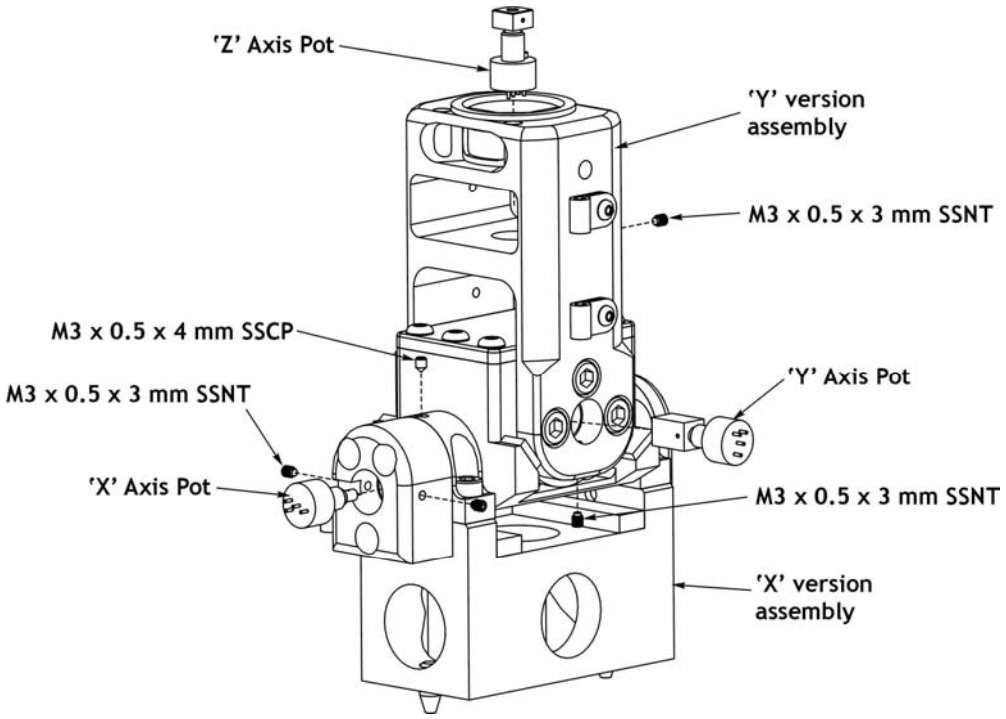

'Z' Axis Pot
'Y' version assembly
M3 x 0.5 x 3 mm SSNT
M3 x 0.5 x 4 mm SSCP
M3 x 0.5 x 3 mm SSNT
'Y' Axis Pot
'X' Axis Pot
M3 x 0.5 x 3 mm SSNT
'X' version assembly

Figure 1.86 — Ankle assembly potentiometers

1.7.4 Adjusting the leg

1.7.4.1 General

The WorldSID leg assembly has two joint adjustments that control the 1-to-2-G-setting, and that one of the joint adjustment points is located at the knee pivot and the other is located at the top of the ankle assembly.

1.7.4.2 Adjusting the knee pivot rotation

Note the following:

- The knee pivot screw (see Figure 1.87) controls the motion of the lower leg. In order to do this there are several components involved: clamping, compression and friction washers, and the pivot shaft assembly. For the knee pivot screw to control the friction in the knee joint all of these component must be correctly installed and in good working condition. Tighten the knee pivot

screw to obtain a1-to-2-G-setting. This screw will squeeze the compression washer against the friction washer thus increasing the resistance to movement of the knee bone in the knee clevis.

- The friction washer must be installed with the friction material toward the knee clevis or the washer will provide very little resistance to movement. The compression washer (a neoprene material) should be inspected to ensure that it is not permanently compressed or damaged.

- The SSHDP that locks the pivot shaft assembly in place in the knee bone must be correctly installed. The SSHDP M6 shown in Figure 1.88 must be installed so that the tip is in the locking hole at the middle of the pivot shaft.

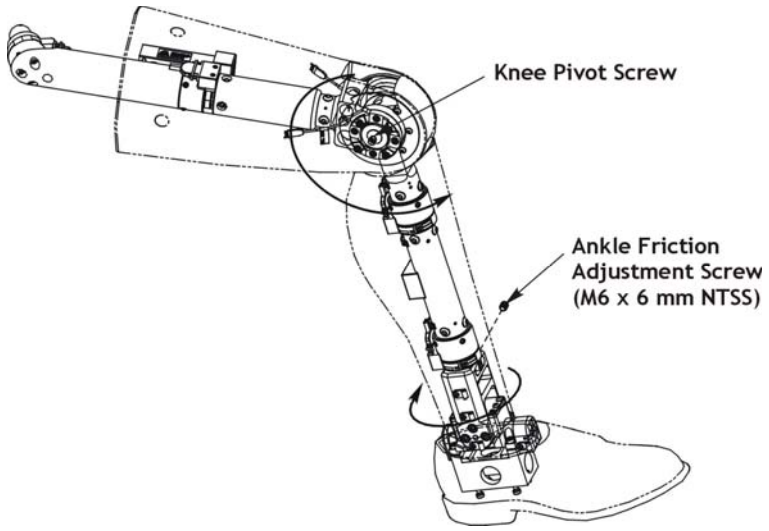


Figure 1.87 — Knee assembly

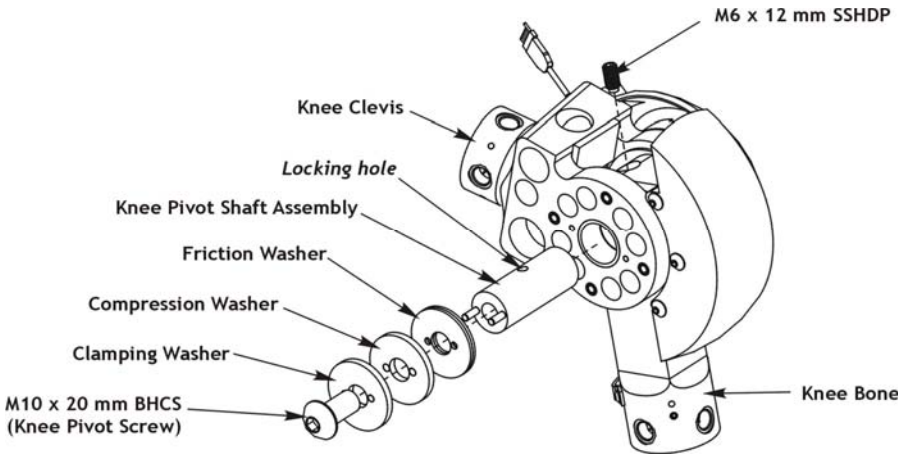


Figure 1.88 — Leg joint adjustments

1.7.4.3 Adjusting ankle rotation

Note the following:

- The ankle adjustments are not easily done due to the lack of mass of the components.

- This joint is adjusted to approximate a 1-to-2-G-setting.

- The ankle rotation friction is controlled by a M6 set screw and a M14 lock nut (z-axis nut) (see Figure 1.89).

Loosen the M6 set screw and check the z-axis movement of the lower leg load cell in the ankle assembly. The z-axis is on a line extending perpendicular to the sole of the foot and through longitudinal centerline of the lower leg load cell. Tighten the z-axis nut sufficiently to eliminate movement along the z-axis at the load cell while allowing for free rotation about the z-axis.

Adjust the set screw M6 in the ankle assembly such that there is consistent stiffness in the joint to approximate a 1-to-2-G-setting as the foot is rotated about the lower leg.

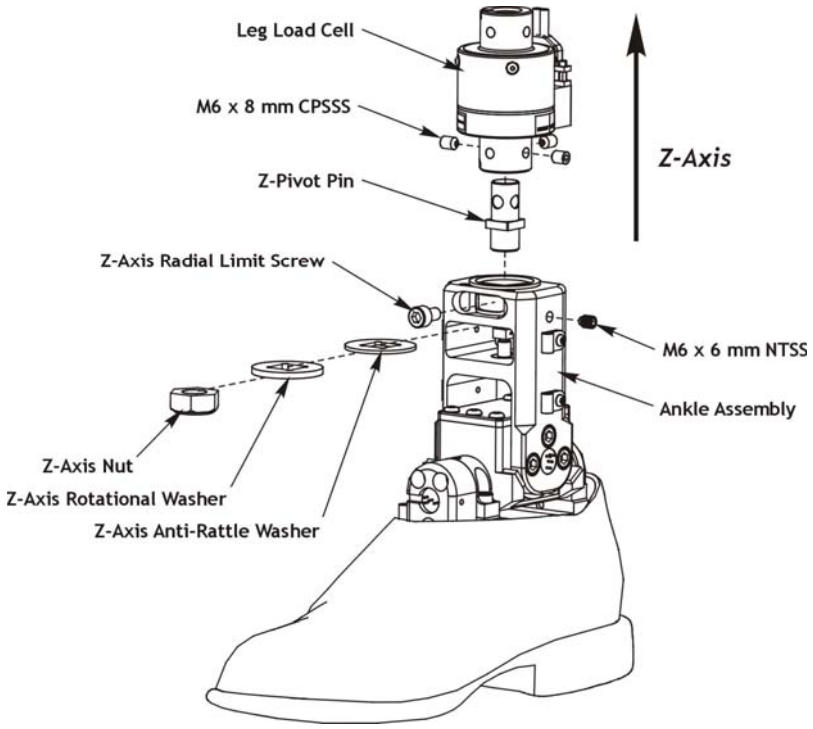


Figure 1.89 — Ankle adjustment

1.8 Suit assembly

1.8.1 Parts list for suit

The part number for the WorldSID suit is W50-80100.

1.8.2 Disassembly

Unzip all suit zippers and carefully remove the suit by reversing the assembly procedures.

1.8.3 Assembly

Install the dummy lifting bracket, and lift the dummy with a hoist. Open all the zippers on the suit, including the front and rear of the thorax and both legs. If working with a full arm, set the full arm sleeves aside at this point. Insert the arms through the short sleeves and close the zipper on the rear side of the dummy. Straighten the legs, pull the suit tight around the legs

and close both leg zippers. Make sure the shoulder pads are in the proper position, and zip the front thorax zipper half way. Note the front thorax zipper cannot be fully zipped due to the lifting bracket. Install full arm sleeves if needed. Move the dummy to the bench or inside the vehicle; remove the lifting bracket by removing the M8 bolt on the top and M12 bolt on the bottom, and then close the front thorax zipper.

SECTION 2

2. RECOMMENDED WORLDSID GENERAL PRACTICES

2.1 Certification test intervals

The acceptable interval between WorldSID certification tests is highly dependent upon the type and severity of impacts to which the WorldSID is subjected. Each user should determine their own requirements based on their existing policies, regulatory requirements, impact severity, and experiences with the WorldSID.

Users should perform certification tests as follows;

- before and after each series of sled tests,
- after every three full scale vehicle tests;
- after each high energy impact;
- after any unusual impact;
- if ribs exhibit more than 2 mm of permanent deformation when compared to their original shape.

2.2 Recommended inspection practices

As with the certification test interval discussed in 2.1, each WorldSID user should determine their own inspection requirements based on their existing policies, regulatory requirements, impact severity, and their experience with the WorldSID.

When establishing appropriate inspection practices, users should consider the following:

- All parts should be visually inspected during each assembly and disassembly process.

- Before performing certification tests, the involved parts should be visually inspected.

- Components subjected to high energy impact should be inspected following the test.

- Ribs should be inspected on a regular basis and after high energy impacts to determine if permanent deformation exceed 2 mm.

- The rib doubler to rib joint should be inspected on a regular basis and after high energy impacts to determine if there has been any separation of the doubler from the rib.

- Flesh components should be inspected for tears.

- Sensor and DAS cables should be inspected for cuts and excessive wear.

- Joint tension should be checked and adjusted as described in Section 1

Sensor and DAS functions should be verified prior to each test.

2.3 WorldSID thorax half width

When calculating thorax injury indices, a WorldSID thorax half width of 170 mm should be used.

2.4 Avoiding possible connector damage

When using the optional G5 DAS, each WorldSID sensor cable has a connector with exposed pins which can be damaged during installation, removal, or handling.

To prevent damage the user should consider the following preventative measures:

1) Use extreme care when the connectors are installed, handled or routed in the dummy.

2) Install available connector covers, any time the pins are exposed, removing them only immediately before plugging the connector into the interposer.

2.5 Temperature range

The WorldSID dummy temperature, when measured by the optional internal temperature sensor, should be 20,6 degrees C to 22,2 degrees C. The test environment temperature should be 20,6 degrees C to 22,2 degrees C.

2.6 Dummy handling

2.6.1 General

A lifting bracket assembly and fasteners (part number W50-84100) as shown in Figure 2.1 containing the parts listed in Table 2.1 is included with each dummy for handling.

Table 2.1 — Parts list for lifting bracket assembly

Item number	Quantity	Part number	Description
1	1	5000537	Screw, SHCS M8 x 1,25 x 80
2	1	W50-84106	Handle, threaded rod
3	1	W50-84104	Handle, threaded hole
4	1	W50-84110	Lifting bracket weldment
5	1	5000538	Screw, SHCS M12 x 1,75 x 150

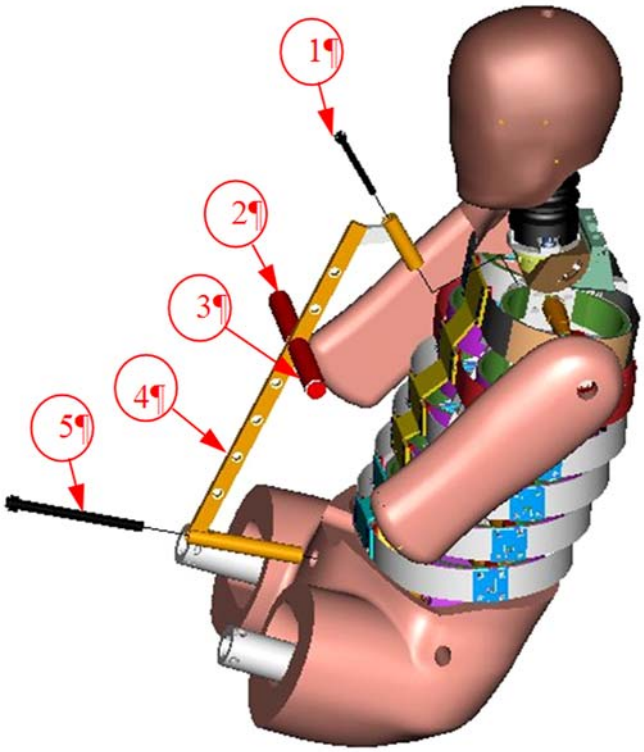


Figure 2.1 — Lifting bracket assembly

2.6.2 Procedures for using the lifting bracket are as follows

1) Insert the lifting bracket (Figure 2.1, Item 4) through a hole on the pelvis flesh and align it with the threaded hole inside the pelvis.

2) Thread bolt (Figure 2.1, Item 5) a few threads into the pelvis so that it is engaged but not tight.

3) Bend the dummy forward to align the upper portion of the lifting bracket with the hole on the top front of the spine box assembly.

4) Loosely install bolt (Figure 2.1, Item 1).

5) Tighten both bolts (Figure 2.1, Items 1 and 5).

6) If needed, some soft webbing can be used to loop around the upper leg above the knee area and attached to the lifting bracket to help support the legs.

7) Handles (Figure 2.1, Items 2 and 3) can be used for handling of the dummy inside the vehicle.

8) When the dummy is positioned, remove the bracket from the dummy before conducting any test.

2.7 Dummy storage

The dummy should be stored in a seating position with the lifting bracket installed.

SECTION 3

3. SUGGESTED WORLDSID WIRING PROCEDURES

3.1 Head Wiring

Head wiring should be installed as follows.

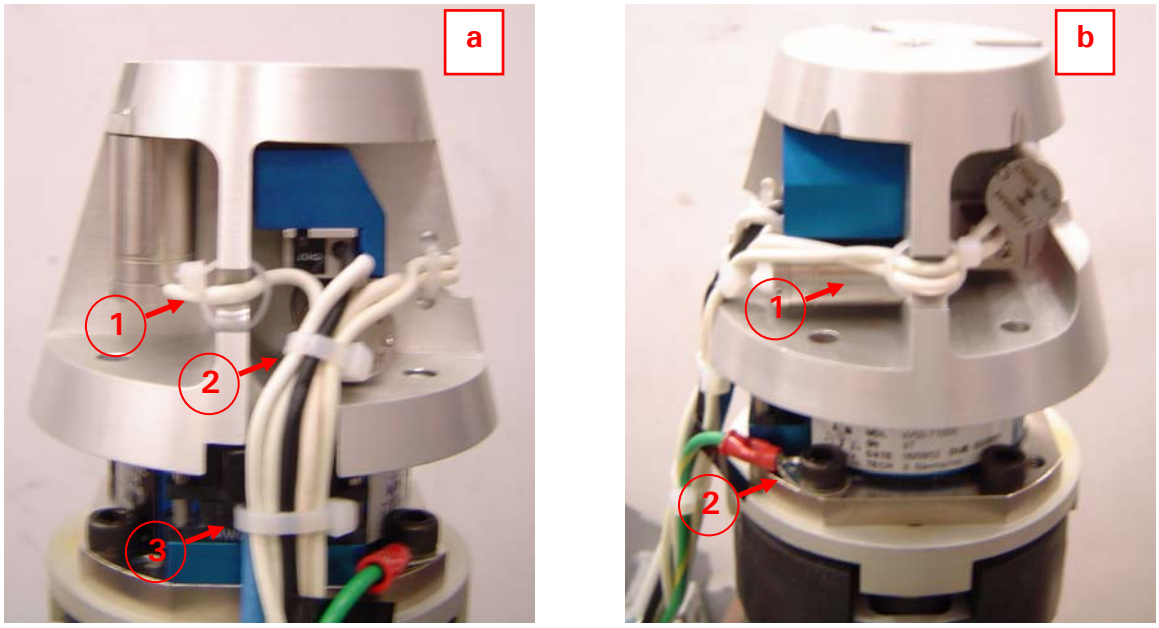


Figure 3.1 — Cable routing for the head

1) Use a cable tie to mount z-axis rotational accelerometer as illustrated by Item 1 in Figure 3.1a.

2) Bundle the accelerometer and y-axis rotational accelerometer cables with cable tie as shown by Item 1 in Figure 3.1b.

3) Sort all the cables together and tie them together with cable tie as shown by Item 2 in Figure 3.1a.

4) Lay all the cables from the head as shown and tie them together with the upper neck load cell cables as shown by Item 3 in Figure 3.1a.

5) Small extra loops of wire inside the head core may be utilized as a precaution against cable pulls damaging the sensor.

3.2 Neck

Neck wiring should be installed as follows.

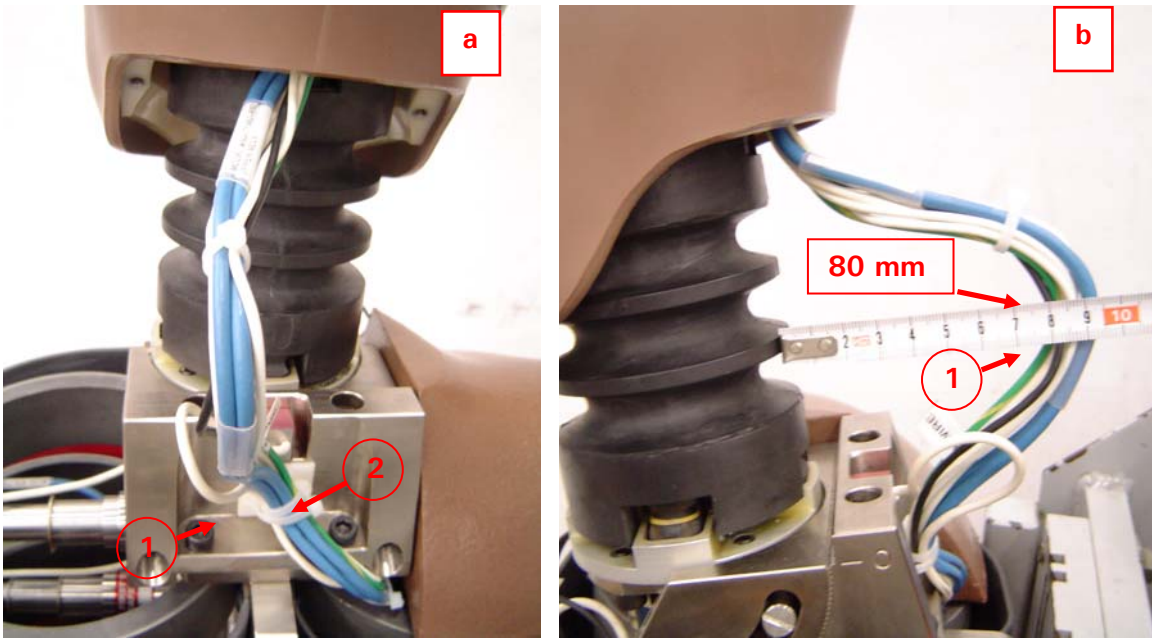


Figure 3.2 — WorldSID neck cable routing

1) Install the head and install a cable tie mount on the back of the lower neck bracket as shown by Item 1 in Figure 3.2a.

2) Bundle all the cables to the cable tie mount as shown, Item 2 in Figure 3.2a, make sure the cable has enough slack as illustrated by Item 1 in Figure 3.2b.

3.3 Shoulder rib and 1st thorax rib

Shoulder rib and 1st thorax rib wiring should be installed as follows.

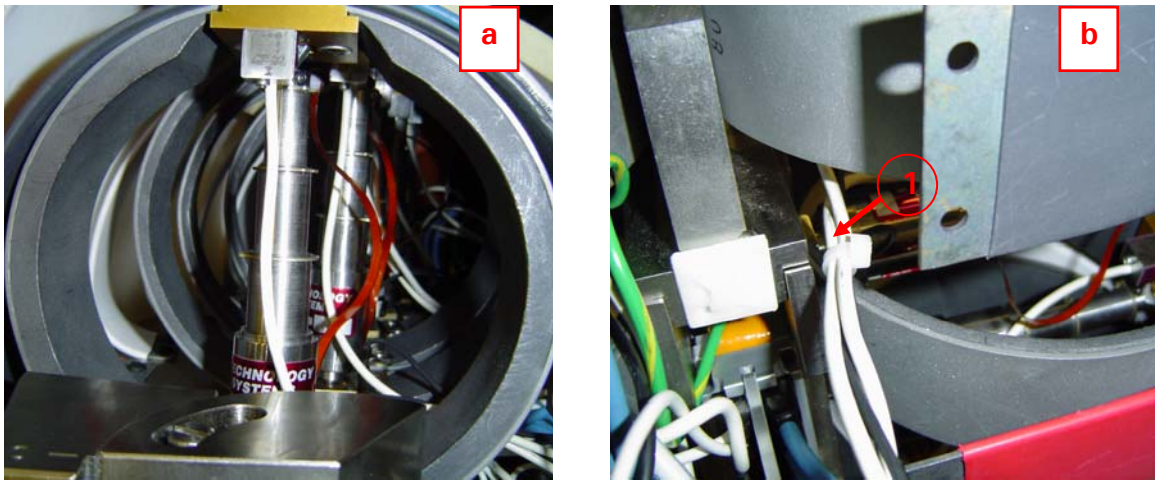


Figure 3.3 — IR-TRACC and linear accelerometer routing for shoulder and 1st thorax ribs

1) Lay the cables of the IR-TRACCs and rib accelerometers as shown in Figure 3.3a.

2) Group these four cables and bundle them together with tie wrap as shown by Item1 in Figure 3.3b.

3.4 2nd and 3rd Thorax ribs and abdomen ribs

Second and 3rd thorax ribs and abdomen ribs wiring should be installed as follows.

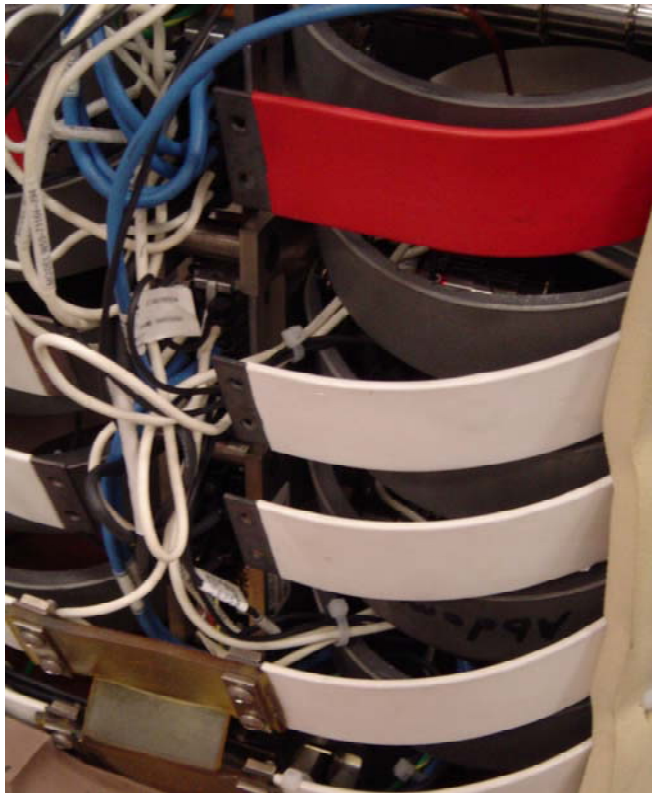


Figure 3.4 — Cable routing for IR-TRACC and linear triax accelerometers of the 2nd, 3rd thorax ribs and abdomen ribs

1) Layout the IR-TRACC and rib accelerometer cables similar to the shoulder as shown in Figure e.3a.

2) Route sensor cables of the 2nd and 3rd thorax ribs thorough the gap between 2nd and 3rd thorax ribs and bundle them as shown by Item 1 in Figure 3.4.

3) Route the sensor cables of the 1st and 2nd abdomen ribs as shown by Item 2 in Figure 3.4.

3.5 Pelvis cable routing

Pelvis wiring should be installed as follows.

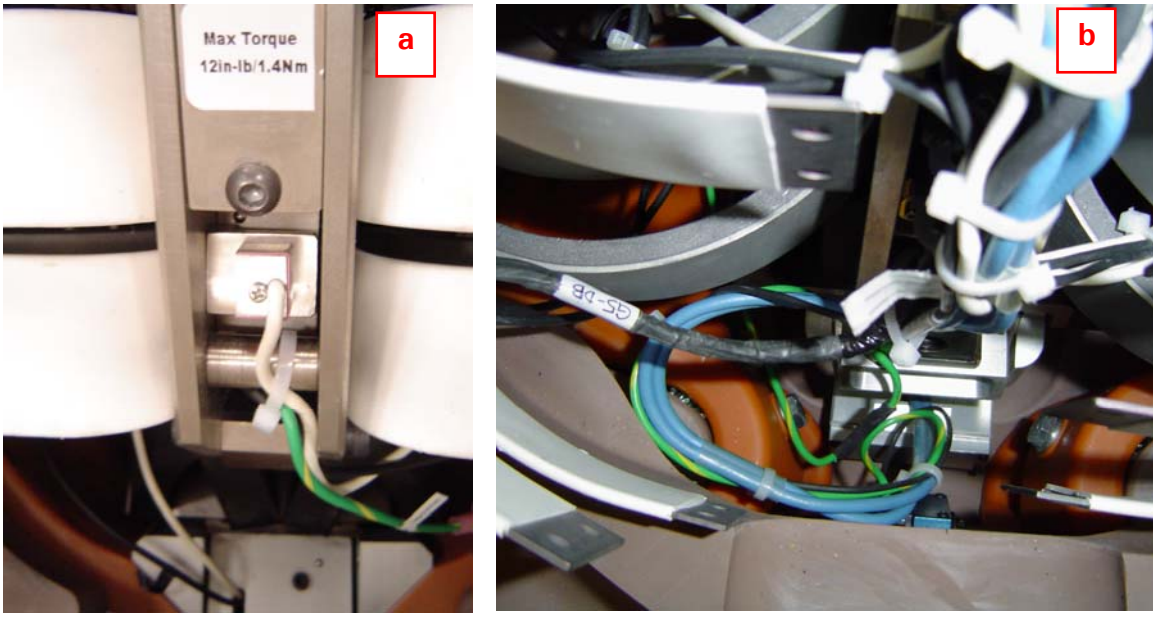


Figure 3.5 — Pelvis cable routing

1) Tie the T12 and ground cable to the back of spine box as shown in Figure 3.5a.

2) Route the pelvis cable as shown in the Figure 3.5b.

3.6 Installation of sensor connectors to the thorax connector station

Thorax connector station wiring should be installed as follows.

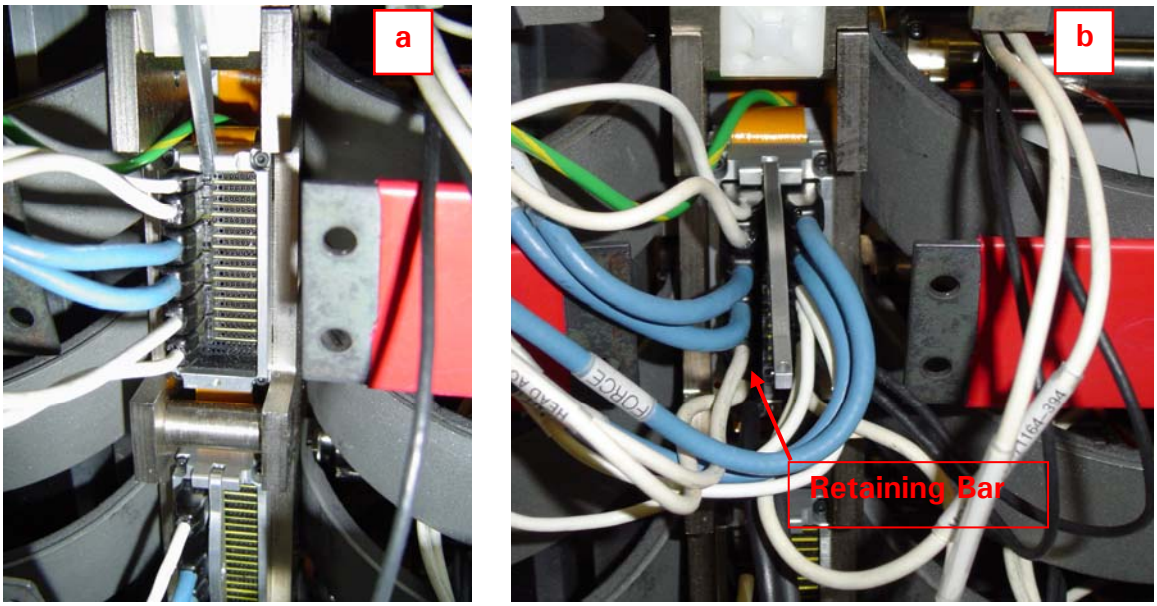


Figure 3.6 — Installations of sensor connectors to the thorax connector station

1) Route all cables from the head, neck cables to the non-impact side through the gap between the shoulder rib and 1st thorax rib.

2) Sort all the cables in front of the connector station and determine the final plug and connector positions.

3) The following cable groupings are recommended. Dummies with a pelvis DAS will be different.

DAS number 1 upper thorax:

1. Upper neck load cell (6 channels)
2. Lower neck load cell (6 channels)
3. Shoulder load cell (3 channels)
4. Head rotational accelerometer x

5. Head rotational accelerometer y
6. Head rotational accelerometer z
7. Head triax accelerometer
8. T1 triax accelerometer
9. T4 triax accelerometer
10. Shoulder triax accelerometer
11. Shoulder IR-TRACC
12. Thoracic rib 1 IR-TRACC

DAS number 2 lower thorax:

1. Thorax rib 1 triax accelerometer
2. Thorax rib 2 triax accelerometer
3. Thorax rib 3 triax accelerometer
4. Abdominal rib 1 triax accelerometer
5. Abdominal rib 2 triax accelerometer
6. Thorax rib 2 IR-TRACC
7. Thorax rib 3 IR-TRACC
8. Abdominal rib 1 IR-TRACC
9. Abdominal rib 2 IR-TRACC
10. T12 accelerometer
11. Pelvis triax accelerometer
12. Pubic load cell (1 channel)
13. Lumbar load cell (6 channels)

NOTE Special care is needed when plugging in the sensor connectors to prevent pin damage. A flash light is helpful for better visibility.

4) Plug in the connectors along one side for the upper thorax station as shown in Figure 3.6a and then the other side as shown in Figure 3.6b.

5) Connect the DAS communication cable and secure the retaining bar shown in Figure 3.6b with an SHCS M1,6.

6) Repeat steps 4 and 5 for the lower thorax station as shown in Figure 3.7.

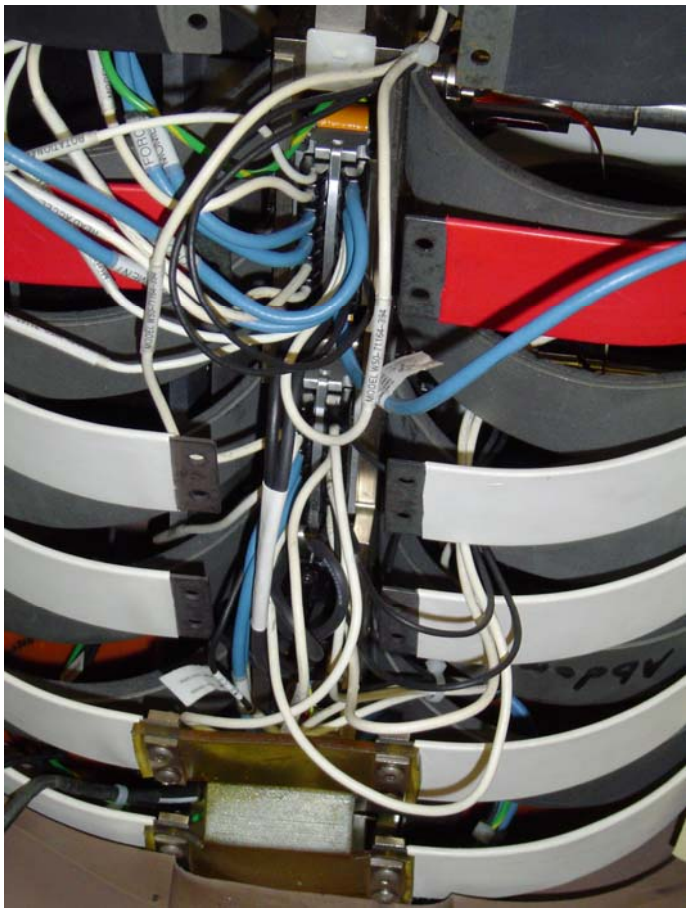


Figure 3.7 — Cable routing for the thorax connector station

7) Bundle the cables at the upper thorax portion to a cable mount as shown in Figure 3.8a, tie the rest of the cable as illustrated in Figure 3.8b.

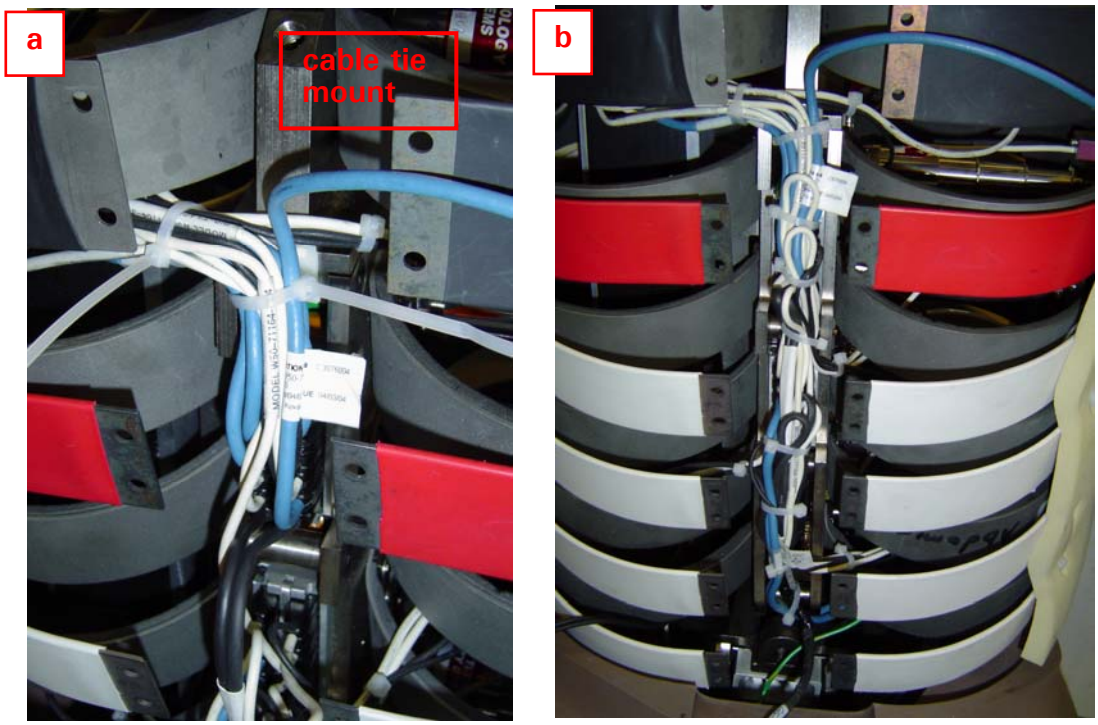


Figure 3.8 — Thorax cable routing

8) Group and bundle the cables in the shoulder area as shown in Figure 3.9.

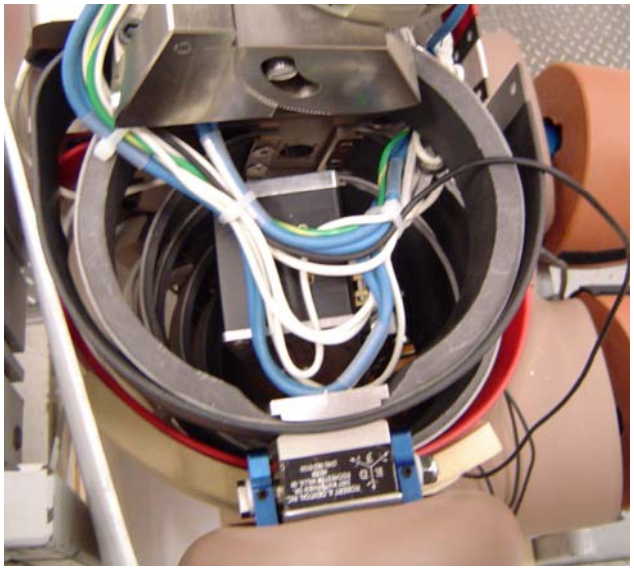


Figure 3.9 — Shoulder area final cable routing

9) Tie the pelvis cable and dummy exit cable as shown in Figure 3.10. The overall thorax cable routing will be as illustrated in Figure 3.11.

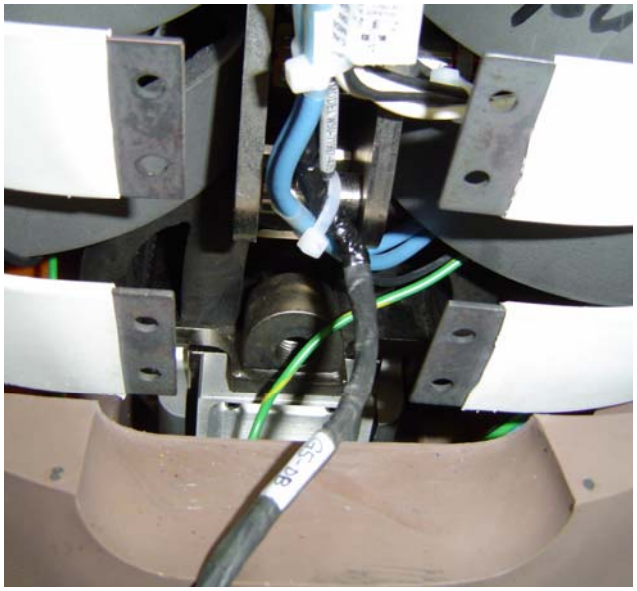


Figure 3.10 — Pelvis cable and dummy exit cable routing

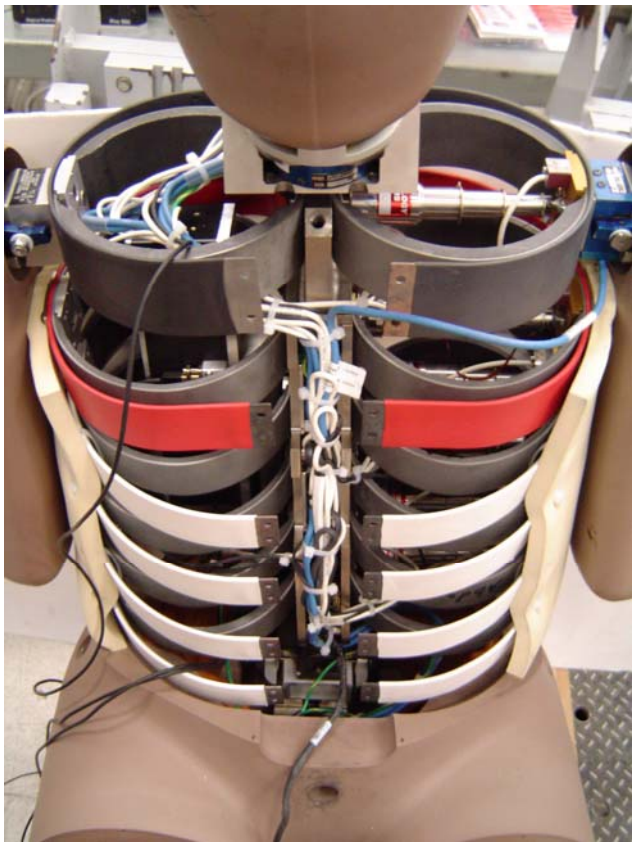


Figure 3.11 — Thorax cable routing

10) Install the sternum and the abdomen coupling, make sure that the dummy exit cable and tilt sensor cables are routed between the abdomen ribs as shown in Figure 3.12. Loop a cable tie around the 2nd abdomen rib (Figure 3.12), then secure the cables to the loop with another cable tie (Figure 3.12).

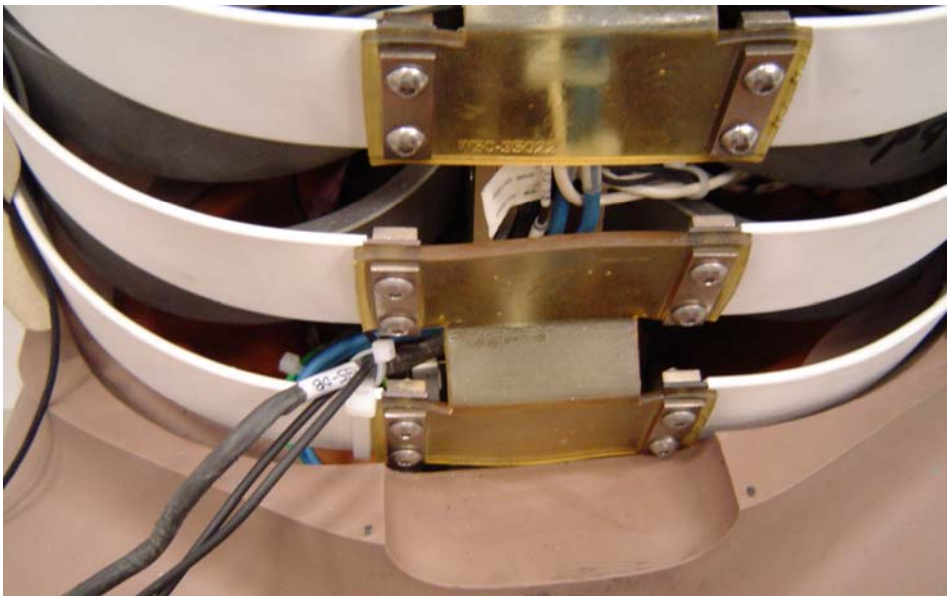


Figure 3.12 — DAS exit cable and tilt sensor cables

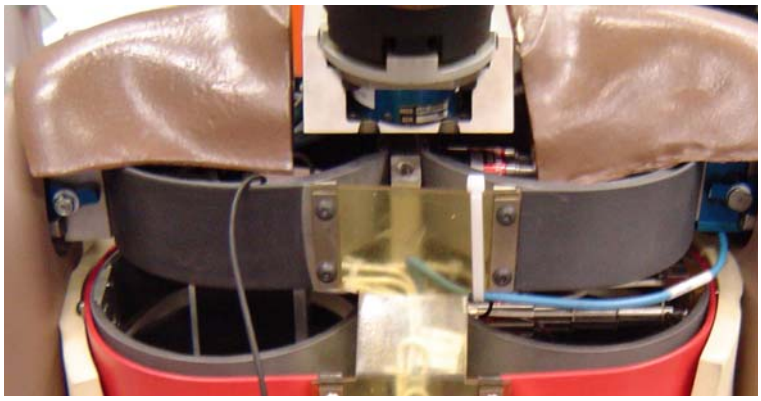


Figure 3.13 — Shoulder load cell cable rounting

11) Route the shoulder load cell cable as shown in Figure 3.12 and tie it to the sternum with a cable tie. The finished wiring looks as shown in Figure 3.14.

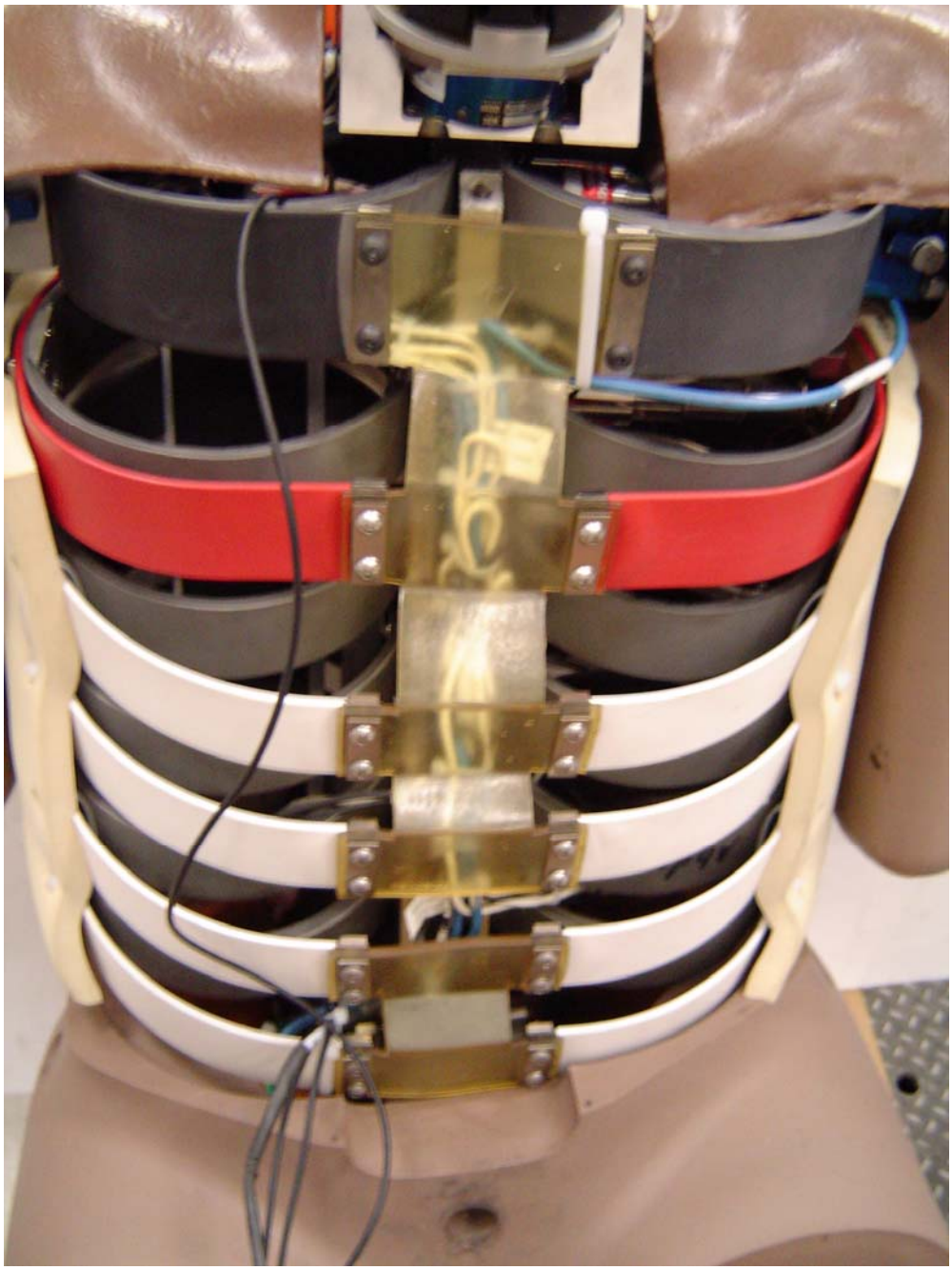


Figure 3.14 — WorldSID final dummy wiring

3.7 Instrumented arm cable routing

3.7.1 General considerations

The following are recommended WorldSID instrumentation cable routing procedures. There are two primary concerns with instrumentation cable routing: 1) cable protection during dynamic testing, 2) reducing the cable's influence on the motion of the dummy during dynamic testing.

3.7.2 Lower arm cables

Route and secure the lower arm cables as shown in Figure 3.15.

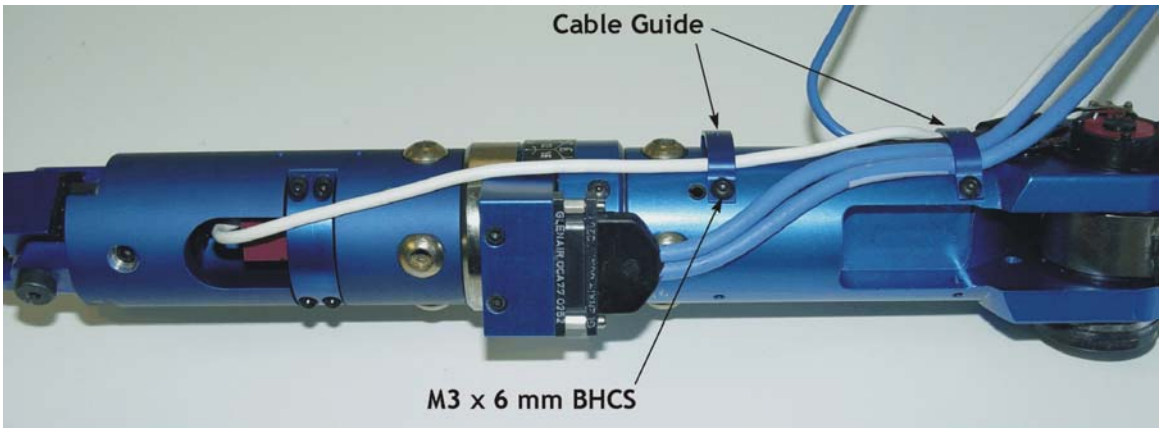


Figure 3.15 — Lower arm cables

3.7.3 Upper arm cables

Route and secure the upper arm cables as shown in Figure 3.16.

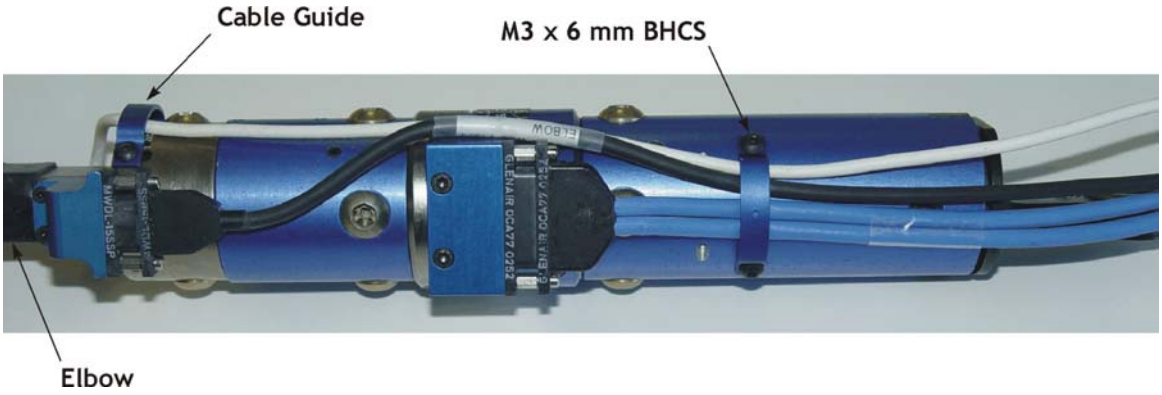


Figure 3.16 — Upper arm cables

3.7.4 Elbow cables

Route and secure cables in the area of the elbow as shown in Figure 3.17.

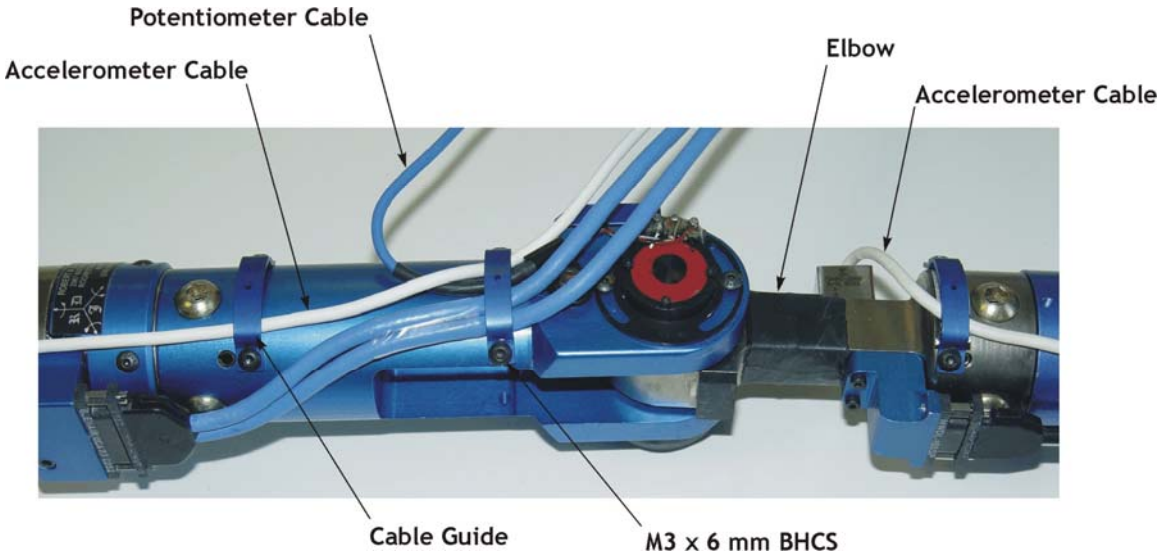


Figure 3.17 — Cables in the elbow region

3.7.5 Routing wires through flesh component

The instrumented arm flesh and suit components should be installed with wire routing as shown in Figure 3.18, Figure 3.19, and Figure 3.20.

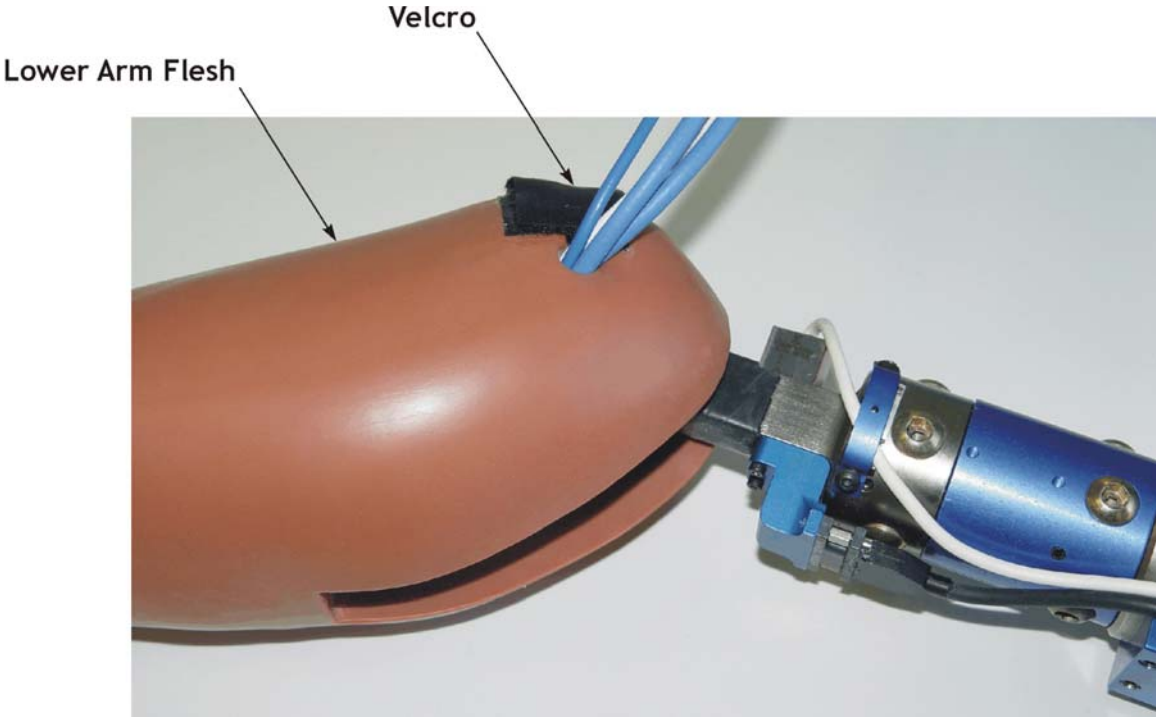


Figure 3.18 — Lower arm flesh

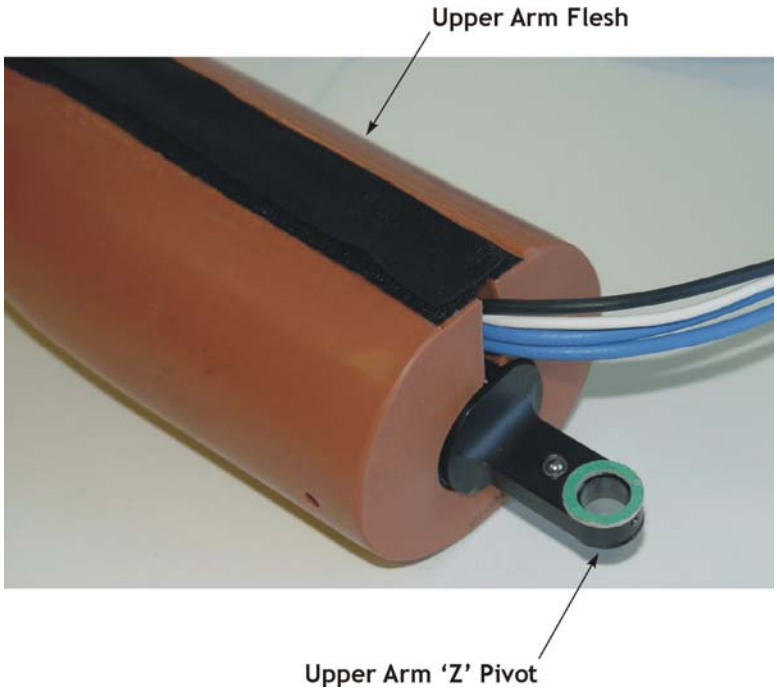


Figure 3.19 — Upper arm flesh

Figure 3.20 — Lower arm suit

3.8 Instrumented leg cable routing

3.8.1 Lower leg cable routing

Route and secure the lower leg cables as shown in Figure 3.21.

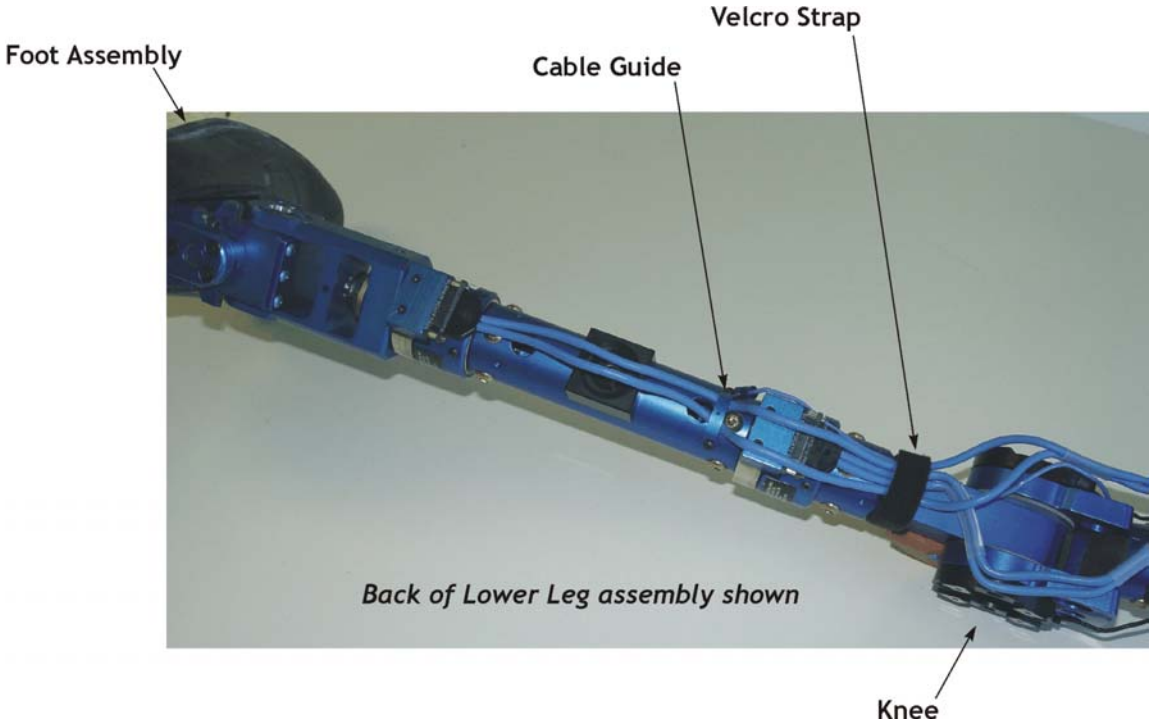


Figure 3.21 — Lower leg cables

3.8.2 Knee cable routing

Route and secure cables in the area of the knee as shown in Figure 3.22, Figure 3.23, and Figure 3.24.

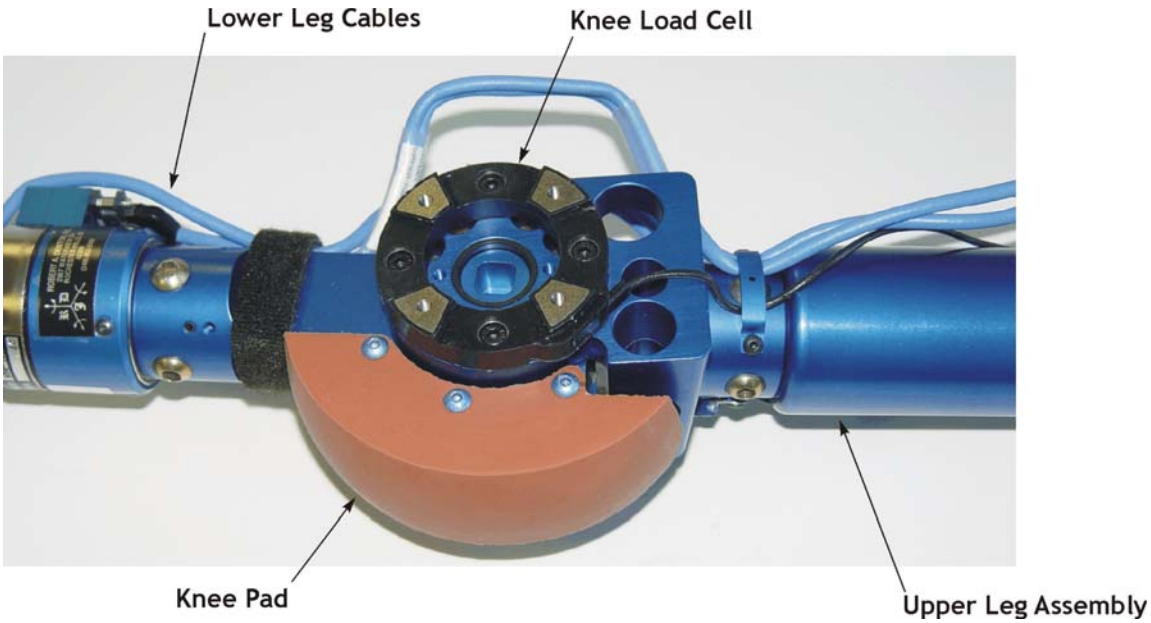


Figure 3.22 — Knee area cable routing

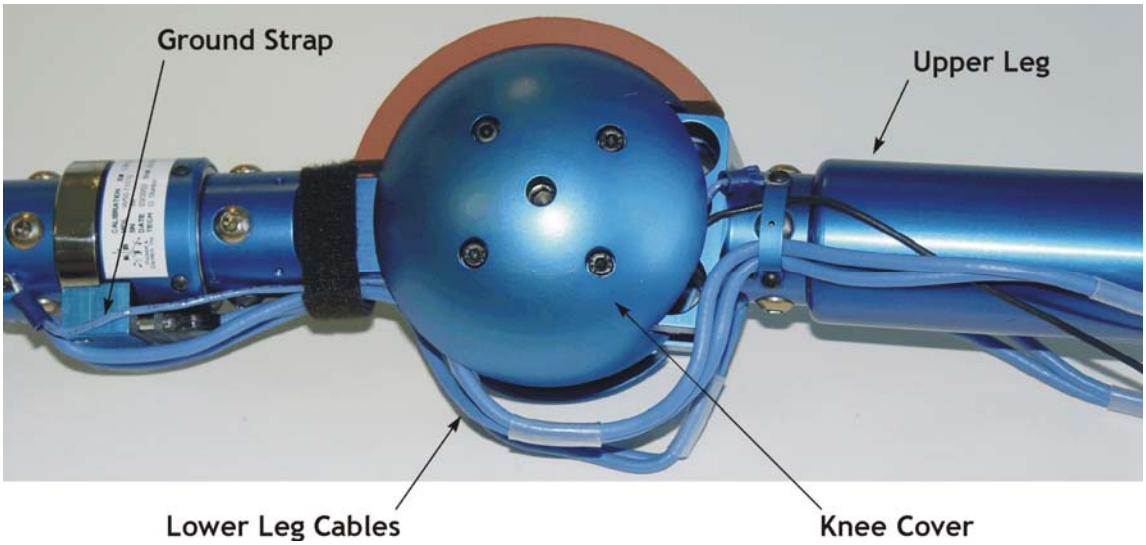


Figure 3.23 — Knee area cable routing

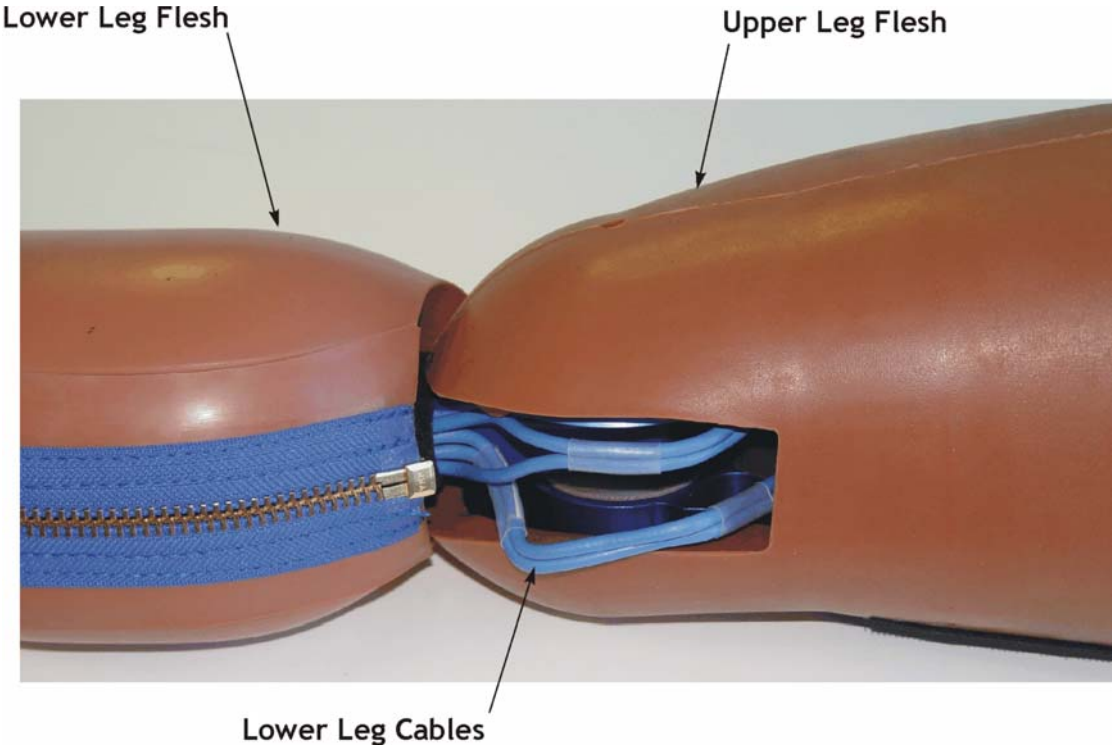


Figure 3.24 — Knee area cable routing and flesh

3.8.3 Femoral neck cable routing

The femoral neck load cell cable should be routed as shown in Figure 3.25.

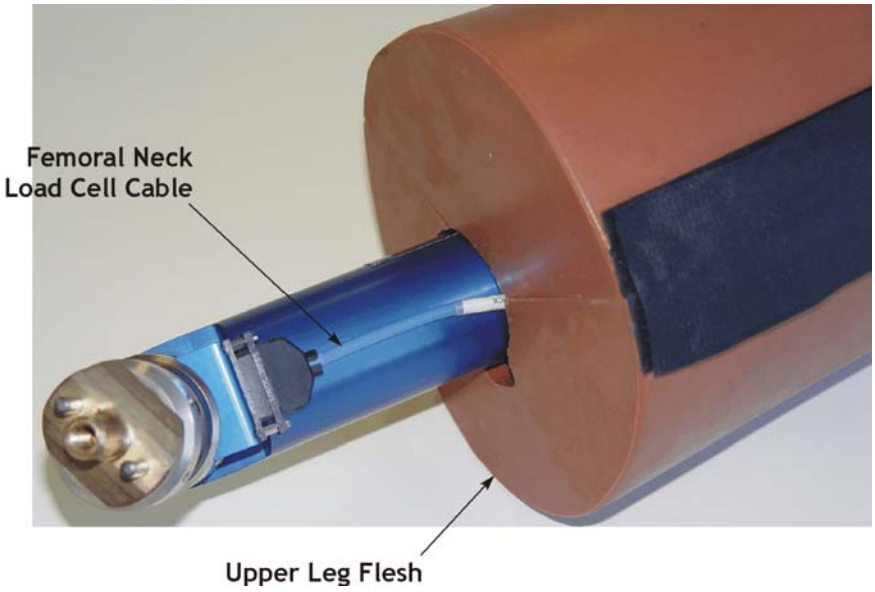


Figure 3.25 — Femoral neck cable routing

3.9 Wiring with an external DAS

For sensor wiring in conjunction with an external DAS, the procedures described in this Section which relate to the sensor end of the cable (see for example Figure 3.1) should be followed when possible.

The routing of the cable or cables exiting the dummy may vary depending upon the DAS, vehicle or test, but in all cases the cable should be secured to the dummy such that the motion of dummy components of interest (e.g., impact side ribs) are not affected and also such that cable tension is not applied to sensors.

Section 4

4. RECOMMENDED WORLDSID GROUNDING SCHEME

4.1 Parts list

The parts given in Table 4.1 should be used to provide electrical continuity between the dummy components and an off-dummy electrical ground point.

Table 4.1 — List of ground cables

Cable number	Part number	Description	Quantity
1	W50-75801	head to thorax	1
2	W50-75802	torso to sacrum	1
3	W50-75803	sacrum to pubic	1
4	W50-75804	sacrum to upper leg	2
5	W50-75805	upper leg to lower leg	2
6	W50-75806	torso to external ground	1

4.2 Grounding procedures

The WorldSID dummy should be grounded as follows.

1) Attach cable 1 to the right side rear mounting screw of the upper neck load cell as shown in Figure 4.1.

Figure 4.1 — Cable attachment to the upper neck load cell

2) Route cable one with the other cables around the neck and through the spine box as shown in Figure 4.2.

Figure 4.2 — Spine box cable routing

3) Attach the other end of cable 1 and one end of cable 2 to the spine box with a SHCS M5 x 6 mm as shown in Figure 4.3. In addition, attach one end of cable 6 (not shown) to this same screw.

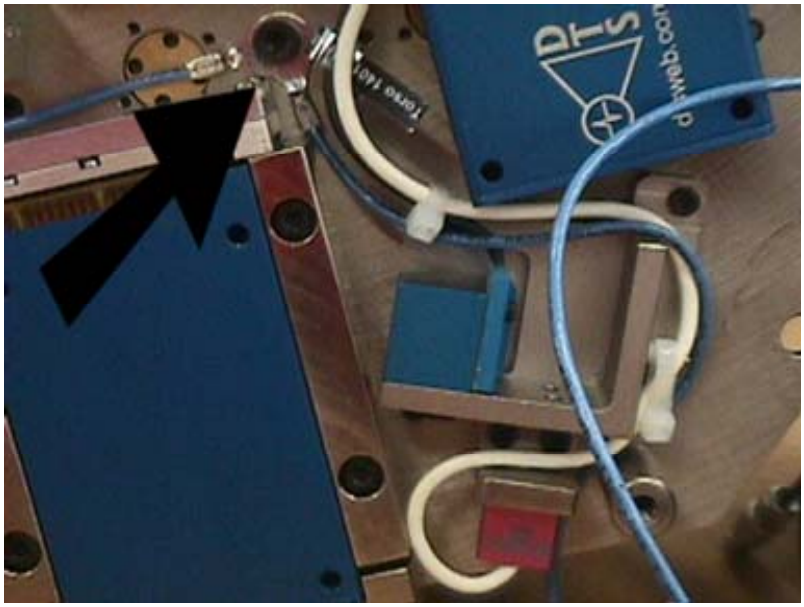


Figure 4.3 — Spine box cable attachment

4) Route cable 2 through the spine box as shown in Figure 4.4.

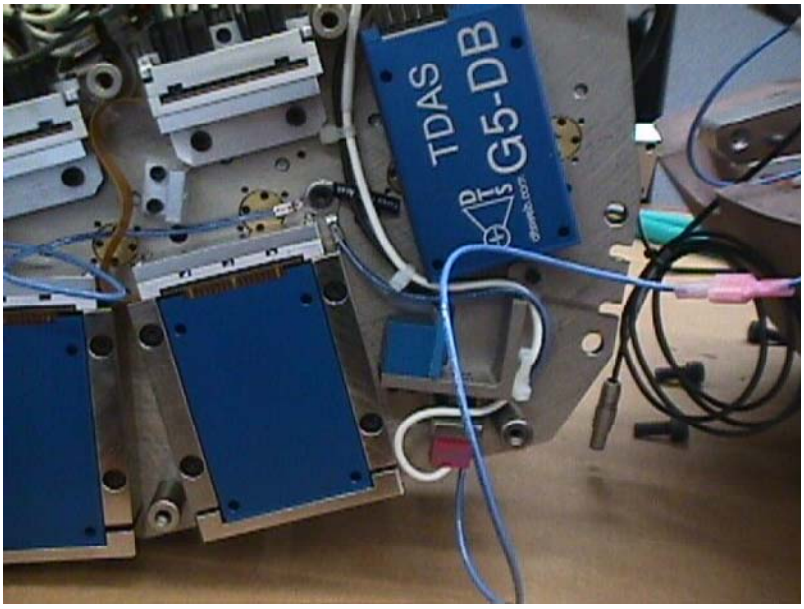


Figure 4.4 — Spine box cable attachment

5) Attach the other end of cable 2 to the front lumbar to sacrum attachment screw on the non-struck side along with one end of cable 3 and one end of cable 4 as shown in Figure 4.5.

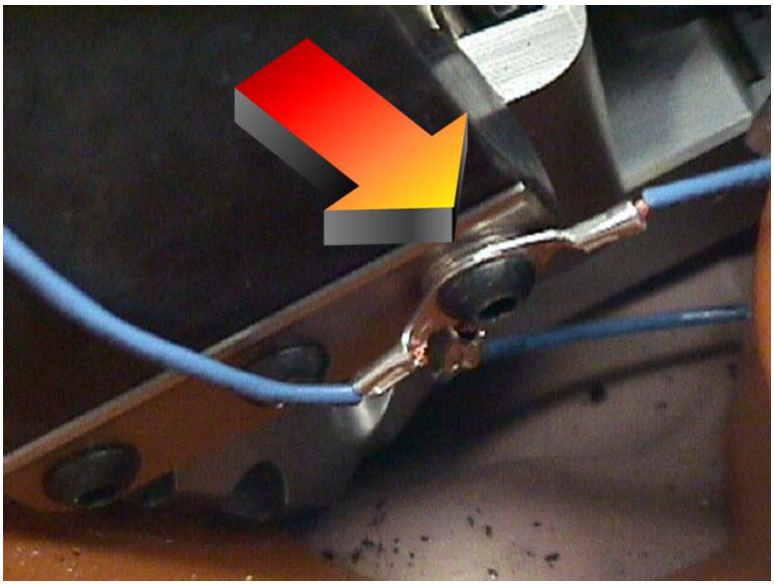


Figure 4.5 — Lumbar cable attachment

6) Attach the other end of cable 3 to the top inner pubic load cell attachment bolt on the non-struck side as shown in Figure 4.6.

Figure 4.6 — Pelvic load cell cable attachment

7) Attach the other end of cable 4 to the non-struck side knee clevis using a BHCS M3 x 6 mm along with one end of cable 5 as shown in Figure 4.7.

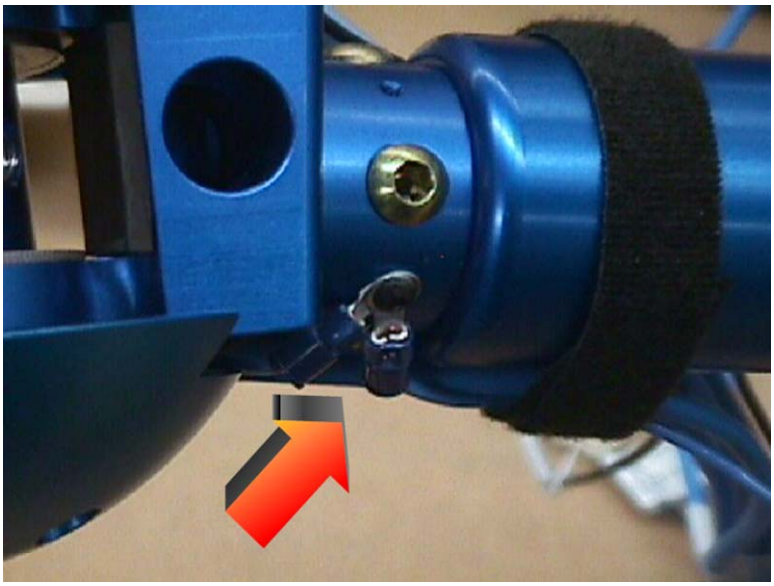


Figure 4.7 — Knee cable attachment

8) Attach one end of the second cable 4 to the front lumbar to sacrum attachment screw on the struck side as shown in Figure 4.8.

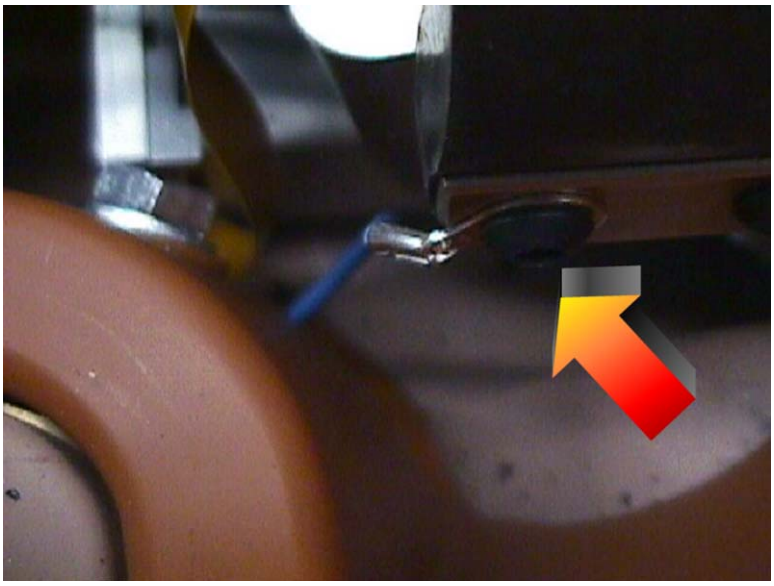


Figure 4.8 — Cable attachment

9) Attach the other end of the second cable 4 to the struck side knee clevis using a BHCS M3 x 6 mm along with one end of the second cable 5 as shown in Figure 4.7.

10) For each of the legs, attach the other end of cable 5 to the strain relief attachment screw just below the upper tibia load cell as shown in Figure 4.9.

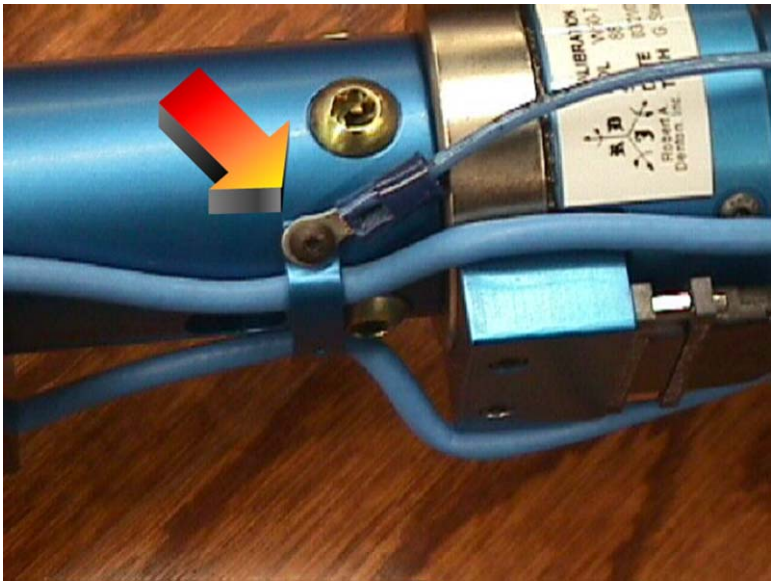


Figure 4.9 — Tibia cable attachment

11) Attach the other end of cable 6 to an off dummy earth ground point. The same ground point should be used as for the DAS.

Section 5

5. WORLDSID TEMPERATURE INFORMATION

5.1 Temperature sensitivity of WorldSID

It is believed that the WorldSID components with the most sensitivity to temperature change are the inner ribs, as related to the energy absorbing material which covers the inner ribs.

5.2 Monitoring of temperature variations of WorldSID

As specified in Section 2, the recommended chest cavity air temperature operating range for the WorldSID is 20,6 to 22,2 degrees C. This was based on a study of the influence of temperature variations on the performance of the shoulder, thorax, abdomen and pelvis.

In addition, in order to quantify air temperature variations within the chest cavity, internal air temperatures were measured by placing a thermocouple on each of the inner ribs in the locations shown in Figure 5.1, which are in the vicinity of typical maximum bending stress. From the results, it was determined that the air temperature in the chest cavity has a relatively uniform distribution.

The WorldSID has a permissible (i.e., optional) chest cavity air temperature sensor mounted on the non-impact side of the spine box which can be read directly through the TDAS G5 hardware and software. This temperature sensor has an internal log function where it stores temperature variation data from the last 24 hours.

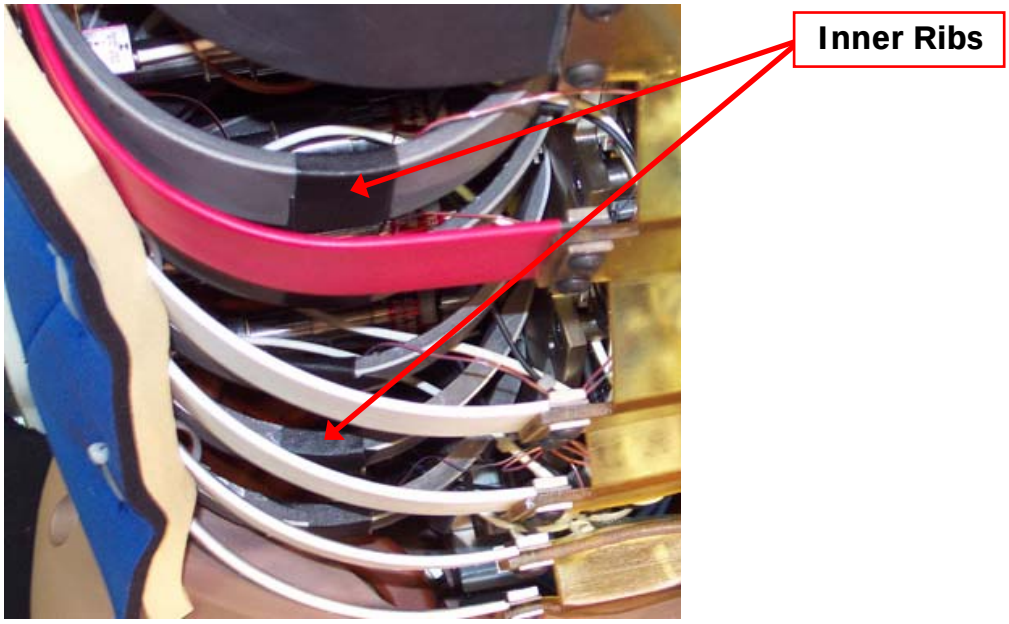


Figure 5.1 — Location of temperature sensors used for internal temperature survey

5.3 Effect of internal DAS on dummy temperature

Extensive testing was performed to determine the effects on internal air temperature due to operation of the permissible internal TDAS G5 system. Based on this testing, changes were made to the pre-production TDAS G5 design so that it would draw much less power. The internal DAS heating was compared to heating created by running a typical external DAS with 10 V excitation and with the same set of sensors. A summary of the results is given in Table 5.1. For the optional DTS TDAS control, refer to Annex D regarding the low power mode intended to mitigate temperature concerns due to prolonged sensor excitation.

Table 5.1 — Effect of internal and external DAS on WorldSID internal air temperature

Condition	Temperature increase in thorax
Production TDAS G5 with 5 V excitation, system in fully armed mode	1,34 degrees C per hour
External DAS with 10 V excitation	1,32 degrees C per hour

5.4 Practical notes for full body testing related to temperature

The following notes are provided for the information of users performing full body testing with the WorldSID:

- Similar temperature increases occur when the same set of sensors is used, regardless of whether a typical external DAS or the internal TDAS G5 system is used.

- Since the temperature specification is 20,6 to 22,2 degrees C, the dummy can be temperature soaked near the lower end of this range to allow for heating during a test.

- Once the internal or external DAS is armed and sensor excitations are powered, it is recommended that the test be performed within 30 minutes in order to minimize temperature effects (i.e., there is an approximately 0,7 degrees C increase in 30 minutes).

- If the permissible internal TDAS G5 system is used, the software will provide a real time internal chest cavity air temperature measurement to the user. The previous 24 hour temperature time history will also be automatically downloaded with the test data.

- If a different temperature sensor and recording method is used, it is recommended that the internal chest cavity air temperature be measured and monitored during the test.

Section 6

6. RECOMMENDED WORLDSID SEATING PROCEDURE

6.1 Placement procedures for the driver seat position

6.1.1 General

The WorldSID should be positioned following the IIHS/UMTRI seating procedure. Guidelines may be downloaded from http://www.highwaysafety.org/ vehicle_ratings/tech_info.htm.

6.1.2 Electronic spreadsheets

Accompanying templates for position calculations may be downloaded from http://www.highwaysafety.org/ vehicle_ratings/tech_info.htm.

6.2 Placement procedures for the rear seat position

6.2.1 ATD preparation

Adjust the dummy as recommended in Section 1. This adjustment should include joint placement, like the neck bracket, and joint torque specifications for the arms and legs.

6.2.2 Position the seat

If the seat position is adjustable on a track in the fore/aft direction, place the seat in the rearmost locking position.

6.2.3 Dummy placement

6.2.3.1 Install the dummy into the vehicle such that the midsagittal plane is vertical and coincident with the seat centreline. The buttocks and torso should be in contact with the seat back.

6.2.3.2 Adjust the knee position such that the distance between the knees is 330 mm measured at the knee centrelines. Alternatively, the knee separation distance can be measured from the inside edge of the knee and placed 102 mm from the seat centreline.

If either knee of the dummy is in contact with the vehicle interior, rotate the entire contacting leg(s) at the hip joint away from the obstruction until no contact occurs. Record any variation in the knee separation distance.

6.2.3.3 Place both feet with the heel on the floor pan and as far forward as permitted by foot contact, thigh-cushion contact or leg contact with the forward seat structure. For the rotation of the ankle joint, allow the feet to remain in a neutral position. Align the feet parallel to the vehicle centreline.

6.2.3.4 Rear seats with adjustable seat backs.

6.2.3.5 Fully recline the seat back.

6.2.3.6 Hold the ATD's thighs down and push rearward on the upper torso to maximize the ATD's pelvic angle.

6.2.3.7 While holding the thighs in place, rotate the ATD torso forward until the torso recline angle (the angle of a side view line from the ATD H-point to the head's center of gravity) is set to 12 degrees ± 1 degree. While supporting the ATD, rotate the seat back forward until the ATD torso is supported in the 12 degrees ± 1 degree torso recline position.

6.2.3.8 Gently rock the upper torso relative to the lower torso laterally in a side-to-side motion three times through a ± 5 degree arc (approximately 50 mm side to side) to reduce friction between the ATD and the seat.

6.2.3.9 Reposition feet if necessary.

6.2.3.10 Rotate the arms to 45 degrees ± 1 degree.

6.2.3.11 Rear seats with non-adjustable seat backs.

6.2.3.12 Hold the ATD's thighs down and push rearward on the upper torso to maximize the ATD's pelvic angle.

6.2.3.13 Gently rock the upper torso relative to the lower torso laterally in a side-to-side motion three times through a ± 5 degree arc (approximately 50 mm side to side) to reduce friction between the ATD and the seat.

6.2.3.14 Reposition feet if necessary.

6.2.3.15 Rotate the arms to 45 degrees.

6.2.3.16 If applicable place the adjustable head restraint such that the vertical centerline of the head restraint is aligned with the c.g. of the dummy head.

7. Mechanical Requirements and Certification Test Procedures for WorldSID

7.1 Head

7.1.1 General description

The head assembly shall consist of the components and assemblies listed in head assembly drawing W50-10000.pdf.

7.1.2 Certification specification

When assembled according to Section 1 and tested using the procedure specified in 7.1.3, the head assembly shall meet the specifications given in Table 7.1.

Table 7.1 — WorldSID head certification specifications

Frontal drop	
Variable	Absolute value
Peak resultant acceleration (G)	225 to 275
Peak lateral acceleration (a_Y) (G)	< 15
Maximum percentage, subsequent-to-main peak (%)	< 10
Lateral drop	
Variable	Absolute value
Peak resultant acceleration at CG (G)	99 to 121
Peak longitudinal acceleration (a_X) (G)	< 15
Maximum percentage, subsequent-to-main peak (%)	< 10

7.1.3 Certification test procedures

7.1.3.1 Principle

Certify the dynamic response of a head assembly by performing a 200 mm lateral drop on each side of the head and a 376 mm drop on the forehead.

7.1.3.2 Apparatus

- 49 CFR Part 572, Subpart E, horizontal head impact surface
  - chrome plated rigidly supported horizontal steel plate
  - 50,8 mm x 610 mm x 610mm
  - 8 – 80 rms micron/mm surface finish
- Head drop tool assembly (drawing W50-82100.pdf)
- Instrumented head assembly (drawing W50-10000.pdf) including the instrumentation insert and upper neck load cell or structural replacement
- Two SHCS M6 x 12

7.1.3.3 Sensors

Use triaxial linear accelerometers as described in Section 1.

7.1.3.4 Preparation

- Expose the head assembly to an environment with a temperature of 21,4 degrees C ± 0,8 degrees C and a relative humidity between 10% and 70% for a period of at least four hours prior to a test.
- Clean the head skin surface and the surface of the impact plate with 1,1,1 trichlorethane or equivalent.
- Install the triaxial accelerometer in the head assembly.

- Install the upper neck load cell, angular accelerometers and dual-axis tilt sensor, or their structural or mass replacements.

- Attach the head drop tool to the bottom of the upper neck load cell or its structural replacement with the two SHCS M6x12. Mount the tool for left or right lateral, or frontal drops as shown in Figures 2, 3, 4 and 5. When mounted for lateral drops, position the head such that its midsagittal plane has an angle of 35° ± 1° with the impact surface and its anterior-posterior axis is horizontal to within 1 degree.

- Suspend the head above the drop table using the head drop tool and a quick release mechanism.

- For lateral tests, position the head so its lowest point is 200 mm ± 0,25 mm above the impact surface and drop the head.

- For a frontal test, position the head so the lowest point on the forehead is 376 mm ± 0,25 mm above the impact surface.

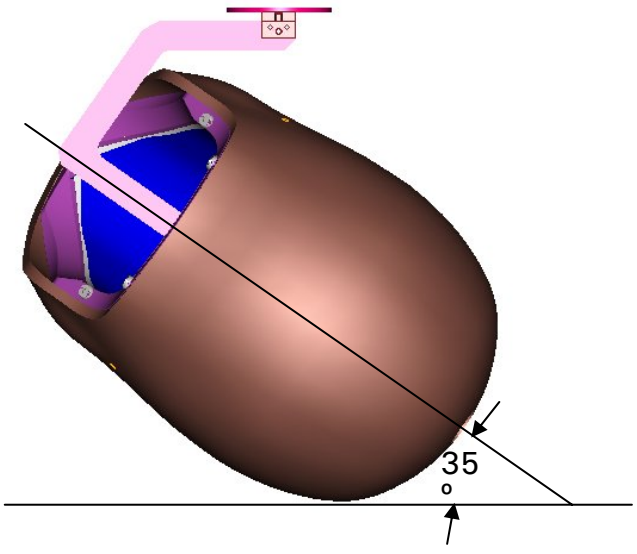


Figure 7.1 — Lateral head drop angle

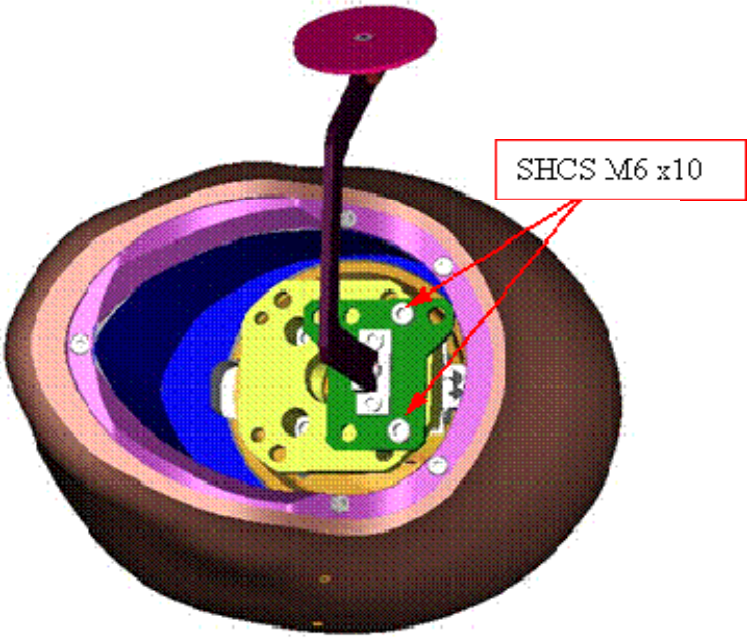


Figure 7.2 — Head bracket installation for lateral drops

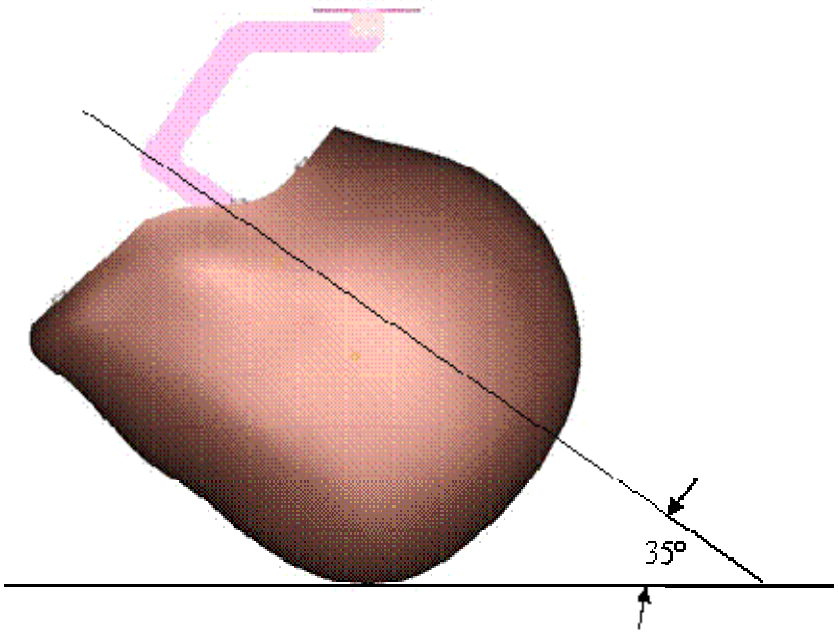


Figure 7.3 — Frontal head drop angle

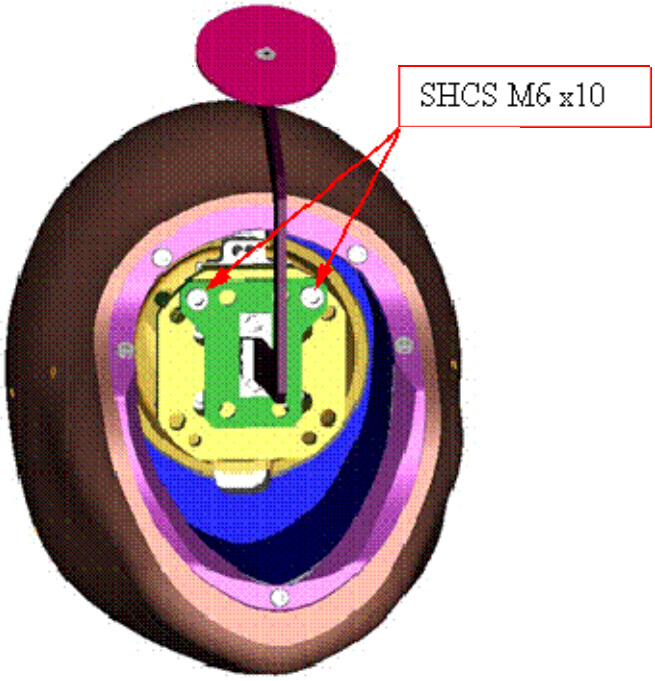


Figure 7.4 — Head bracket installation for frontal drops

7.1.3.5 Procedure

- Record and filter the head accelerations from the triaxial accelerometer according to SAE J211 and ISO 6487 Channel filter class 1000.

- Drop the head onto the rigid plate from the specified height by means that ensure quick release.

- Visually inspect the head for damage to the skin or skull, and note any such damage in the test report.

- Allow at least 2 hours between successive tests on the same head.

7.1.3.6 Test report

Document the results of both the left and right lateral and the frontal drop tests.

7.2 Neck

7.2.1 General description

The neck assembly shall consist of the components and assemblies listed in neck assembly drawing W50-20000.pdf.

7.2.2 Certification specification

When assembled according to Section 1, and tested using the procedure specified in 7.2.3, the neck assembly shall meet the specifications given in Table 7.2.

Table 7.2 — WorldSID neck certification specifications

Variable	Absolute value
Maximum angular displacement of the head form relative to the pendulum, β (degrees)	50 to 61
Decay time of β to 0 degrees (ms)	58 to 72
Peak moment at occipital condyle (Nm)	55 to 68

Peak moment decay time to 0 Nm (ms)[a]	71 to 87
Peak forward potentiometer angular displacement (degrees)	32 to 39
Time of peak forward potentiometer angular displacement (ms)[a]	56 to 68
Peak rearward potentiometer angular displacement, θ_F (degrees)	30 to 37
Time of peak rearward potentiometer angular displacement, θ_R (ms)[a]	56 to 68
a T = 0 s at initial pendulum contact with honeycomb or alternative products which can be shown to lead to the same results.	

7.2.3 Certification test procedures

7.2.3.1 Principle

Certify the dynamic response of the neck assembly by performing lateral pendulum tests.

7.2.3.2 Materials

For the pendulum stop, use aluminium honeycomb, of density 28,8 kg/m^3 ± 4,90 kg/m^3 and dimensions 102,0 mm minimum x 102,0 mm minimum with a thickness along the cells of 76,2 mm ± 4 mm or alternative products which can be shown to lead to the same results.

7.2.3.3 Apparatus

- Neck assembly as specified in 7.2.1.
- WorldSID head form (drawing W50-83000.pdf)
- Neck pendulum apparatus as specified in 49CFR Part 572, Subpart E

7.2.3.4 Sensors

Perform the test using the sensors given in Table 7.3.

Table 7.3 — Sensors for neck assembly

Variable	Sensor	Performance
Pendulum acceleration	Single axis accelerometer Endevco 7231C-750	SAE J2570
Pendulum velocity	Not specified	Resolution 0,02 m/s or better
Angular displacement of forward pendulum-to-head form sliding rod, positive when doing a right side impact (θ_F)	Angular potentiometer	SAE J2570
Angular displacement of rearward pendulum-to-head form sliding rod, positive when doing a right side impact (θ_R)	Angular potentiometer	SAE J2570
Angular displacement of head form about forward pendulum-to-head form sliding rod, positive when doing a right side impact (θ_H)	Angular potentiometer	SAE J2570
Neck moment M_x	Upper load cell Denton W50-71000	SAE J2570
Neck force F_y	Upper load cell Denton W50-71000	SAE J2570

7.2.3.5 Preparation

Expose the neck to the conditions specified in Table 7.4 for at least four hours prior to a test.

Table 7.4 — Neck test preconditions

Variable	Specification
Temperature (degrees C)	21,4 ± 0,8
Relative humidity (%)	40 ± 30

- Attach the top of the neck to the head form.

- Attach the bottom of the neck to the pendulum interface. Ensure that the screws do not protrude into the neck rubber as this may influence the response. If the screws are too long, insert washers under the head of the screw in order to prevent rubber contact. Mount the pendulum interface to the pendulum such that the head

form's midsagittal plane is vertical and is perpendicular to the plane of motion of the pendulum's longitudinal centreline.

- Slide the carbon fiber rods through the potentiometer housings on the pendulum. First slide the pivot of the potentiometer closest to the pendulum over the central steel rod in the head form, then install the small spacer ring and the second pivot. Carefully tighten the second pivot.

7.2.3.6 Procedure

- Record and filter the data according to ISO 6487 or SAE J211 Channel filter class 1000.

- Release the pendulum and allow it to fall freely from a height such that the velocity at impact is 3,4 m/s ± 0,1 m/s, measured at the centre of the pendulum mounted accelerometer.

- Decelerate the pendulum arm using the 28,8 kg/m^3 aluminium honeycomb or alternative products which can be shown to lead to the same results, to achieve the pendulum pulse given in Table 7.5.

- Allow the neck to flex without impact of the head or neck with any object other than the pendulum arm.

- Conduct the test such that the time between raising the pendulum and releasing it does not exceed 5 minutes.

- Conduct the test such that the time between any tests on the same WorldSID neck is not less than 30 minutes.

Table 7.5 — Pendulum arm deceleration pulse

Variable	Value
Velocity change at 4 ms[a]	0,77 m/s to 1,04 m/s
Velocity change at 8 ms[a]	1,60 m/s to 2,16 m/s
Velocity change at 12 ms[a]	2,43 m/s to 3,29 m/s
a T = 0 s at initial contact with honeycomb or alternative products which can be shown to lead to the same results.	

7.2.3.7 Calculation procedures

- Filter the data according to ISO 6487 or SAE J211, as given in Table 7.6.

- Integrate the filtered and adjusted acceleration time histories.

- Calculate the flexion angle of the head form using the following equation:

$$\beta = \theta_F + \theta_H$$

where:

β = angular displacement of head form relative to the pendulum

θ_F = Angular displacement of forward pendulum-to-head form sliding rod, positive when doing a right side impact

θ_H = Lateral angular displacement of head form about forward pendulum-to-head form sliding rod, positive when doing a right side impact

- After performing this calculation, digitally filter all angular displacements using ISO 6487 or SAE J211 CFC 180

- Calculate the moment about the occipital condyle as $M_{OCx} = M_X + (F_y)$ x (0,0195m), where the M_X and F_y polarities are in accordance with the SAE J211 sign convention.

Table 7.6 — Filter specification for neck test

Variable	Filters[a]
Pendulum acceleration	CFC 60
Pendulum velocity	No digital filtering
Angular displacement of forward rod (θ_F)	CFC 1000
Angular displacement rear rod (θ_R)	CFC 1000
Angular displacement of head form (θ_H)	CFC 1000
Neck moment M_x	CFC 600
Neck force F_y	CFC 1000
a ISO 6487 or SAE J211	

7.2.3.8 Test reports

Document the results of the test.

7.3 Thorax/abdomen/shoulder

7.3.1 General description

The thorax/abdomen/shoulder assembly shall consist of the components and assemblies listed in thorax/abdomen/shoulder assembly drawing W50-30000.pdf.

7.3.2 Full body test setup

7.3.2.1 Materials

Use Teflon® sheets of sufficient size to cover seat.

7.3.2.2 Apparatus

- H-Point tool (drawing W50-82500.pdf)
- Tilt sensor or inclinometer
- Dummy certification test bench

- Seat and back Teflon® sheets described in Annex E.1

7.3.2.3 Preparation

Expose the dummy, clothed in its suit, to the conditions given in Table 7.7 for at least four hours prior to a test.

Table 7.7 — Dummy full body test preconditions

Variable	Value
Temperature (degrees C)	21,4 ± 0,8
Relative humidity (%)	40 ± 30

7.3.2.4 Setup procedure

- Install the H-point tool.

- Install dual axis tilt sensors in the head, thorax and pelvis to check the angles about x and y direction.

- Cover the seat back and base with Teflon® sheets.

- Seat the dummy on the rigid seat as shown in Figure 7.5 and Figure 7.6.

- Place the dummy on the seat and position it using either mechanical measurements on a dummy component or tilt sensors to verify the positions. The relationship between mechanical angle measurements and the tilt sensors are given in Table 7.8.

- Position the dummy according to the criteria given in Table 7.9.

Table 7.8 — Relationship between mechanical measurement indicators and the tilt sensors

Location	Mechanical reference	Tilt sensor (angular displacement about the noted axis)
Head zero	Landmark on head is horizontal	X : 0°, Y : 0°
Thorax zero	Top of the lower neck bracket is horizontal	X : 0°, Y : 0°
Pelvis zero	X angle zero degree H-point tool oriented at 45° below horizontal (Y)	X : 0°, Y : 14,5°

Table 7.9 — Dummy set up criteria

Variable	Criteria	Sensor readings
Thorax angle	0° ± 2°	
Pelvic orientation	5° ± 2°[a]	This pelvic orientation is coincident with H-point tool at 40° ± 2° below horizontal, and a pelvic tilt sensor at 19,5° ± 2°
Distance between knee centres	279 mm ± 50 mm	

[a] Due to the low friction of the Teflon® pieces, the dummy is not able to sit at zero pelvis angle. Five degrees is an achievable angle on the test bench.

Figure 7.5 — Front view of setup for full dummy certification tests

Figure 7.6 — Side view of setup for full dummy certification tests

Figure 7.7 — Using an inclinometer with the H-point tool to check pelvis angle

7.3.3 Shoulder

When assembled according to Section 1, and tested using the procedure specified in 7.3.2 and 7.3.3.1, the shoulder assembly shall meet the specifications given in Table 7.10.

Table 7.10 — WorldSID shoulder certification specifications

Variable	Absolute value
Peak pendulum force (kN)	2,6 to 3,3
Peak shoulder rib deflection (mm)	35 to 44

7.3.3.1 Shoulder certification test procedures

7.3.3.1.1 Principle

Perform a test involving a lateral impact to the shoulder in order to certify the dynamic response of the shoulders.

7.3.3.1.2 Apparatus

Use 49 CFR Part 572, subpart E Hybrid III 50th percentile adult male dummy pendulum (23,4 kg, 152,4 mm face diameter).

7.3.3.1.3 Sensors

Install instrumentation to obtain data for the items given in Table 7.11.

Table 7.11 — Sensors for shoulder test

Variable	Sensor	Performance
Peak pendulum acceleration (G)	See Table 7.3	Per SAE J2570
Peak shoulder rib deflection (mm)	IR-TRACC	See sensor specification details on electronic drawing number IF-363
Impact velocity (m/s)	Not specified	Resolution 0,02 m/s or better

7.3.3.1.4 Procedure

- Set up the dummy in standard test posture as described in 7.3.2 with the half arm aligned horizontal on the impact side as shown in Figure 7.8.

- Align the pendulum centreline with the centreline of the shoulder y-axis rotation point.

- Raise the pendulum to achieve a 4,3 m/s ± 0,1 m/s impact velocity.

- Release the pendulum to impact the dummy.

Figure 7.8 — Shoulder test, dummy and arm position

7.3.3.1.5 Calculation procedures and expression of results

- Filter the data according to ISO 6487 or SAE J211, as given in Table 7.12.

- Calculate the pendulum impactor force by multiplying the pendulum acceleration time history by the measured impactor mass.

- Graph the time histories of impactor force and shoulder deflection.

Table 7.12 — Filter specifications for shoulder test

Variable	Filter
Pendulum acceleration (G)	CFC 180
Shoulder deflection (mm)	CFC 600

7.3.3.1.6 Test reports

Document the results of the test.

7.3.4 Thorax with half arm

When assembled according to Section 1, and tested using the procedure specified in 7.3.2 and 7.3.4.1, the thorax with half-arm assembly shall meet the specifications given in Table 7.13.

Table 7.13 — WorldSID thorax with half-arm certification specifications

Variable	Absolute value
Peak pendulum force (kN)	4,7 to 6,4
Peak T4 acceleration along y axis (G)	24 to 33
Peak T12 acceleration along y axis (G)	20 to 28
Peak thorax rib 1 deflection (mm)	35 to 47
Peak thorax rib 2 deflection (mm)	42 to 57
Peak thorax rib 3 deflection (mm)	40 to 54

7.3.4.1 Thorax with half arm certification procedures

7.3.4.1.1 Principle

Perform a test involving a lateral impact to the thorax with the half arm in order to certify the dynamic response of the thorax.

7.3.4.1.2 Apparatus

Use 49 CFR Part 572, subpart E Hybrid III 50th percentile adult male dummy pendulum (23,4 kg, 152,4 mm face diameter).

7.3.4.1.3 Sensors

Install instrumentation in order to obtain data for the items given in Table 7.14.

Table 7.14 — Sensor specifications for thorax with half arm test

Variable	Sensor	Performance
Peak pendulum acceleration (G)	See Table 7.3	SAE J2570
Peak upper spine (T4) y-axis acceleration (G)	Triaxial linear accelerometer Endevco 7268C-2000M1	SAE J2570
Peak lower spine (T12) y-axis acceleration (G)	Triaxial linear accelerometer Endevco 7268C-2000M1	SAE J2570
First, second and third thorax rib deflections (mm)	IR-TRACC Model IF-363	See sensor specification details on electronic drawing number IF-363
Impact velocity (m/s)	Not specified	Resolution 0,02 m/s or better

7.3.4.1.4 Procedure

- Set up the dummy in standard test posture as described in 7.3.2 with the half arm parallel to the thorax

- Align the pendulum centreline with the centreline of the middle thorax rib

- Raise the pendulum to achieve a 6,7 m/s ± 0,1 m/s impact velocity

- Release the pendulum to impact the dummy

7.3.4.1.5 Calculation procedures and expression of results

- Filter the data according to ISO 6487 or SAE J211, as given in Table 7.15

- Calculate the pendulum impactor force by multiplying the pendulum acceleration time history by the measured impactor mass

- Plot the time histories of impactor force, T4 and T12 y-axis accelerations, and deflections of thorax ribs 1, 2, and 3

Table 7.15 — Filter specifications for thorax with half arm test

Variable	Filter
Peak pendulum acceleration (G)	CFC 180
Peak T4 y-axis acceleration (G)	CFC 180
Peak T12 y-axis acceleration (G)	CFC 180
Peak thorax rib 1 deflection (mm)	CFC 600
Peak thorax rib 2 deflection (mm)	CFC 600
Peak thorax rib 3 deflection (mm)	CFC 600

7.3.4.1.6 Test reports

Document the results of the test.

7.3.5 Thorax without arm

When assembled according to Section 1, and tested using the procedure specified in 7.3.2 and 7.3.5.1, the thorax without arm assembly shall meet the specifications given in Table 7.16.

Table 7.16 — WorldSID thorax without arm certification specifications

Variable	Absolute value
Peak pendulum force (kN)	3,2 to 3,9
Peak T4 acceleration along y axis (G)	12 to 17
Peak T12 acceleration along y axis (G)	15 to 21
Peak thorax rib 1 deflection (mm)	34 to 43
Peak thorax rib 2 deflection (mm)	34 to 43
Peak thorax rib 3 deflection (mm)	34 to 43

7.3.5.1 Thorax without arm certification procedures

7.3.5.1.1 Principle

Perform a test involving a lateral impact to the thorax without the arm in order to certify the dynamic response of the thorax.

7.3.5.1.2 Apparatus

Use 49 CFR Part 572, subpart E Hybrid III 50th percentile adult male dummy pendulum (23,4 kg, 152,4 mm face diameter).

7.3.5.1.3 Sensors

Install instrumentation to obtain data for the items given in Table 7.17.

Table 7.17 — Sensor specifications for thorax without arm test

Variable	Sensor	Performance
Peak pendulum acceleration (G)	See Table 7.3	SAE J2570
Peak upper spine (T4) y-axis acceleration (G)	Triaxial linear acceleration Endevco 7268C-2000M1	SAE J2570
Peak lower spine (T12) y-axis acceleration (G)	Triaxial linear acceleration Endevco 7268C-2000M1	SAE J2570
First, second and third thorax rib deflections (mm)	IR-TRACC Model IF-363	See sensor specification details on electronic drawing number IF-363
Impact velocity (m/s)	Not specified	Resolution 0,02 m/s or better

7.3.5.1.4 Procedure

- Set up the dummy without arm in standard test posture as described in 7.3.2.

- Raise the arm to a vertical orientation as shown in Figure 7.9.

- Align the pendulum centreline with the centreline of the middle thorax rib.

- Raise the pendulum to achieve a 4,3 m/s ± 0,1 m/s impact velocity.

- Release the pendulum to impact the dummy.

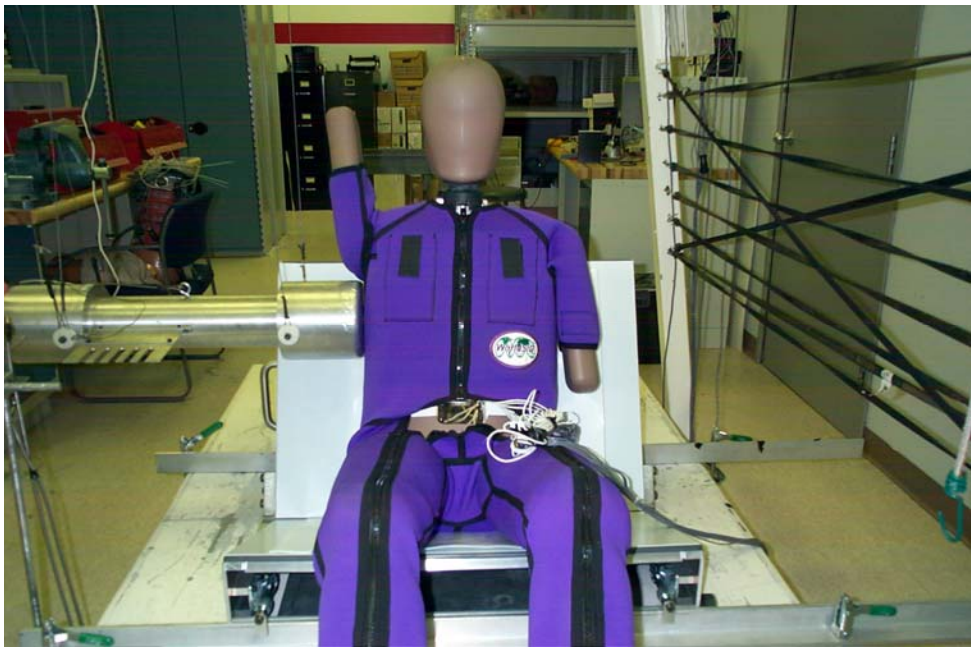


Figure 7.9 — Thorax test without arm, dummy and arm position

7.3.5.1.5 Calculation procedures and expression of results

- Filter the data according to ISO 6487 or SAE J211, as given in Table 7.18.

- Calculate the pendulum impactor force by multiplying the pendulum acceleration time history by the measured impactor mass.

- Graph the time histories of impactor force, T4 and T12 y-axis accelerations, and deflections of thorax ribs 1, 2, and 3.

Table 7.18 — Filter specifications for thorax without half arm test

Variable	Filter
Peak pendulum acceleration (G)	CFC 180
Peak T4 y-axis acceleration (G)	CFC 180
Peak T12 y-axis acceleration (G)	CFC 180
Peak thorax rib 1 deflection (mm)	CFC 600
Peak thorax rib 2 deflection (mm)	CFC 600
Peak thorax rib 3 deflection (mm)	CFC 600

7.3.5.1.6 Test reports

Document the results of the test.

7.3.6 Abdomen

When assembled according to Section 1, and tested using the procedure specified in 7.3.2 and 7.3.6.1, the abdomen without arm assembly shall meet the specifications given in Table 7.18.

Table 7.19 — WorldSID abdomen certification specifications

Variable	Absolute value
Peak abdomen rib 1 deflection (mm)	33 to 41
Peak abdomen rib 2 deflection (mm)	31 to 39
Peak pendulum force (kN)	2,6 to 3,3
Peak T12 acceleration along y axis (G)	15 to 20

7.3.6.1 Abdomen test certification procedures

7.3.6.1.1 Principle

Perform a test involving a lateral impact to the abdomen in order to certify the dynamic response of the abdomen ribs.

7.3.6.1.2 Apparatus

Use the following items:

- 49 CFR Part 572, subpart E Hybrid III 50th percentile adult male pendulum (23,4 kg, 152,4 mm face diameter).

- Simulated armrest consisting of a rigid hardwood block as given in Table 7.20 attached to the impact face of the pendulum. The centreline of the armrest simulator shall be aligned with the centreline of the pendulum.

Table 7.20 — Simulated armrest specifications

Variable	Value
Width (mm)	150 ± 0,5
Height (mm)	70 ± 0,5
Depth (mm)	60 ± 0,5
Corner radius (mm)	10 ± 1
Mass (Kg)	1,00 ± 0,01

7.3.6.1.3 Sensors

Install instrumentation in order to obtain data for the items given in Table 7.21.

Table 7.21 — Sensor specifications for abdomen test

Variable	Sensor	Performance
Pendulum acceleration (G)	See Table 7.3	SAE J2570
Lower spine (T12) y-axis acceleration (G)	Triaxial linear accelerometer Endevco 7268C-2000M1	SAE J2570
Abdomen rib 1 and 2 deflections (mm)	IR-TRACC Model IF-363	See sensor specification details on electronic drawing number IF-363
Impact velocity (m/s)	Not specified	Resolution 0,02 m/s or better

7.3.6.1.4 Procedure

- Set up the dummy in standard test posture as described in 7.3.2 with the half arm in the driving posture as shown in Figure 7.5.

- Align the wood block face so it is aligned with and parallel to the middle of the two abdomen ribs.

- Place the wood block in contact with the side of the dummy.

- Raise the pendulum to achieve a 4,3 m/s ± 0,1 m/s impact velocity.

- Release the pendulum to impact the dummy.

7.3.6.1.5 Calculation procedures and expression of results

- Filter the data according to ISO 6487 or SAE J211-1, as given in Table 7.22.

- Calculate the pendulum impactor force by multiplying the pendulum acceleration time history by the combined measured mass of the pendulum and armrest simulator.

- Graph the time histories of impactor force, T12 y-axis acceleration, and deflections of abdomen ribs 1 and 2.

Table 7.22 — Filter specifications for abdomen test

Variable	Filter
Pendulum acceleration (G)	CFC 180
T12 y-axis acceleration (G)	CFC 180
Abdomen rib 1 deflection (mm)	CFC 600
Abdomen rib 2 deflection (mm)	CFC 600

7.3.6.1.6 Test reports

Document the results of the abdomen test.

7.4 Lumbar spine and pelvis

7.4.1 General description

The lumbar spine and pelvis assembly shall consist of the components and assemblies listed in lumbar spine and pelvis assembly drawing W50-40000.pdf.

7.4.2 Certification

When assembled according to Section 1, and tested using the procedure specified in 7.3.2 and 7.6.3, the pelvis assembly shall meet the specifications given in Table 7.23.

Table 7.23 — WorldSID pelvis certification specifications

Variable	Absolute value
Peak acceleration along y axis (G)	41 to 51
Peak pelvis pendulum force (kN)	6,3 to 7,8
Peak T12 acceleration along y axis (G)	10 to 14

7.4.3 Pelvis certification test procedure

7.4.3.1 Principle

Perform a test involving a lateral impact to the pelvis in order to certify the dynamic response of the pelvis.

7.4.3.2 Apparatus

Use 49 CFR Part 572, subpart E Hybrid III 50th percentile adult male dummy pendulum (23,4 kg, 152,4 mm face diameter).

7.4.3.3 Sensors

Install instrumentation to obtain data for the items given in Table 7.24.

Table 7.24 — Sensor specifications for pelvis test

Variable	Sensor	Performance
Pendulum acceleration (G)	See Table 7.3	SAE J2570
Lower spine (T12) y-axis acceleration (G)	Triaxial linear accelerometer Endevco 7268C-2000M1	SAE J2570
Pelvis acceleration (G)	Triaxial linear accelerometer Endevco 7268C-2000M1	SAE J2570
Impact velocity (m/s)	Not specified	Resolution 0,02 m/s or better

7.4.3.4 Procedure

- Set up the dummy with half arm in standard test posture as described in 7.3.2.

- Align the pendulum centreline with the H-point.

- Raise the pendulum to achieve a 6,7 m/s ± 0,1 m/s impact velocity.

- Release the pendulum to impact the dummy.

7.4.3.5 Calculation procedures and expression of results

- Filter the data according to ISO 6487 or SAE J211-1, as given in Table 7.24.

- Calculate the pendulum impactor force by multiplying the pendulum acceleration time history by the measured impactor mass.

- Graph the time histories of impactor force, pelvis and T12 y-axis accelerations.

Table 7.25 — Filter specifications for pelvis test

Variable	Filter
Pendulum acceleration (G)	CFC 180
T12 y-axis accleration (G)	CFC 180
Pelvis y-axis acceleration (G)	CFC 180

7.4.3.6 Test reports

Document the results of the pelvis test.

Annex A

FASTENER TORQUE VALUES

Table A.1 — Screw torques

Screw Type	Screw Size	Torque[a]	
		Nm	in-lbf
SHCS	M2 X 0,4	1	9
SHCS	M2.5 X 0,45	1	9
SHCS	M4 X 0,7	4	35
SHCS	M5 x 0,8	8	71
SHCS	M6 x 1	14	124
SHSS (hand and wrist pivot screw)	M6 X 25 mm	3	27
BHCS	M3 X 0,5	1	9
BHCS	M4 X 0,7	3	27
Modified BHCS (p/n: W50-61042)	M6 x 1	10	89
BHCS ("Z" pivot screw)	M6 X 1	2[b]	18
BHCS (Elbow pivot screw)	M10 X 1,5	3[b]	27
FHCS	M4 X 0,7	3	27
LWSHCS	M3 X 0,5	3	27
LWSHCS	M6 X 1	15	133
CPSSS	M3 x 0,5	1	9
CPSSS	M6 x 1	7	62
SSCP	M4 X 0,7	2	18
SSCP	M6 X 1	7	62
SSFP	M4 X 0,7	2	18
SSNT	M3 x 0,5	1	9
SSNT	M4 X 0,7	2	18
SSNT ('Z' pivot screw)	M6 X 1	3[b]	27
SSHDP	M6 X 1	8	71

[a] Torques based on manufacturer's recommendation of 50% of yield strength.

[b] Used for 1-to-2 G-setting. Torque may vary with components.

Annex B

FASTENER ABBREVIATIONS

Table B.1 gives a summary of fasteners abbreviations, descriptions and ISO references, for the convenience of users of this document.

Table B.1 — Summary of fasteners abbreviations, descriptions and ISO references

Abbreviations	Descriptions	ISO references
BHCS	Button head cap screw	ISO 7380
Cheese screw	Cheese head screw	ISO 1207
CPNT	Cone point nylon tip set screw	-
CPSS	Cone point set screw	ISO 4027
CPSSS	Cone point socket set screw	ISO 4027
FHCS	Flat head cap screw	ISO 10642
LHSHCS	Low head socket head cap screw	-
NTSS	Nylon tip set screw	
SHCS	Socket head cap screw	ISO 4762
SHSS	Socket head shoulder screw	ISO 7379
SSCP	Set screw cup point	ISO 4029
SSFP	Set screw flat point	ISO 4026
SSHDP	Set screw half dog point	-
SSNP	Set screw nylon point	-
SSNT	Set screw with nylon tip	-

Annex C

OVERVIEW OF AN EXAMPLE INTERNAL DATA ACQUISITION SYSTEM

C.1 General

This annex gives an overview of the main functional components of and cable pinout scheme for the WorldSID G5 DAS which is an example internal data acquisition system for the WorldSID.

Users of an internal data acquisition system should contact the manufacturer to request operating procedures and specifications for the system.

WorldSID Task Group document N397 contains some geometric, mass and performance characteristics for permissible internal data acquisition systems.

The WorldSID G5 DAS is an example of a system which conforms to these normative specifications and was used in the 11 pre-production WorldSIDs.

C.2 System components

The basic components of the WorldSID G5 DAS system are shown in Figure C.1. Table C.1 lists parts and part numbers. A description of each item is given below for the convenience of users of this example system.

Table C.1 — WorldSID G5 DAS parts list

Description	Part number
TDAS G5 Module	TDAS5-M32
TDAS G5-DB	TDAS5-DB
TDAS G5 DB Dog Bone connector clamp	TDAS5-DBCON-CL
TDAS G5-DB Dummy exit cable	TDAS5-C-DBDE
Dummy exit to TDAS status box cable	TDAS5-C-DESB
Ethernet communication cable: from status box to PC	TDAS5-ETH-SBPC
Wireless Ethernet programming cable	TDAS5-C-WEP
Wireless Ethernet jumper plug	TDAS5-P-WEJ
TDAS status box	TDAS5-SB
Antenna	TDAS5-SBAN
TDAS power supply	TDAS5-PS
TDAS G5 User's manual and software	TDAS5-Soft
Allen wrench	TDAS5-Wrench
Rugged instrument case, Pelican 1550	TDAS5-1550
2,4 Amp power supply with 4-Pin Lemo connector	TDAS5-PS-2,4Amp

C.3 G5 module

Each G5 module records data from as many as 32 sensors and has sensor ID capabilities. The G5 system installed on the WorldSID pre-production dummies had the provision for mounting five G5 modules on the dummy, two in the spine, one in the pelvis, and one in each upper leg skin. In addition, if needed, additional G5 units can be located in the dummy suit pockets to support full arm sensors. See the manufacturer-supplied G5 module hardware user's manual for additional information.

C.4 G5 docking station

The docking station consists of a mechanical guide and connector for the G5 module, flex cable and sensor input connectors. As specified in the G5 documentation, when attaching a G5 to the docking station the attachment bolt torque should be 1,6 to 1,8 Nm. Additional information

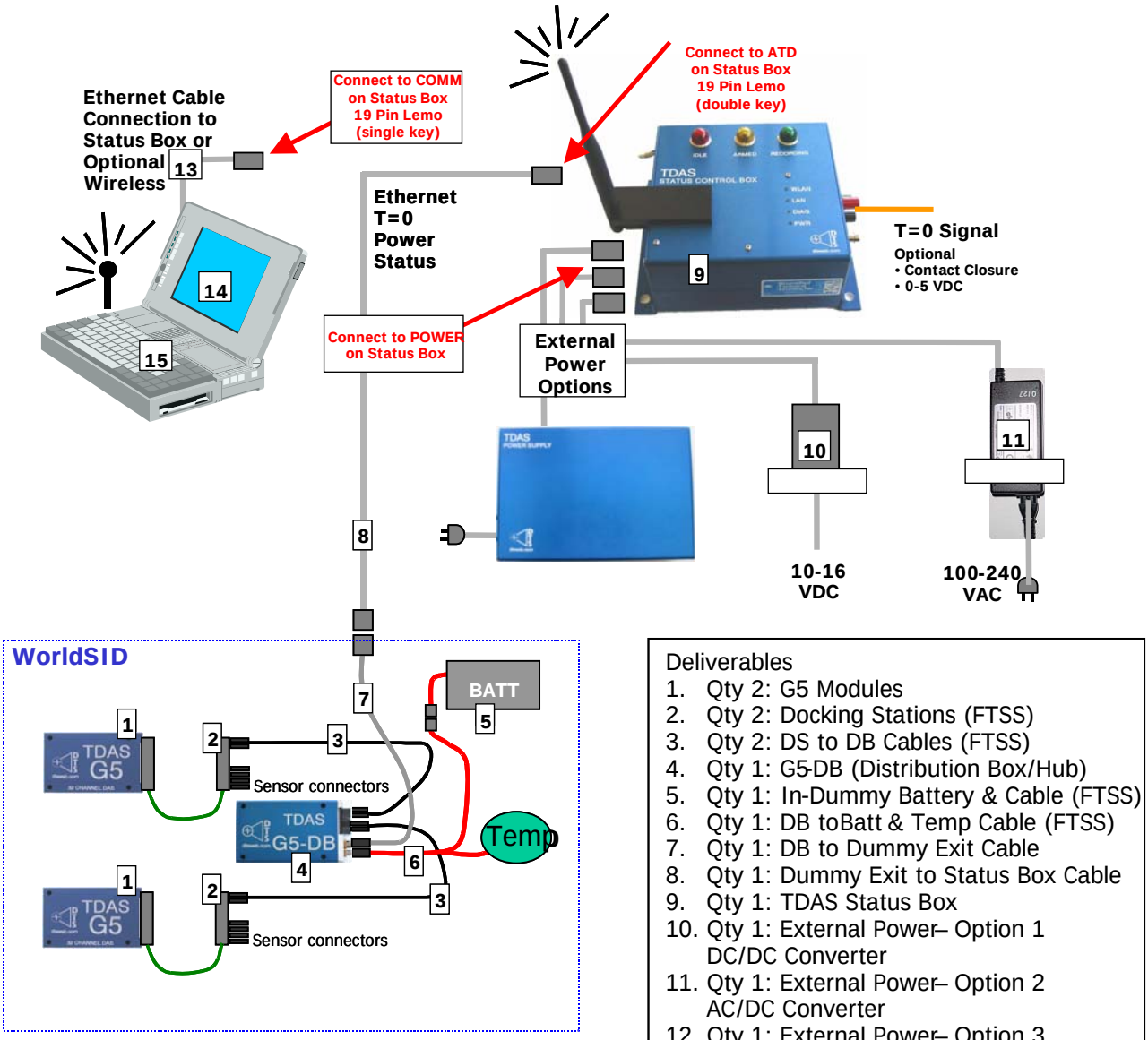
regarding the docking station is found in the manufacturer-supplied G5 module hardware user's manual.

C.5 G5-DB

The G5-DB is used to link up to five G5 Modules together inside the dummy. Note that the in-dummy temperature sensor is also connected to the G5-DB. The G5-DB also manages power input from the in-dummy battery and external power sources. See the G5-DB hardware user's manual for additional information.

C.6 Docking station to G5-DB cable

The G5 docking station to G5-DB cable connects each G5 Module to the G5-DB. Additional information regarding the cable is found in the G5-DB hardware user's manual.



Deliverables

1. Qty 2: G5 Modules
2. Qty 2: Docking Stations (FTSS)
3. Qty 2: DS to DB Cables (FTSS)
4. Qty 1: G5-DB (Distribution Box/Hub)
5. Qty 1: In-Dummy Battery & Cable (FTSS)
6. Qty 1: DB toBatt & Temp Cable (FTSS)
7. Qty 1: DB to Dummy Exit Cable
8. Qty 1: Dummy Exit to Status Box Cable
9. Qty 1: TDAS Status Box
10. Qty 1: External Power– Option 1 DC/DC Converter
11. Qty 1: External Power– Option 2 AC/DC Converter
12. Qty 1: External Power– Option 3 TDAS Power Supply & Cable – NOT Crashworthy
13. Qty 1: TDAS Software
14. Qty 1: Status Box to PC Cable
15. Qty 1: Notebook PC (ordered separately)

Figure C.1 — WorldSID G5 DAS system diagram

C.7 In-dummy battery and cable

The in-dummy battery and integrated cable provide backup power for the G5 system. This optional internal backup battery is provided, however it is only for backup purposes and should not be relied upon for more than brief periods (see manufacturers specification for battery capacities).

C.8 G5-DB to battery and temperature sensor cable

The G5-DB to battery and temperature sensor cable connects these three components.

C.9 G5-DB to dummy exit cable

The G5-DB to dummy exit cable is a separate, replaceable cable used for connecting the G5-DB system to the outside of the dummy. This cable carries external power, Ethernet communications, t = 0 event signal and status signals. See the manufacturer-supplied G5-DB hardware user's manual for additional information.

C.10 Dummy exit to TDAS status box cable

The dummy exit to TDAS status box cable is a separate, replaceable cable used for connecting the WorldSID to the TDAS Status Box. This cable carries external power, Ethernet communications, t = 0 event signal and status signals. See C.5 for additional information.

C.11 TDAS status box

The impact resistant TDAS status box is connected to the WorldSID and displays the status of the system via large red, yellow and green lights. In place of the internal Li-Ion batteries, DTS has provided two options for external power (see C.2.10 and C.2.11 below). The TDAS Status Box is described in a later clause of this annex.

C.12 DC/DC converter

This impact resistant device accepts 10-18 VDC input and provides 13,5 VDC output to the TDAS Status Box. The user must supply a 10-18 VDC source with a minimum of 5A current capability.

C.13 AC/DC converter

This impact resistant device accepts 100-240 VAC input and provides 13,5 VDC output to the TDAS Status Box. The user must supply a 100-240 VAC source.

C.14 TDAS power supply

The TDAS power supply non-impact resistant device accepts 100-240 VAC input and provides 13,5 VDC output to the TDAS Status Box. The user must supply a 100-240 VAC source.

C.15 TDAS software

The provided TDAS software is used for sensor database management, test setup, test execution, data download, post test viewing and data export. See the manufacturer-supplied software user's manual for additional information.

C.16 Status box to PC cable

The status box to PC cable connects a PC to the TDAS Status Box. This cable carries Ethernet communications signals.

C.17 Notebook PC

If an optional notebook PC was acquired with the WorldSID G5 DAS, it may be pre-loaded with TDAS software, sensor database and example test setups. Since WorldSIDs will move from place to place, it is strongly recommended that a PC be dedicated to the dummy. This will make setup at the new operating location much easier.

C.18 Dummy exit to status box cable pinout

Table C.2 and Figure C.2 and Figure C.3 give the cable pinout scheme for the dummy exit to status box cable.

Table C.2 — Dummy exit to status box cable pinout

Lemo Pin Number	20 Feet 9507 – Color Code	Function
1	RED	Main Power, +12 VDC
2	BLACK	Main Power, +12 VDC
8	BROWN	Main GND
4	BLACK	Main GND
5	GREEN	Ethernet +Rx
6	BLACK	Ethernet –Rx
7	ORANGE	Ethernet +Tx
3	BLACK	Ethernet –Tx
9	WHITE	Event +
10	BLACK	Event –
11	BLUE	Arm Status (RS-232 Level, +V=Armed)
12	BLACK	Power ON (short to GND = ON)
13	YELLOW	Status Output (5V = OK)
14	BLACK	Start Record (Vin = Record)

NOTE Belden 9507 cable contains 7 twisted pairs. Each pair contains a black wire and a colored wire. It is very important that the pairs be kept together as shown above.

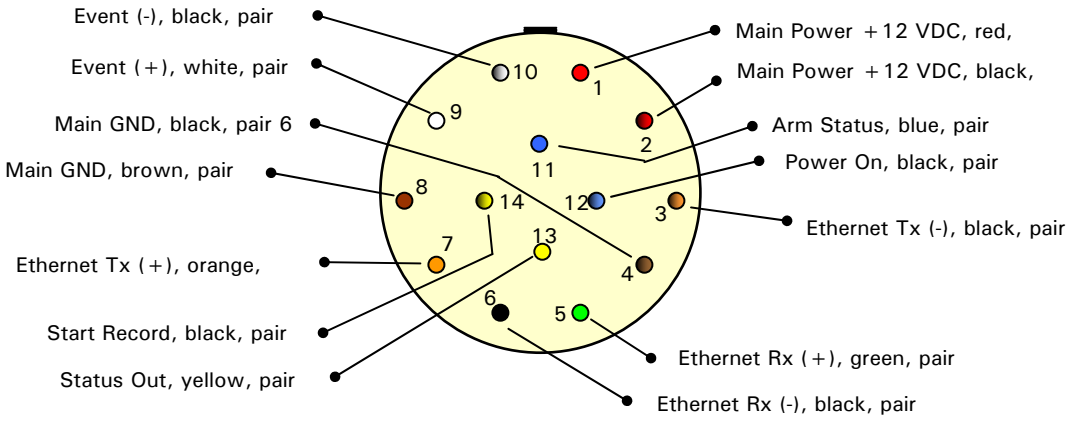


Figure C.2 — Dummy exit to TDAS status box cable 2B 14-pin lemo connector wiring side view sockets

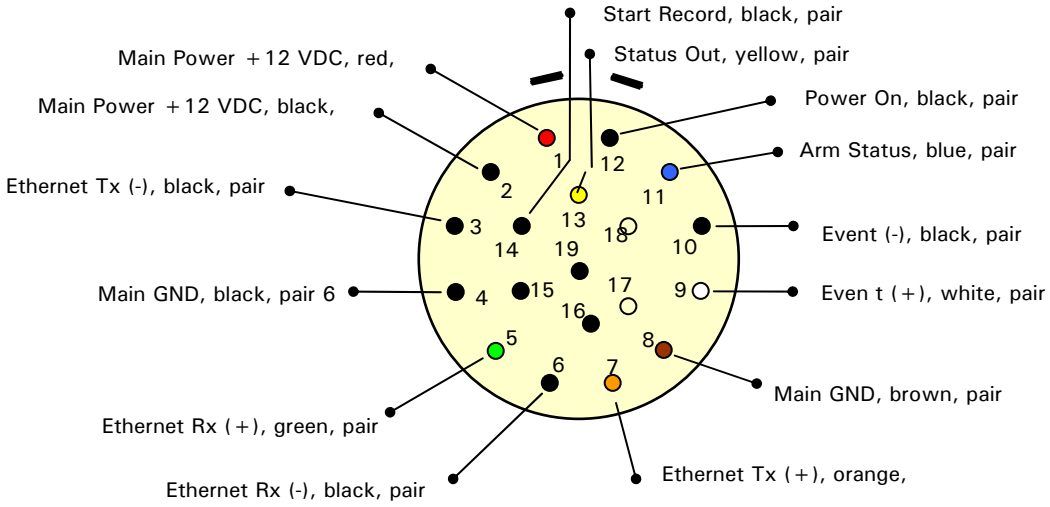


Figure C.3 — Dummy exit to TDAS status box cable 2B 19-pin lemo connector, wiring side view, pins

C.19 Sensor cable length

When the G5 system is used in the WorldSID, sensor cable lengths will be dependent upon the location of the sensor and the location of the G5

used to record the sensor data. Cable lengths for an example G5 and sensor system are shown in Table C.3.

Table C.3 — Example instrumentation cable lengths

Position	No. of channels	Length[a] mm (inches)	DAS[b] location	Qty	Part number
Head accelerometer	3	767 (30,2)	Upper spine	1	W50-71164-767
Head rotation accelerometer	1	750 (29,5)	Upper spine	3	W50-71165-750
Upper neck	6	692 (27,2)	Upper spine	1	W50-71982-692
Lower neck	6	314 (12,4)	Mid spine	1	W50-71981-314
Thorax accelerometer	3	553 (21,8)	Mid spine	1	W50-71164-553
Thorax rotation accelerometer	1	234 (9,2)	Mid spine	1	W50-71165-234
T1 accelerometer	3	416 (16,4)	Mid spine	1	W50-71164-416
T4 accelerometer	3	326 (12,8)	Mid spine	1	W50-71164-326
Rib accelerometers	3	394 (15,5)	Mid spine	6	W50-71164-394
T12 accelerometer	3	347 (13,7)	Mid spine	1	W50-71164-347
Pelvis accelerometer	3	382 (15,0)	Pelvis	1	W50-71164-382
IR-TRACC (shoulder)	1	280 (11,0)	Upper spine	1	W50-74411
IR-TRACC (thorax)	1	280 (11,0)	Mid spine	3	W50-74411
IR-TRACC (abdominal)	1	280 (11,0)	Mid spine	2	W50-74411
Sacro-iliac (R & L)	6	290 (11,4)	Pelvis	2	W50-71983-290
Lumbar[b]	6	475 (18,7)	Mid spine	1	W50-71983-475
Lumbar	6	318 (12,5)	Pelvis	1	W50-71983-318
Pubic	1	246 (9,7)	Pelvis	1	W50-71987-246
Pubic	1	435 (17,1)	Mid spine	1	W50-71987-435
Femoral neck	3	406 (16,0)	Leg	2	W50-71984-406
Femoral neck[b]	3	1080 (42,5)	Pelvis	2	W50-71984-1080
Mid-femur	6	254 (10,0)	Leg	2	W50-71981-254
Knee contact	1	356 (14,0)	Leg	4	W50-71020-356
Knee pot.	1	356 (14,0)	Leg	2	W50-71162
Upper tibia	6	508 (20,0)	Leg	2	W50-71981-508
Lower tibia	6	686 (27,0)	Leg	2	W50-71981-686
Ankle pot.	3	914 (36,0)	Leg	2	W50-71161
Upper arm	6	700 (27,6)	Upper spine	1	W50-71981-700

Position	No. of channels	Length[a] mm (inches)	DAS[b] location	Qty	Part number
Lower arm	6	1100 (43,3)	Upper spine	1	W50-71981-1100
Wrist accelerometer	3	1200 (47,2)	Upper spine	1	W50-71164-1200
Elbow	2	800 (31,5)	Upper spine	1	W50-71992-800
Elbow accelerometer	3	1200 (47,2)	Upper spine	1	W50-71164-1200
Elbow potentiometer	1	950 (37,4)	Upper spine	1	W50-71163
Shoulder	3	355 (14,0)	Upper spine	2	W50-71986-355

a 9,2 m optional cables for off board DAS are also available

b Multiple DAS locations require different cable lengths

Annex D

OPTIONAL DTS G5 DAS LOW POWER MODE: HEAT BUILDUP MITIGATION

D.1 General

To help address temperature concerns inherent when sensors and DAS are installed in-dummy, TDAS CONTROL has a Low Power Mode option for use with iDummy™. Low Power Mode is only available when using Recorder Mode for data collection.

D.2 What is Low Power Mode?

In the standard Recorder Mode, the system starts to collect data when it receives the software ARM signal and it continues to collect data until a hard-wired Start Record input is received. Once received, the system will collect data until the test time expires.

Low Power Recorder Mode is a little different. When the system receives the software ARM signal, it readies for data collection but does not actually start collecting data. Instead, the system goes to sleep—it shuts off excitation to all sensors and waits until it receives a hard-wired or software-driven Start Record signal. When it does, the TDAS G5 DAS wakes up, turns on all excitation circuits—quickly powering up the sensors—and begins to collect data. (The delay between the Start Record request and the start of data collection is 100 milliseconds.) The system acknowledges that it is now collecting data (visible via the status box lights) and will continue to do so until the test time expires. (Currently the user is not able to change the delay time between the Start Record request and the start of data collection.)

D.3 How to Implement Lower Power Mode

D.3.1 Update your tdas.ini file

This can be done by changing the "Default Data Collection Mode" to "Recorder" from within TDAS CONTROL (either "Edit TDAS.INI" or "Setup>>Options" windows)...

...or by editing your tdas.ini file directly and changing the entry below.

```
---- Default Data Collection Mode - (CIRCULAR-BUFFER=0, RECORDER=1, or MULTIPLE-EVENT=2) ----
1
```

D.4 Enable Software Triggering and Low Power Mode

This will enable the hidden Start Record and Trigger buttons. This can be done from within TDAS CONTROL (the "Advanced" window accessible by "Edit TDAS.INI")...

...or by editing your tdas.ini file directly and changing the two entries below.

```
---- Enable Software Trigger/Start Record (0 = No, 1 = Yes)
1
---- Enable low power arm mode for G5 in Recorder mode (0 = No, 1 = Yes)
1
```

After these changes are made, every test performed will be armed using Low Power Mode.

Annex E

SUPPORT EQUIPMENT

E.1 Specialized WorldSID support equipment

Specialized WorldSID support equipment needed for WorldSID assembly, handling, or certification testing consists of the items given in Table E.1.

Table E.1 — Specialized WorldSID support equipment

Reference	Description	Use	Part number
5.1	Head drop tool	Certification	W50-82100
5.2	Head form	Certification	W50-83000
5.1	Head sensor extension cables for head drop test	Certification	Custom[a]
5.2	Head form rotational potentiometers, quantity of three	Certification	F.1A
5.2	Carbon rods for potentiometers	Certification	F.GL
5.2	Circular section neck buffers with different hardness	Certification	W50-20006
5.2	Neck and head form sensor extension cables for neck test	Certification	Custom [a]
5.3	H-Point tool	Test set up	W50-82500
5.3	Teflon® covered dummy certification test bench	Certification	W50-82200
5.3	Small Teflon® sheets for the seat and back	Certification	W50-82244 W50-82245
	Modified spanner wrench, 25 mm to 28 mm dia.	Assembly	W50-51001
	Spanner wrench, 40 mm to 42 mm dia.	Assembly	W50-51002
	Modified hex key wrench	Assembly	W50-51003
	Modified 22 mm open-end wrench	Assembly	W50-51004
	Shortened 6 mm hex key 15 mm long	Assembly	W50-20018
	C-wrench for hip joint	Assembly	W50-42521
	Lifting mechanism	Handling	W50-84100 [a]
a This equipment may need to be customized for each lab.			

E.2 Other support equipment typically available in test laboratories

Other dummy support equipment needed for WorldSID certification and typically available in test laboratories are given in Table E.2.

Table E.2 — Other standard support equipment

Reference	Description	Use
5.1	49 CFR Part 572, Subpart E horizontal head impact surface	Certification
5.1	Quick release mechanism	Certification
5.2	49 CFR Part 572, Subpart E neck pendulum apparatus	Certification
5.2	49 CFR Part 572, Subpart E pendulum decelerating aluminium honeycomb or alternative products which can be shown to lead to the same results	Certification
5.2	Neck bending pendulum accelerometer, Endevco 7231C-750	Certification
5.3	49 CFR Part 572, subpart E Hybrid III 50th percentile adult male dummy pendulum (23,4 kg with 6 in. dia.)	Certification
5.3	49 CFR Part 572, subpart E Hybrid III 50th percentile adult male dummy pendulum accelerometer, Endevco 7231C-750	Certification
E.BF	Neck compression wrench	Assembly

Annex F

DRAWING LIST

This annex lists the WorldSID drawings in Table F.1 and fasteners in Table F.2 for the convenience of users.

Table F.1 — WorldSID drawing list

Drawing number	Description	Electronic file format	
		PDF	STP
W50-00000	WorldSID ATD	X	
W50-10000	Head assembly, tested and certified	X	
W50-10007	Head core	X	
W50-10010	Rotational accelerometer replacement, Endevco 7302BM4	X	
W50-10011	Tilt sensor mass replacement	X	
W50-14014	Head, moulded tested and certified	X	X
W50-20000	Neck assembly	X	
W50-20002	Neck/head/torso interface plate	X	
W50-20006	Neck buffer assembly	X	
W50-20007	Screw, half spherical	X	
W50-20009	Lower neck bracket	X	
W50-20010	Upper neck bracket	X	
W50-20011	Nut, neck bracket	X	
W50-20016	Flexion extension buffer	X	
W50-20018	Shortened 6 mm hex key	X	
W50-21001	Neck assembly tested and certified	X	
W50-22003	Neck, moulded	X	X
W50-24013	Neck shroud assembly	X	
W50-24014	Neck shroud ring	X	X
W50-24015	Neck shroud	X	
W50-30000	Torso-shoulder thorax abdomen, WorldSID	X	
W50-31000	Spine box assembly	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-31010	Upper bracket weldment, spine box, WorldSID	X	
W50-31011	Shoulder mounting plate	X	
W50-31012	Middle plate	X	
W50-31013	Neck bracket mounting plate	X	
W50-31020_1	Side plate, left Worldsid	X	
W50-31020_2	Side plate, left Worldsid	X	
W50-31030_1	Side plate, right Worldsid	X	
W50-31030_2	Side plate, right Worldsid	X	
W50-31041	Spacer, WorldSID	X	
W50-31042	Mounting bracket #1	X	
W50-31043	Mounting bracket #2	X	
W50-31045	Cover plate spine box	X	
W50-31050	Ball joint assembly, IRTRACC	X	
W50-31051	Ball-shaft assembly	X	
W50-31053	Ball-shaft, IRTRACC	X	
W50-31054	Ball socket, IRTRACC	X	
W50-31055	Ball retainer, IRTRACC	X	
W50-31060	IR-TRACC mass replacement	X	
W50-32000	Rib, shoulder	X	
W50-32001	Rib assembly, shoulder	X	
W50-32010	Rib doubler, shoulder	X	
W50-32110	Thorax rib 1, WorldSID	X	
W50-32111	Thorax rib assembly 1 WorldSID	X	
W50-32130	Thorax rib 2 and 3 abdominal ribs WorldSID	X	
W50-32131	Thorax rib assembly, 2 and 3 WorldSID	X	
W50-32150	Thorax rib assembly, inner band, WorldSID	X	
W50-32151	Rib, damping	X	
W50-32152	Thorax rib bent, WorldSID	X	
W50-32155	Abdomen rib assembly, inner band, WorldSID	X	
W50-32156	Rib, damping	X	
W50-32160	Shoulder rib assembly, inner band, WorldSID	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-32161	Rib, damping	X	
W50-32162	Shoulder rib bent, WorldSID	X	
W50-32171	Shoulder rib mounting bracket, struck side, WorldSID	X	
W50-32172	Thorax and abdominal rib accelerometer mounting bracket, WorldSID	X	
W50-32173	Thorax and abdominal rib clamping bracket, WorldSID	X	
W50-32175	Shoulder rib sternum mounting strip, threaded	X	
W50-32176	Thorax and abdominal rib mounting strip, threaded	X	
W50-32177	Shoulder rib sternum mounting strip	X	
W50-32178	Thorax and abdominal rib sternum mounting strip	X	
W50-32179	Screw, rib IRTRACC mount	X	
W50-32180	Clamp, damping	X	
W50-35021	Rib coupler abdominal, WorldSID	X	X
W50-35022	Sternum, thorax rib	X	X
W50-35023-1	Shoulder pad, left, WorldSID	X	X
W50-35023-2	Shoulder pad, right, WorldSID	X	X
W50-35024	Pad, thorax	X	
W50-37011	Battery mounting bracket	X	
W50-37012	Battery structural replacement	X	
W50-37022	Backup plate mounting bracket	X	
W50-37023	Angular accelerometer, tilt sensor mount bracket	X	
W50-37024	T12 accelerometer mount, WorldSID	X	
W50-37029	Bracket, rotational accelerometer mount	X	
W50-38000	Battery assembly	X	
W50-38001	Back plate, battery enclosure	X	
W50-38002	Enclosure cover, battery	X	
W50-38004	Foam pad, 3 mm thick	X	
W50-40000	Pelvis assembly	X	
W50-41018	Lumbar spine rubber	X	X
W50-41019	Bushing lumbar	X	
W50-41020	Bushing, lumbar spine, top	X	
W50-41021	Lumbar lower clamping plate	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-41022	Lumbar upper clamping plate	X	
W50-41026	Lumbar mounting wedge	X	
W50-41030	Weldment lower lumbar mounting bracket	X	
W50-41031	Lower lumbar mounting bracket	X	
W50-41032	Dummy lifting socket	X	
W50-41041	DAS cover	X	
W50-41042	Docking station pelvis	X	
W50-42002	Sacro-illiac load cell backing plate	X	
W50-42005	Hip joint socket	X	
W50-42007	Inner ring hip joint	X	
W50-42008	Hip socket retainer	X	
W50-42010	Pelvis bone, left hand	X	X
W50-42011	Pelvis bone, right hand	X	X
W50-42012	Insert, illiac wing	X	
W50-42016	Sacro-illiac load cell interface left hand	X	
W50-42017	Sacro-illiac load cell interface right hand	X	
W50-42019	Pelvis flesh	X	X
W50-42030	Instrumentation bracket pelvis	X	
W50-42031	Instrumentation cover plate, pelvis	X	
W50-42510	Pubic buffer moulded	X	
W50-42516	End plate medial	X	
W50-42517	End plate lateral	X	
W50-42521	C-wrench for hip joint	X	
W50-51000	Upper leg assembly, right	X	
W50-51001	Modification of small spanner wrench (25mm-28mm)	X	
W50-51002	Unmodified large spanner wrench (40mm-42mm)	X	
W50-51003	Modified 4mm hexagon key wrench	X	
W50-51004	Modified 22mm open end wrench	X	
W50-51017	Trochanter	X	
W50-51022	Trochanter tube assembly, right	X	
W50-51023	Trochanter assembly left	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-51034	Femoral neck assembly	X	
W50-51035	Femoral neck	X	
W50-51038	Femoral ball	X	
W50-51050	Upper leg assembly, left	X	
W50-51052	G5 DAS leg docking station	X	
W50-51053	G5 DAS structural replacement assembly	X	
W50-51058	Upper leg flesh - right - velcro application	X	X
W50-51059	Upper leg flesh - left - velcro application	X	X
W50-51060	Leg structural replacement assembly	X	
W50-51067	Leg extension tube assembly	X	
W50-51068	Leg extension tube	X	
W50-52001 sheet1	Knee assembly right	X	
W50-52001 sheet2	Knee assembly right part list	X	
W50-52002	Knee bone assembly	X	
W50-52004	Knee cover	X	
W50-52005 sheet1	Knee clevis, right	X	
W50-52005 sheet2	Knee clevis, right	X	
W50-52006	Knee clevis stop	X	
W50-52007	Knee pivot shaft	X	
W50-52008	Knee pivot shaft assembly	X	
W50-52009	Knee clevis assembly, right	X	
W50-52010	Knee pad moulded assembly	X	
W50-52011	Side plate	X	
W50-52015	Knee contact load cell structural replacement assembly	X	
W50-52019 sheet1	Knee assembly, left	X	
W50-52019 sheet2	Knee assembly, left parts list	X	
W50-52020	Knee clevis, left	X	
W50-52021	Knee clevis assembly, left	X	
W50-52024	Knee bone	X	
W50-52063	Knee washer	X	
W50-52064	Friction washer assembly	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-52065	Braking washer	X	
W50-52066	Braking washer backing	X	
W50-53001	Lower leg tube	X	
W50-53002	Lower leg flesh	X	X
W50-53007	Zipper assembly	X	
W50-53008	Vinyl strips	X	
W50-54002	Ankle clevis right and left lower limb	X	
W50-54004	Left flexion centre rotational piece	X	
W50-54005	Ankle joint	X	
W50-54006	Base plate	X	
W50-54008	Thrust washer	X	
W50-54009	Z-pivot pin	X	
W50-54010	Z-axis rotational washer	X	
W50-54012	Potentiometer (optional)	X	
W50-54013	Potentiometer structural replacement	X	
W50-54014	Retainer bracket	X	
W50-54015	Ankle joint cover	X	
W50-54016	X-version bushing	X	
W50-54019	Front bearing cover	X	
W50-54020	Rear bearing cover	X	
W50-54021	X-version compression element	X	
W50-54022	Dorsiflexion and plantarflexion hard stop	X	
W50-54023	Z-axis nut	X	
W50-54024	Z-axis anti-rattle washer	X	
W50-54031	Z-axis rotation bearing	X	
W50-54033	Right flexion centre rotational piece	X	
W50-54034	Foot sole locator pins	X	
W50-54035	X-version resistive element	X	
W50-54036	Resistive element	X	
W50-54037	Bumper	X	
W50-54038	Orientation block	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-54041	Z-axis radial limit screw	X	
W50-54042	Front bearing assembly	X	
W50-54043	Rear bearing assembly	X	
W50-54044	X-version assembly	X	
W50-54045	Ankle joint assembly	X	
W50-54046	X-version assembly	X	
W50-54047	Clevis assembly	X	
W50-54048	Left flexion centre assembly	X	
W50-54049	Right flexion centre assembly	X	
W50-54050	Y-version assembly	X	
W50-54051	Z-axis potentiometer assembly (optional)	X	
W50-54052	Y-axis potentiometer assembly (optional)	X	
W50-54053	Lower leg assembly	X	
W50-54054	Ankle assembly	X	
W50-54055	Lower leg assembly, right	X	
W50-54056	Lower leg assembly, left	X	
W50-55003	Sole plate	X	
W50-55004	Left shoe	X	X
W50-55005	Right shoe	X	X
W50-61000	Arm assembly left	X	
W50-61001	Full arm assembly, right	X	
W50-61002	Upper arm, left assembly	X	
W50-61003	Upper arm assembly, right	X	
W50-61004	Upper arm extension tube assembly	X	
W50-61005	Upper arm z-pivot, left	X	
W50-61006	Upper arm z-pivot assembly, left	X	
W50-61007	IGUS bearing (TFI-1214-08)	X	
W50-61008	Z-stop pin	X	
W50-61010	Upper arm z-stop	X	
W50-61011	Arm tube	X	
W50-61012	Upper arm tube assembly	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-61013	Elbow shaft	X	
W50-61014	Clamping washer	X	
W50-61016	Compression washer	X	
W50-61017	Elbow stop	X	
W50-61018	Wrist pivot	X	
W50-61019	Wrist washer	X	
W50-61020	Wrist pivot assembly	X	
W50-61021	Hand bone	X	
W50-61022	Spring washer	X	
W50-61023	Elbow clevis	X	
W50-61024	Elbow clevis assembly	X	
W50-61025	Lower arm tube	X	
W50-61026	Upper arm extension bone	X	
W50-61027	Elbow potentiometer assembly	X	
W50-61028	Elbow shaft assembly	X	
W50-61029	Elbow clevis assembly	X	
W50-61030	Cable guide	X	
W50-61031	Elbow leg load cell structural replacement body	X	
W50-61032	Wrist clevis	X	
W50-61033	Wrist clevis assembly	X	
W50-61034	Lower arm assembly	X	
W50-61035	Wrist assembly	X	
W50-61036	Lower arm tube assembly	X	
W50-61037	Hand, moulded assembly left	X	
W50-61038	Bumper	X	
W50-61039	Accelerometer. mount bracket assembly	X	
W50-61040	Accelerometer. mount bracket	X	
W50-61041	Arm leg load cell structural replacement assembly	X	
W50-61042	Modified button head screw	X	
W50-61044	Bumper	X	
W50-61045	Bumper	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-61046	Bumper, wrist pivot	X	
W50-61047	Modified IGUS bearing	X	
W50-61048	Bumper, hand	X	
W50-61049	Pivot shaft	X	
W50-61050	Pivot washer	X	
W50-61051	Shoulder clevis assembly	X	
W50-61052	Bumper, moulded assembly	X	
W50-61053	Shoulder assembly	X	
W50-61054	Flexion-extension stop assembly	X	
W50-61055	Flexion-extension stop	X	
W50-61056	Stop bumper	X	
W50-61057	Shoulder bumper plate	X	
W50-61058 sheet 1	Clevis	X	
W50-61058 sheet 2	Clevis	X	
W50-61059	Shoulder load cell abduction bumper	X	
W50-61060	Friction pad	X	
W50-61062	Elbow ballast for structural replace	X	
W50-61063	7268-C accelerometer structural replacement	X	
W50-61065	Elbow load cell structural replacement assembly	X	
W50-61067	Moulded hand assembly, right	X	X
W50-61068	Moulded hand assembly, left	X	X
W50-61069	Hand, moulded assembly right	X	
W50-61070-x	IGUS bearing general table	X	
W50-61074	Arm tube assembly	X	
W50-61084	Z-pivot, right	X	
W50-61090	Modified IGUS bearing	X	
W50-61098	Upper arm flesh - right - velcro application	X	X
W50-61099	Upper arm flesh - left - velcro application	X	X
W50-61100	Lower arm flesh velcro application	X	X
W50-61110	Shoulder bumper assembly	X	
W50-61111	Z-pivot assembly, right	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-61113 sheet1	Shoulder clevis for half arm	X	
W50-61113 sheet2	Shoulder clevis for half arm	X	
W50-61117	Shoulder clevis assembly	X	
W50-61123	Structural replacement-elbow potentiometer assembly	X	
W50-62000	Half arm assembly	X	X
W50-62002	Half arm bone	X	
W50-71000	Neck load cell assembly (optional)	X	
W50-71003	Neck load cell structural replacement body	X	
W50-71010	Leg load cell assembly (optional)	X	
W50-71020	Knee contact load cell assembly (optional)	X	
W50-71051	Pubic symphysis load cell	X	
W50-71059	Pubic load cell structural replacement assembly	X	
W50-71060	Elbow load cell assembly (optional)	X	
W50-71070	Arm load cell assembly (optional)	X	
W50-71077	Denton COE tilt sensor adaptor block head	X	
W50-71079	Denton COE tilt sensor adaptor block	X	
W50-71080	Femoral neck load cell assembly (optional)	X	
W50-71090	Shoulder load cell assembly (optional)	X	
W50-71092	Shoulder load cell structural replacement assembly	X	
W50-71094	Denton COE tilt sensor adaptor block head	X	
W50-71097	Bushing	X	
W50-71098	Slug	X	
W50-71120	Lumbar spine load cell assembly (optional)	X	
W50-71122	Lumbar spine load cell structural replacement assembly	X	
W50-71123	Lumbar spine load cell structural replacement body	X	
W50-71130	Sacro-iliac load cell assembly (optional)	X	
W50-71701	Temperature logger mass replacement	X	
W50-71965	Femoral neck load cell structural replacement assembly	X	
W50-71975	Sacro-iliac load cell structural replacement assembly	X	
W50-74307	G5 DAS structural replacement, body	X	
W50-75001	Interposer replacement	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-75002	Connector housing replacement	X	
W50-75102 sheet 1	Linear triax accelerometer cable, head	X	
W50-75102 sheet 2	Linear triax accelerometer cable, head	X	
W50-75108 sheet 1	Rotational accelerometer cable, universal	X	
W50-75108 sheet 2	Rotational accelerometer cable, universal	X	
W50-75201 sheet 1	Linear triax accelerometer cable, universal	X	
W50-75201 sheet 2	Linear triax accelerometer cable, universal	X	
W50-75801	Head to thorax	X	
W50-75802	Torso to sacrum	X	
W50-75803	Sacrum to pubic	X	
W50-75804	Sacrum to upper leg	X	
W50-75805	Upper leg to lower leg	X	
W50-75806	Torso to external ground	X	
W50-80100_1	WorldSID suit	X	
W50-80100_2	WorldSID suit	X	
W50-80100_3	WorldSID suit	X	
W50-80100_4	WorldSID suit	X	
W50-82100	Head drop bracket assembly, WorldSID	X	
W50-82101	Base plate	X	
W50-82102	Joint bracket	X	
W50-82103	Head drop bracket	X	
W50-82104	Joint bracket, top	X	
W50-82105	Plate, magnet	X	
W50-82200	WorldSID bench	X	
W50-82245	Teflon® sheet	X	
W50-82246	Teflon® sheet	X	
W50-82500	H-point tool	X	
W50-82501	H-point tool plate	X	
W50-82502	H-point tool rod	X	
W50-82600	C wrench	X	
W50-82601	C wrench head	X	

Drawing number	Description	Electronic file format	
		PDF	STP
W50-82602	C wrench handle	X	
W50-83000	Headform assembly, WorldSID	X	
W50-83101	Centre plate	X	
W50-83102	Disc A, WorldSID headform	X	
W50-83103	Disc B, WorldSID headform	X	
W50-83104	Upper neck interface plate	X	
W50-83201	Lower neck interface plate	X	
W50-83202	Shaft	X	
W50-83205	Shaft coupling	X	
W50-83206	Mounting base	X	
W50-83207	Potentiometer mounting bracket	X	
W50-84100	Lifting bracket assembly, WorldSID	X	
W50-84104	Handle, threaded hole	X	
W50-84106	Handle, threaded rod	X	
W50-84110	Lifting bracket weldment	X	
W50-84111	Upper rod	X	
W50-84112	Lower rod	X	
W50-84113	Middle bar	X	
W50-84114	Wedge	X	
000-2001	T-insert	X	
734-0800	Temperature logger assembly	X	
E_BF	Neck compression tool	X	
E2-20123	Neck intermediate plate	X	
F_D	Potentiometer assembly	X	
F_DA	Potentiometer housing assembly	X	
F_DB	Potentiometer clamp	X	
F_DE	Bearing	X	
F_DF	Potentiometer housing	X	
f_e	Coupling assembly	X	
f_ea	Coupling	X	
f_eb	Bearing	X	

Drawing number	Description	Electronic file format	
		PDF	STP
F_GA	Arrow shaft-pivot assembly A	X	
F_GB	Arrow shaft-pivot assembly B	X	
F_GC	Arrow shaft assembly	X	
F_GD	Pivot, inside assembly	X	
F_GE	Pin, machined	X	
F_GH	Pivot, outside	X	
F_GJ	Pivot, inside	X	
F_GK	Coupling	X	
F_GL	Arrow shaft	X	
F_HC	Space	X	
F_IA	Rotary potentiometer	X	
IF-363	IR-TRACC specification sheet	X	

Table F.2 — WorldSID fasteners

Description	Fastener number
Ball nose spring plunger MCM# 84895A21	5000257
Ball nose spring plunger MCM# 84895A73	5000256
BHCS M10 X 1.5 X 20mm	5000176
BHCS M2.5 X 10	5000208
BHCS M2.5 X 3	5000248
BHCS M2.5 X 6	5000244
BHCS M3 X 0.5 X 10mm	5000178
BHCS M3 X 0.5 X 6mm	5000171
BHCS M4 X 0.7 X 10mm	5000010
BHCS M4 X 0.7 X 12mm	5000005
BHCS M4 X 0.7 X 6mm	5000179
BHCS M4 X 16	5000153
BHCS M5 X .8 X 25	5000466
BHCS M5 X 0.8 X 10.0	5000003
BHCS M5 X 20	5000210

Description	Fastener number
BHCS M5 X 6	5000214
BHCS M6 X 1 X 18	5000465
BHCS M6 X 1.0 X 16	5000072
BHCS M6 X 22	5000211
BHCS M2.5 X .45 X 5	5000429
BHCS M6 X 1 X 20	5000438
BHCS M8 X 1.25 X 25	5000255
Cable clamp	5000191
Cheese screw M2 X 10	5000220
Cheese screw M2 X 12	5000253
Cheese screw M2 X 16	5000254
Cheese screw M2 X 18	5000221
Cheese screw M3 X 6	5000222
Dowel pin M1.5 X 5mm	5000224
Dowel pin M1.5 X 6mm	5000167
Dowel pin M2 X 5mm	5000225
Dowel pin M3 X 12mm	5000183
Dowel pin M3 X 16mm	5000223
Dowel pin M3 X 6mm	5000385
Dowel pin M3 X 8mm	5000384
Dowel pin M4 X 10	5000414
Dowel pin M4 X 14	5000053
Dowel pin M5 X 16	5000331
Dowel pin M6 X 12mm	5000217
FHCS M2 X 12	5000207
FHCS M2.5 X 12	5000206
FHCS M2.5 X 6	5000202
FHCS M3 X 10	5000203
FHCS M4 X 0.7 X 12mm	5000177
FHCS M5 X .8 X 16	5000467
FHCS M5 X 0.8 X 10	5000084
FHCS M6 X 1.0 X 20.0	5000036
FHCS M6 X 10	5000204

Description	Fastener number
FHCS M6 X 16 stainless steel	5000090
FHCS M6 X 30	5000265
Flat washer M3	5000181
Flat washer M4	5000155
Helicoil M4 X 0.7 X 8mm	5000047
Helicoil M4 X 12mm	5000205
Helicoil M4 X 6mm	5000200
Helicoil M5 X 10mm	5000213
Helicoil M6 X 1 X 6	5000049
Helicoil M6 X 1.0 X 6mm	5000087
Helicoil M6 X 1.0 X 9	5000088
Helicoil M6 X 12mm	5000175
Helicoil M8 X 1.25 X 8	5000348
Hex nut M2	5000216
Hex nut with nylon locking insert M14	5000219
HH BOLT M8 X 1.25 X 10	5000569
Locknut M6 HEX	5000143
Locknut, nylon insert, M12 X 1.75	5000462
LWSHCS M3 X 0.5 X 12mm	5000620
LWSHCS M6 X 1.0 X 12mm	5000194
Retaining ring 12mm Steel	5000249
Retaining ring 16mm Steel	5000250
Retaining ring 18mm Steel	5000251
Roll pin M1.5 X 8mm	5000189
Roll pin M3 X 10mm	5000199
Roll pin M3 X 12mm	5000166
Roll pin M3 X 14mm	5000196
Roll pin M3 X 20mm	5000188
Roll pin M3 X 8mm	5000195
Roll pin M4 X 10mm	5000182
Roll pin M4 X 14mm	5000197
SHCS M1.6 X 0.35 X 5	5000338
SHCS M1.6 X 6 CLASS 12.9 Alloy steel	5000343

Description	Fastener number
SHCS M2 X 0.4 X 18mm	5000164
SHCS M2 X 0.4 X 6mm	5000082
SHCS M2 X 0.4 X 8mm	5000083
SHCS M2 X 10	5000215
SHCS M3 X .5 X 6	5000393
SHCS M3 X 0.5 X 12mm	5000070
SHCS M3 X 10	5000119
SHCS M3 X 14	5000252
SHCS M4 X .7 X 10	5000151
SHCS M4 X 0.7 X 8.0	5000024
SHCS M5 X 0.8 X 12mm	5000002
SHCS M5 X 0.8 X 16mm	5000020
SHCS M5 X 18	5000112
SHCS M6 X 1.0 X 16	5000081
SHCS M6 X 1.0 X 20.0	5000001
SHCS M6 X 12	5000281
SHCS M6 X 50	5000324
SHCS M8 X 18	5000209
SHCS, M3 X 0.5 X 8	5000388
SHCS, M4 X .7 X 14	5000459
SHCS, M4 X .7 X 25	5000461
SHCS, M5 X .8 X 30	5000471
SHCS, M6 X 1 X 10	5000457
SHSS M6 X 25mm	5000163
Spring washer M6	5000134
SSCP M2.5 X 5	5000340
SSCP M3 X 0.5 X 4mm	5000470
SSCP M3 X 16	5000212
SSCP M4 X 0.7 X 6mm	5000076
SSCP M6 X 1.0 X 8mm	5000622
SSCP nylon tip M4 X .7 X 10	5000260
SSFP flat point M4 X 6	5000464
SSFT M6 X 10mm	5000226

Description	Fastener number
SSHDP M6 X 1.0 X 6mm	5000165
SSHDP M6 X 1.0 X 12mm	5000185
SSNT M3 X 0.5 X 3mm	5000190
SSNT M4 X 0.7 X 4mm	5000201
SSNT M6 X 1.0 X 6mm	5000621
Threaded rod M12 X 1.5	5000048
Washer, flat M1.6 X 1.7 X 4 X .25	5000428
Washer, flat M8 (8.9 ID X 18.8 OD X 2.3 THK)	5000123